IAI
Quality and Innovation

GB

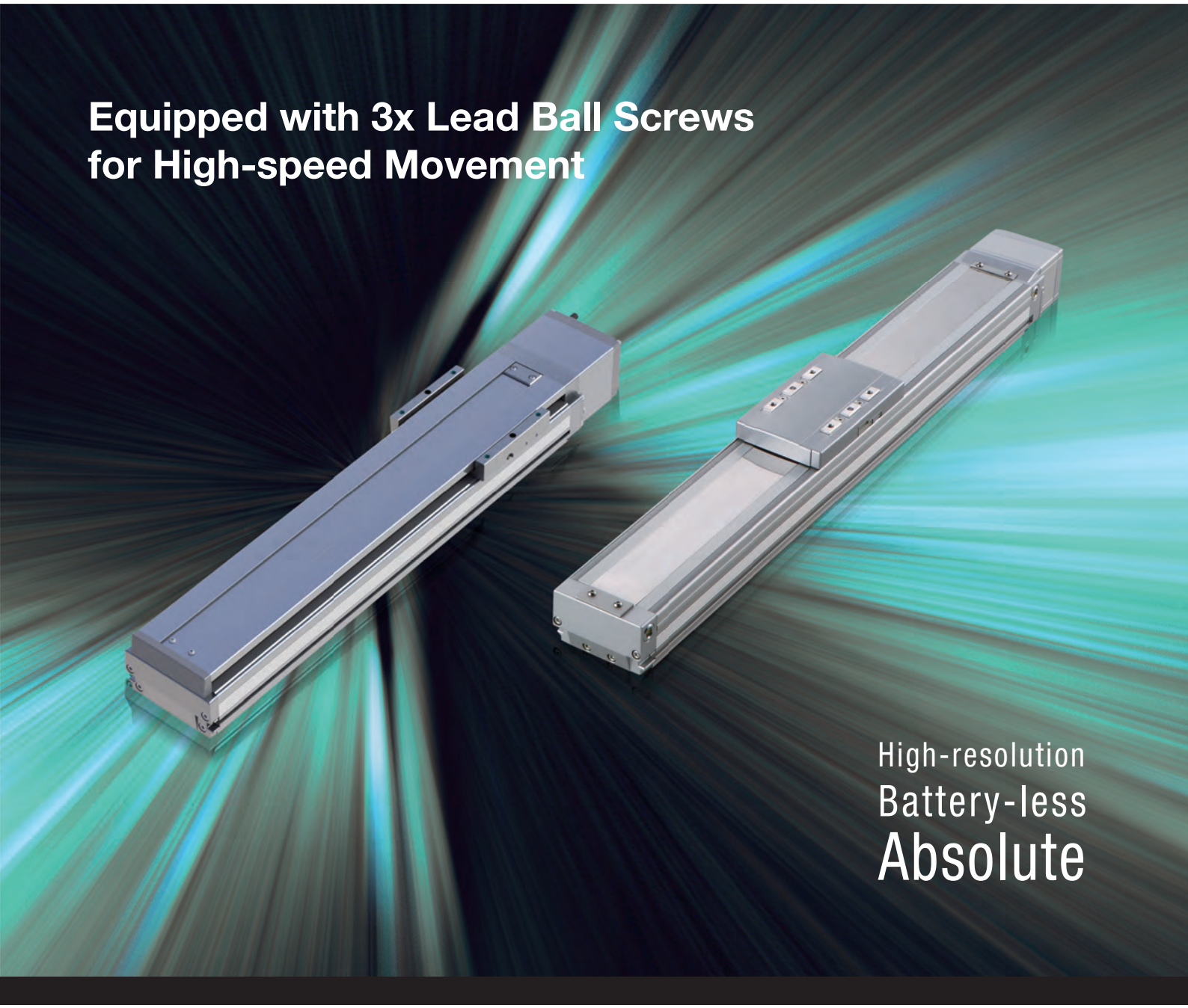
High-speed Single-axis Robot
Small Standard/Simple Dust-proof Type

ISB/ISDB S-100-36

High-speed Single-axis Robot
Medium Standard/Simple Dust-proof Type

ISB/ISDB M-400-48

Equipped with 3x Lead Ball Screws for High-speed Movement



High-resolution
Battery-less
Absolute

www.intelligentactuator.de

Introducing a high-speed actuator that reduces production costs by reducing cycle time.

Features 1 Max. Speed 2500mm/s, Max. Acceleration/Deceleration 3.0G

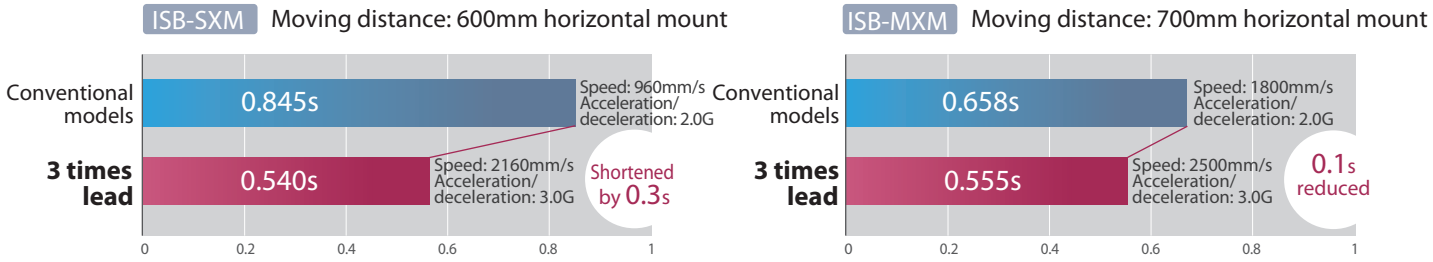
The lineup of ISB/ISDB actuators now have up to 3 times the screw lead which is "the first in the industry" for rolled ball screws. These are low-cost yet high-speed actuators with rolled ball screws that have three times the lead.
The maximum speed is up to 2.3 times higher and acceleration/deceleration up to 1.5 times higher as compared with the conventional product.

	ISB-SXM			ISB-MXM		
	Conventional models		**3x lead ball screws**	Conventional models		**3x lead ball screws**
Ball screw lead (mm)	16		**36**	30		**48**
Max. speed (mm/s)	960	2.3x	**2160**	1,800	1.4x	**2500**
Acceleration/deceleration (G) *	2.0	1.5x	**3.0**	2.0	1.5x	**3.0**
Max. Stroke (mm)	900	+200	**1100**	1,100	+200	**1300**

* Values for off-board tuning.

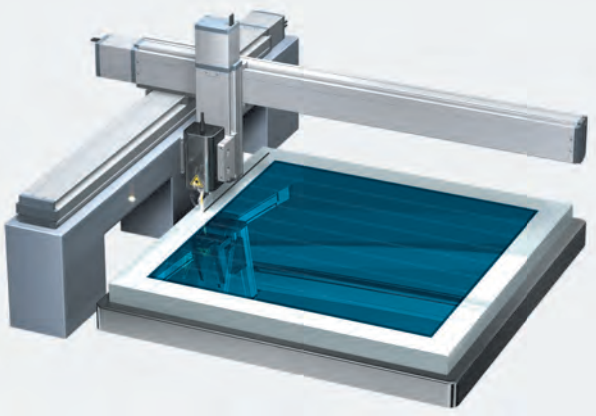
Features 2 Reduced Cycle Time

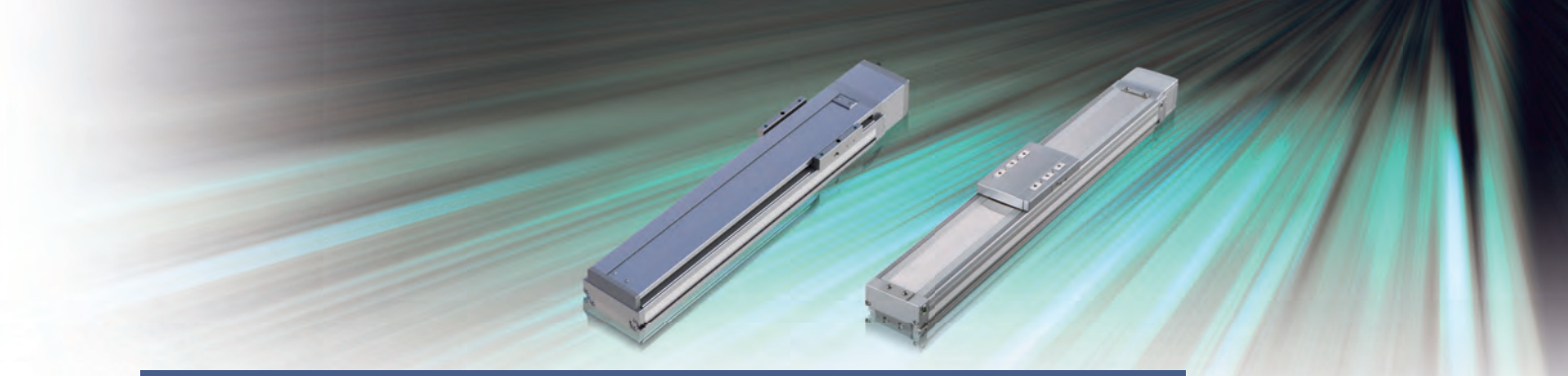
Positioning time can be greatly shortened by increasing acceleration, deceleration and maximum velocity.



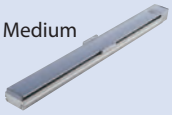
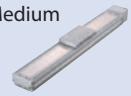
Application Examples

A laser trimming apparatus with thin-film solar cells that combines a high-speed actuator (with 3x lead ball screws).
It shortens the cycle time and improves productivity by speeding up trimming.





Product Lineup

Series	External View	Body width (mm)	Type		Motor wattage (W)	Ball screw lead (mm)	Stroke (mm)	Max. Speed (mm/s)	Max. Payload (kg)		Ref. page
									Horizontal	Vertical	
ISB	Small 	 90	Standard Slider	SXM	100	36	100~1100 (Every 50mm)	2160	10	2	P.3
			Long Slider	SXL			130~1080 (Every 50mm)				P.5
	Medium 	 120	Standard Slider	MXM	400	48	100~1300 (Every 50mm)	2500	20	6	P.7
			Long Slider	MXL			120~1270 (Every 50mm)				P.9
			Intermediate Support	MXMX			800~2000 (Every 50mm)	2200	20	—	P.11
ISDB Simple dust-proof type	Small 	 90	Standard Slider	S	100	36	100~800 (Every 50mm)	2000	10	2	P.13
	Medium 	 120	Standard Slider	M	400	48	100~1100 (Every 50mm)	2200	20	6	P.15
			Intermediate Support	MX			800~1600 (Every 50mm)		20	—	P.17

* The maximum speed may not be reached if the stroke is short. Longer strokes may cause the maximum speed to decrease due to resonance.
Please refer to the reference page of each model for details.

3x lead ball screw model part number breakdown

Series	Type	Encoder Type	Motor Type	Ball Screw Lead	Stroke	Applicable Controller	Cable Length	Options
		WA				T2		

Series

ISB	Standard type
ISDB	Simple dust-proof type

Type

ISB	SXM	Small / Standard slider type
	SXL	Small / Long slider type
	MXM	Medium / Standard slider type
	MXL	Medium / Long slider type
	MXMX	Medium / Standard slider and intermediate support type
ISDB	S	Small type
	M	Medium type
	MX	Medium / Intermediate support type

Encoder Type

WA	Battery-less abs.

Motor Type

100	100W
400	400W

Ball Screw Lead

36	36mm
48	48mm

Stroke

100	100mm
≀	≀
2000	2,000mm

(Can be set in 50mm increments)

Applicable Controller

N	None
S	3m
M	5m
X□□	Specified length

Options

A1S	Cable exits from the left side
A1E	Cable exits from the back left side
A3S	Cable exits from the right side
A3E	Cable exits from the back right side
AQ	AQ seal (standard feature)
B	Brake
C	Creep sensor
CL	Creep sensor symmetrically opposite
L	Home limit switch
LL	Home limit switch symmetrically opposite
LM	Master axis setting
LLM	Master axis setting (sensor symmetrically opposite)
NM	Non-motor end specification
RT	Guide with ball retention mechanism
S	Slave axis specified
SR	Slider section roller specification
ST	Straightness high-precision specification
W	Double slider specification
EU	Round cable joint connector with screw locking

*The type of motor, ball screw lead, stroke, and options vary depending on the actuator type.
Please refer to the reference page of each type for details.

ISB-SXM-100

±10μm Standard | Battery-less Absolute | Small X-axis Type | Standard Slider | Body Width 90 mm | 100 W

■ Model Specification Items

ISB — SXM — WA — 100 — 36 — □ — T2 — □ — □

Series	Type	Encoder Type	Motor Type	Lead	Stroke	Applicable Controllers	Cable Length	Options
ISB	SXM	WA: Battery-less absolute	100 : 100W	36 : 36mm	100 : 100mm ~ 1100 : 1100mm (50mm increments)	T2 : SCON, MSCON, SSEL, XSEL-P/Q	N : None, S : 3m, M : 5m, X□□ : Specified Length	Please refer to the option table below

* Does not include a controller.
* Please contact IAI for more information about the model specification items.

* Be sure to specify the AQ seal (AQ) option. Be sure to select a symbol for the cable outlet direction.

CE RoHS

Horizontal | Vertical | Side | Ceiling

* Depending on the model, there may be some limitations to using the vertical, side, and ceiling mount positions. Please contact IAI for more information regarding mounting positions. Please contact IAI for more details.

POINT Selection Notes

(Note 1) The value of payload is when operating at an acceleration of 0.4G. When the acceleration is increased, the payload will be reduced. Please refer to P.21 for more information.

(Note 2) The straightness of straight line motion is the value when the straightness high precision specifications (optional) are specified.

Model/Specifications

■ Lead and Payload

Model	Motor wattage (W)	Lead (mm)	Max. payload (*1) Horizontal (kg)	Max. payload (*1) Vertical (kg) (*2)	Rated thrust (N)	Stroke (mm)
ISB-SXM-WA-100-36-①-T2-②-③	100	36	10	2	47.2	100~1100 (Every 50mm)

Legend: ① Stroke ② Cable length ③ Option

(*1) Refer to P. 21 for the relationship of acceleration and payload.
(*2) If the guide with ball retention mechanism (RT) is used, the vertical payload decreases by 0.5kg.

■ Stroke and Max. Speed

Stroke	100	150	200	250	300	350	400
Max. Speed	1100	1425	1700	1925	2075	2125	2160

Stroke	450	500	550	600	650	700	750
Max. Speed	2160			2000	1740	1520	1340

Stroke	800	850	900	950	1000	1050	1100
Max. Speed	1190	1065	960	865	790	721	660

(Unit: mm/s)

Cable Length

Type	Cable code	Standard	With LS
Standard type	**S** (3m)	○	
	M (5m)	○	
Specified length	**X06** (6m) ~**X10** (10m)	○	○
	X11 (11m) ~**X20** (20m)	○	○

* Only the robot cable is available for this model.
* Please contact IAI for more information regarding the maintenance cables.
* When using a cable of 21 to 30m, specify "N" for the cable length of the actuator model, and separately purchase the motor cable [CB-X(EU)-MA□□□], encoder cable [CB-X(EU)1-PA□□□-AWG24] or encoder cable with LS [CB-X(EU)1-PLA□□□-AWG24]. (Please contact IAI for more details on the cable.)

Options

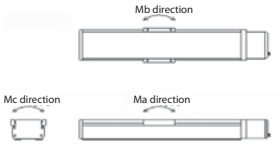
Type	Model	Ref. Page	Type	Model	Ref. Page
Cable exits from the left side	**A1S**	See P.19	Home limit switch symmetrically opposite	**LL**	See P.19
Cable exits from the back left side	**A1E**	See P.19	Master axis specified	**LM**	See P.19
Cable exits from the right side	**A3S**	See P.19	Master axis spec. (sensor symmetrically opposite)	**LLM**	See P.19
Cable exits from the back right side	**A3E**	See P.19	Non-motor end spec.	**NM**	See P.19
AQ seal (standard feature)	**AQ**	See P.19	Guide with ball retention mechanism	**RT**	See P.20
Brake	**B**	See P.19	Slave axis specified	**S**	See P.19
Creep sensor	**C**	See P.19	Straightness high precision specification	**ST**	See P.20
Creep sensor symmetrically opposite	**CL**	See P.19	Double slider specification	**W**	See P.20
Home limit switch	**L**	See P.19	Round cable joint connector with screw locking	**EU**	See P.19

Actuator Specifications

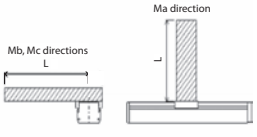
Item	Description
Positioning repeatability	±0.01mm
Drive system	Ball screw ϕ12mm, rolled C10
Lost motion	0.05mm or less
Static allowable moment	Ma: 143.8N·m Mb: 205.4N·m Mc: 336.0N·m
Dynamic allowable moment (*1) (*2)	Ma: 32.9N·m Mb: 47.0N·m Mc: 76.8N·m
Dyn. straightness of straight line motion (*3)	0.02mm/m or less
Base	Material: Aluminum with white alumite treatment
Ambient operating temp. & humidity	0~40°C, 85% RH or less (Non-condensing)

(*1) Assumes a standard rated life of 10000km. The service life will vary depending on operation and installation conditions. Please contact IAI for the running life.
(*2) Please refer to P.22 for more information regarding the directions of the allowable moment and overhang load length when using the double slider (option).
(*3) The value is when the straightness high precision specification (option) is specified.

· Reference for overhang load length: Ma: 450mm or less, Mb, Mc: 450mm or less



Direction of the dynamic allowable moment



Direction of the allowable overhang load length

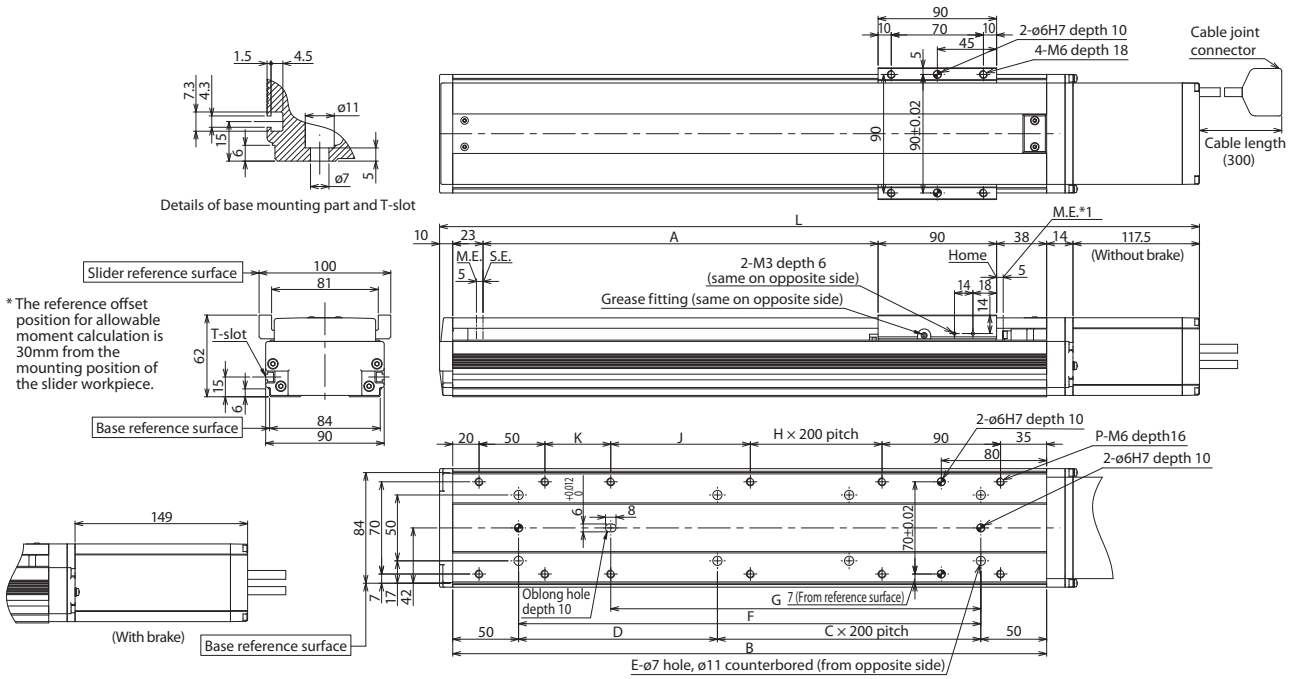
Please refer to the ISB/ISDB basic catalogue for more information regarding the directions of the allowable moment and overhang load length.

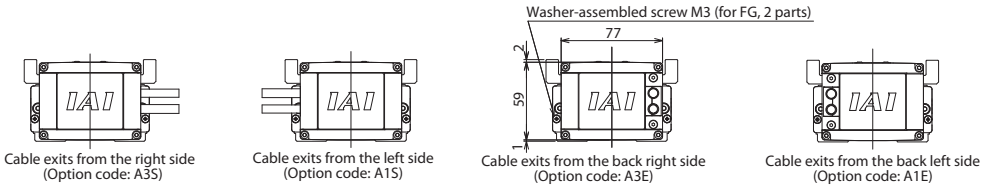
Dimensions

CAD drawings can be downloaded from our website.
www.intelligentactuator.de

*1 When the slider is returning to its home position, please be careful of interference from surrounding objects, as it will travel until it reaches the M.E.
M.E: Mechanical end
S.E: Stroke end

*2 If the home direction needs to be changed after purchase, the actuator must be returned to IAI for adjustment.





■ Dimensions and Mass by Stroke

Stroke		100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100
L	w/o brake	392.5	442.5	492.5	542.5	592.5	642.5	692.5	742.5	792.5	842.5	892.5	942.5	992.5	1042.5	1092.5	1142.5	1192.5	1242.5	1292.5	1342.5	1392.5
	w/brake	424	474	524	574	624	674	724	774	824	874	924	974	1024	1074	1124	1174	1224	1274	1324	1374	1424
A		100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100
B		251	301	351	401	451	501	551	601	651	701	751	801	851	901	951	1001	1051	1101	1151	1201	1251
C		0	0	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5
D		151	201	251	101	151	201	251	101	151	201	251	101	151	201	251	101	151	201	251	101	151
E		4	4	4	6	6	6	6	8	8	8	8	10	10	10	10	12	12	12	12	14	14
F		151	201	251	301	351	401	451	501	551	601	651	701	751	801	851	901	951	1001	1051	1101	1151
G		131	131	181	231	281	331	381	431	481	531	581	631	681	731	781	831	881	931	981	1031	1081
H		0	0	0	0	0	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4
J		56	56	106	156	206	256	106	156	206	256	106	156	206	256	106	156	206	256	106	156	206
K		0	50	50	50	50	50	50	50	50	50	50	50	50	50	50	50	50	50	50	50	50
P		8	10	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16	16	18	18	18
Mass (kg)	w/o brake	3.2	3.6	4.0	4.3	4.7	5.0	5.4	5.7	6.1	6.5	6.8	7.2	7.5	7.9	8.2	8.6	8.9	9.3	9.7	10.0	10.4
	w/brake	3.5	3.9	4.3	4.6	5.0	5.3	5.7	6.0	6.4	6.8	7.1	7.5	7.8	8.2	8.5	8.9	9.2	9.6	10.0	10.3	10.7

Applicable Controllers

The ISB series actuators can be operated by the controllers indicated below. Please select the type depending on your intended use.

Type	External view	Max. number of controlled axes	Power supply voltage	Control method				Maximum number of positioning points	Ref. page
				Positioner	Pulse-train	Program	Network *Option		
SCON-CB/CGB		1	Single-phase 115/230VAC	●	●	–	DeviceNet, CC-Link, PROFIBUS, CompoNet, EtherCAT, EtherNet/IP, PROFINET	512 points (768 for network spec.)	Please contact IAI for more details
SCON-LC/LCG		1		–	–	●		512 points (768 for network spec.)	
SCON-CAL/CGAL		1		●	–	–		512 points (768 for network spec.)	
MSCON-C		6		This model is network-compatible only.				256	
SSEL-CS		2		●	–	●	Note: The type of compatible networks will vary depending on the controller. Please contact IAI for more details.	20000	
XSEL-P/Q		6	Single-phase 230VAC Three-phase 230VAC	–	–	●		20000	

ISB-SXL-100

±10μm Standard | Battery-less Absolute | Small X-axis Type | Long slider | Body Width 90 mm | 100 W

■ Model Specification Items

ISB — SXL — WA — 100 — 36 — □ — T2 — □ — □

Series	Type	Encoder Type	Motor Type	Lead	Stroke	Applicable Controllers	Cable Length	Options
ISB	SXL	WA: Battery-less absolute	100 : 100W	36 : 36mm	130 : 130mm ~ 1080 : 1080mm (50mm increments)	T2 : SCON, MSCON, SSEL, XSEL-P/Q	N : None, S : 3m, M : 5m, X□□ : Specified Length	Please refer to the option table below

* Does not include a controller.
* Please contact IAI for more information about the model specification items.

* Be sure to specify the AQ seal (AQ) option. Be sure to select a symbol for the cable outlet direction.

CE RoHS

Horizontal | Vertical | Side | Ceiling

* Depending on the model, there may be some limitations to using the vertical, side, and ceiling mount positions. Please contact IAI for more information regarding mounting positions. Please contact IAI for more details.

POINT Selection Notes

(Note 1) The value of payload is when operating at an acceleration of 0.4G. When the acceleration is increased, the payload will be reduced. Please refer to P.21 for more information.

(Note 2) The straightness of straight line motion is the value when the straightness high precision specifications (optional) are specified.

Model/Specifications

■ Lead and Payload

Model	Motor wattage (W)	Lead (mm)	Max. payload (*1) Horizontal (kg)	Max. payload (*1) Vertical (kg)	Rated thrust (N)	Stroke (mm)
ISB-SXL-WA-100-36-①-T2-②-③	100	36	10	2	47.2	130~1080 (Every 50mm)

Legend: ① Stroke ② Cable length ③ Option

(*1) Refer to P. 21 for the relationship of acceleration and payload.

■ Stroke and Max. Speed

Stroke	130	180	230	280	330	380	430
Max. Speed	1425	1700	1925	2075	2125	2160	

Stroke	480	530	580	630	680	730	780
Max. Speed	2160		2000	1740	1520	1340	1190

Stroke	830	880	930	980	1030	1080
Max. Speed	1065	960	865	790	721	660

(Unit: mm/s)

Cable Length

Type	Cable code	Standard	With LS
Standard type	**S** (3m)	○	
	M (5m)	○	
Specified length	**X06** (6m) ~**X10** (10m)	○	○
	X11 (11m) ~**X20** (20m)	○	○

* Only the robot cable is available for this model.
* Please contact IAI for more information regarding the maintenance cables.
* When using a cable of 21 to 30m, specify "N" for the cable length of the actuator model, and separately purchase the motor cable [CB-X(EU)-MA□□□], encoder cable [CB-X(EU)1-PA□□□-AWG24] or encoder cable with LS [CB-X(EU)1-PLA□□□-AWG24]. (Please contact IAI for more details on the cable.)

Options

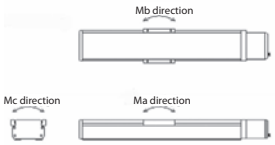
Type	Model	Ref. Page	Type	Model	Ref. Page
Cable exits from the left side	**A1S**	See P.19	Home limit switch symmetrically opposite	**LL**	See P.19
Cable exits from the back left side	**A1E**	See P.19	Master axis specified	**LM**	See P.19
Cable exits from the right side	**A3S**	See P.19	Master axis spec. (sensor symmetrically opposite)	**LLM**	See P.19
Cable exits from the back right side	**A3E**	See P.19	Non-motor end spec.	**NM**	See P.19
AQ seal (standard feature)	**AQ**	See P.19	-	-	-
Brake	**B**	See P.19	Slave axis specified	**S**	See P.19
Creep sensor	**C**	See P.19	Straightness high precision specification	**ST**	See P.20
Creep sensor symmetrically opposite	**CL**	See P.19	Double slider specification	**W**	See P.20
Home limit switch	**L**	See P.19	Round cable joint connector with screw locking	**EU**	See P.19

Actuator Specifications

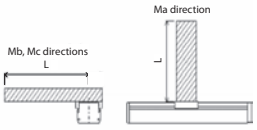
Item	Description
Positioning repeatability	±0.01mm
Drive system	Ball screw ϕ12mm, rolled C10
Lost motion	0.05mm or less
Static allowable moment	Ma: 216.0N·m Mb: 308.5N·m Mc: 415.1N·m
Dynamic allowable moment (*1) (*2)	Ma: 46.3N·m Mb: 66.2N·m Mc: 89.0N·m
Dyn. straightness of straight line motion (*3)	0.02mm/m or less
Base	Material: Aluminum with white alumite treatment
Ambient operating temp. & humidity	0~40°C, 85% RH or less (Non-condensing)

(*1) Assumes a standard rated life of 10000km. The service life will vary depending on operation and installation conditions. Please contact IAI for the running life.
(*2) Please refer to P.22 for more information regarding the directions of the allowable moment and overhang load length when using the double slider (option).
(*3) The value is when the straightness high precision specification (option) is specified.

· Reference for overhang load length: Ma: 550mm or less, Mb, Mc: 550mm or less



Direction of the dynamic allowable moment



Direction of the allowable overhang load length

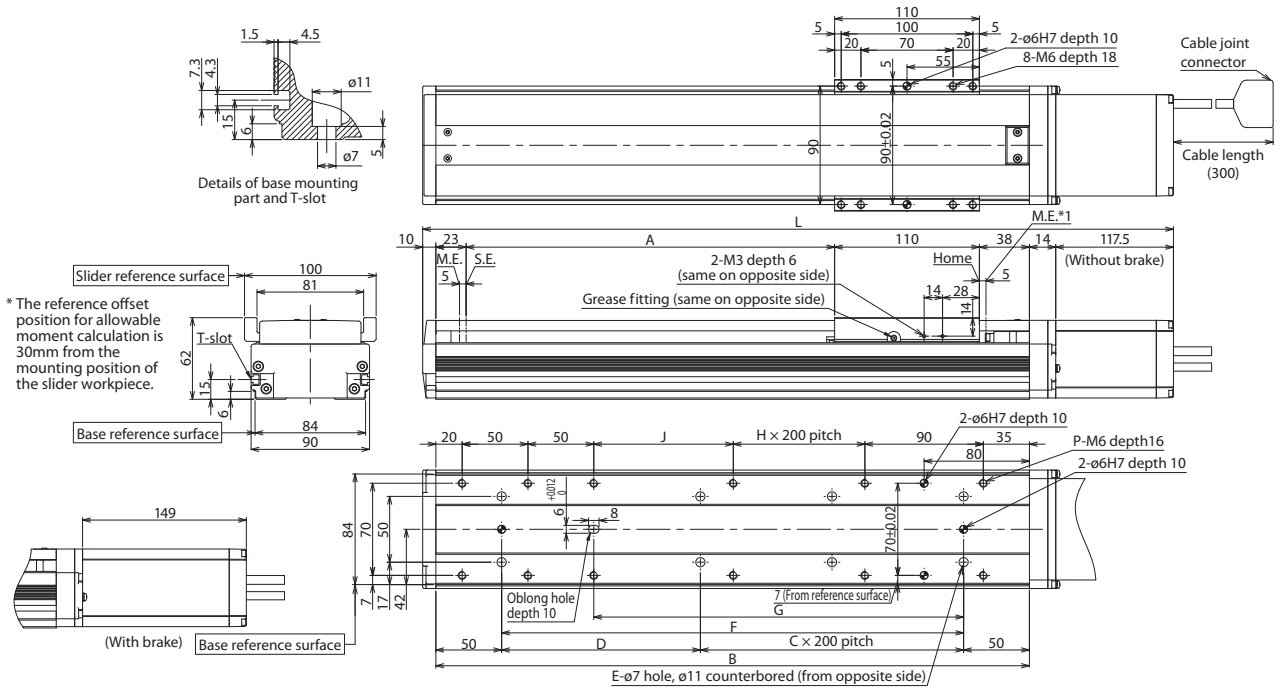
Please refer to the ISB/ISDB basic catalogue for more information regarding the directions of the allowable moment and overhang load length.

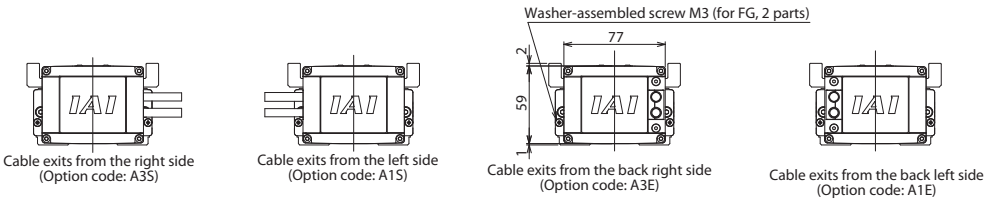
Dimensions

CAD drawings can be downloaded from our website.
www.intelligentactuator.de

*1 When the slider is returning to its home position, please be careful of interference from surrounding objects, as it will travel until it reaches the M.E.
M.E: Mechanical end
S.E: Stroke end

*2 If the home direction needs to be changed after purchase, the actuator must be returned to IAI for adjustment.





■ Dimensions and Mass by Stroke

Stroke		130	180	230	280	330	380	430	480	530	580	630	680	730	780	830	880	930	980	1030	1080
L	w/o brake	442.5	492.5	542.5	592.5	642.5	692.5	742.5	792.5	842.5	892.5	942.5	992.5	1042.5	1092.5	1142.5	1192.5	1242.5	1292.5	1342.5	1392.5
	w/brake	474	524	574	624	674	724	774	824	874	924	974	1024	1074	1124	1174	1224	1274	1324	1374	1424
A		130	180	230	280	330	380	430	480	530	580	630	680	730	780	830	880	930	980	1,030	1,080
B		301	351	401	451	501	551	601	651	701	751	801	851	901	951	1001	1051	1101	1151	1201	1251
C		0	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5
D		201	251	101	151	201	251	101	151	201	251	101	151	201	251	101	151	201	251	101	151
E		4	4	6	6	6	6	8	8	8	8	10	10	10	10	12	12	12	12	14	14
F		201	251	301	351	401	451	501	551	601	651	701	751	801	851	901	951	1001	1051	1101	1151
G		131	181	231	281	331	381	431	481	531	581	631	681	731	781	831	881	931	981	1031	1081
H		0	0	0	0	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4
J		56	106	156	206	256	106	156	206	256	106	156	206	256	106	156	206	256	106	156	206
P		10	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16	16	18	18	18
Mass (kg)	w/o brake	3.7	4.1	4.4	4.8	5.1	5.5	5.8	6.2	6.6	6.9	7.3	7.6	8.0	8.3	8.7	9.0	9.4	9.8	10.1	10.5
	w/brake	4.0	4.4	4.7	5.1	5.4	5.8	6.1	6.5	6.9	7.2	7.6	7.9	8.3	8.6	9.0	9.3	9.7	10.1	10.4	10.8

Applicable Controllers

The ISB series actuators can be operated by the controllers indicated below. Please select the type depending on your intended use.

Type	External view	Max. number of controlled axes	Power supply voltage	Control method				Maximum number of positioning points	Ref. page
				Positioner	Pulse-train	Program	Network *Option		
SCON-CB/CGB		1	Single-phase 115/230VAC	●	●	–	DeviceNet, CC-Link, PROFIBUS, CompoNet, EtherCAT, EtherNet/IP, PROFINET	512 points (768 for network spec.)	Please contact IAI for more details
SCON-LC/LCG		1		–	–	●		512 points (768 for network spec.)	
SCON-CAL/CGAL		1		●	–	–		512 points (768 for network spec.)	
MSCON-C		6		This model is network-compatible only.				256	
SSEL-CS		2		●	–	●	Note: The type of compatible networks will vary depending on the controller. Please contact IAI for more details.	20000	
XSEL-P/Q		6	Single-phase 230VAC Three-phase 230VAC	–	–	●		20000	

ISB-MXM-400

±10μm Standard | Battery-less Absolute | Medium X-axis Type | Standard Slider | Body Width 120 mm | 400 W

■ Model Specification Items

ISB — MXM — WA — 400 — 48 — □ — T2 — □ — □

Series	Type	Encoder Type	Motor Type	Lead	Stroke	Applicable Controllers	Cable Length	Options
ISB	MXM	WA: Battery-less absolute	400 : 400W	48 : 48mm	100 : 100mm ~ 1300 : 1300mm (50mm increments)	T2 : SCON SSEL XSEL-P/Q	N : None S : 3m M : 5m X□□ : Specified Length	Please refer to the option table below

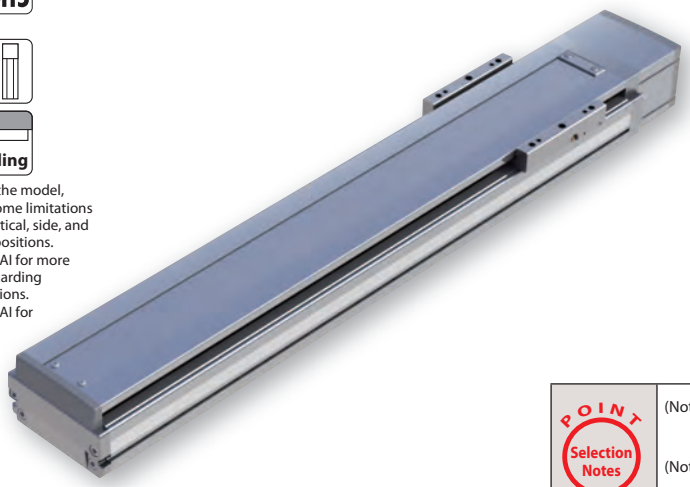
* Does not include a controller.
* Please contact IAI for more information about the model specification items.

* Be sure to specify the AQ seal (AQ) option. Be sure to select a symbol for the cable outlet direction.

CE RoHS

Horizontal | Vertical | Side | Ceiling

* Depending on the model, there may be some limitations to using the vertical, side, and ceiling mount positions. Please contact IAI for more information regarding mounting positions. Please contact IAI for more details.



POINT Selection Notes

(Note 1) The value of payload is when operating at an acceleration of 0.4G. When the acceleration is increased, the payload will be reduced. Please refer to P.21 for more information.

(Note 2) The straightness of straight line motion is the value when the straightness high precision specifications (optional) are specified.

Model/Specifications

■ Lead and Payload

Model	Motor wattage (W)	Lead (mm)	Max. payload (*1) Horizontal (kg)	Max. payload (*1) Vertical (kg)	Rated thrust (N)	Stroke (mm)
ISB-MXM-WA-400-48-①-T2-②-③	400	48	20	6	141.3	100~1300 (Every 50mm)

Legend: ① Stroke ② Cable length ③ Option

(*1) Refer to P. 21 for the relationship of acceleration and payload.

■ Stroke and Max. Speed

Stroke	100	150	200	250	300	350	400
Max. Speed	1025	1325	1575	1825	2025	2200	2350

Stroke	450	500	550	600	650	700	750
Max. Speed	2400	2500					2270

Stroke	800	850	900	950	1000	1050	1100
Max. Speed	2030	1825	1645	1495	1365	1250	1150

Stroke	1150	1200	1250	1300
Max. Speed	1060	980	910	845

(Unit: mm/s)

Cable Length

Type	Cable code	Standard	With LS
Standard type	**S** (3m)	○	
	M (5m)	○	
Specified length	**X06** (6m) ~**X10** (10m)	○	○
	X11 (11m) ~**X20** (20m)	○	○

* Only the robot cable is available for this model.
* Please contact IAI for more information regarding the maintenance cables.
* When using a cable of 21 to 30m, specify "N" for the cable length of the actuator model, and separately purchase the motor cable [CB-X(EU)-MA□□□], encoder cable [CB-X(EU)1-PA□□□-AWG24] or encoder cable with LS [CB-X(EU)1-PLA□□□-AWG24]. (Please contact IAI for more details on the cable.)

Options

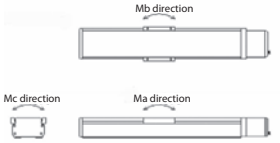
Type	Model	Ref. Page	Type	Model	Ref. Page
Cable exits from the left side	**A1S**	See P.19	Home limit switch symmetrically opposite	**LL**	See P.19
Cable exits from the back left side	**A1E**	See P.19	Master axis specified	**LM**	See P.19
Cable exits from the right side	**A3S**	See P.19	Master axis spec. (sensor symmetrically opposite)	**LLM**	See P.19
Cable exits from the back right side	**A3E**	See P.19	Non-motor end spec.	**NM**	See P.19
AQ seal (standard feature)	**AQ**	See P.19	Guide with ball retention mechanism	**RT**	See P.20
Brake	**B**	See P.19	Slave axis specified	**S**	See P.19
Creep sensor	**C**	See P.19	Straightness high precision specification	**ST**	See P.20
Creep sensor symmetrically opposite	**CL**	See P.19	Double slider specification	**W**	See P.20
Home limit switch	**L**	See P.19	Round cable joint connector with screw locking	**EU**	See P.19

Actuator Specifications

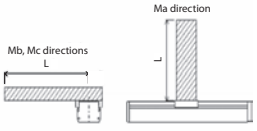
Item	Description
Positioning repeatability	±0.01mm
Drive system	Ball screw ϕ16mm, rolled C10
Lost motion	0.05mm or less
Static allowable moment	Ma: 341.5N·m Mb: 487.0N·m Mc: 796.5N·m
Dynamic allowable moment (*1) (*2)	Ma: 81.0N·m Mb: 116.0N·m Mc: 189.0N·m
Dyn. straightness of straight line motion (*3)	0.02mm/m or less
Base	Material: Aluminum with white alumite treatment
Ambient operating temp. & humidity	0~40°C, 85% RH or less (Non-condensing)

(*1) Assumes a standard rated life of 10000km. The service life will vary depending on operation and installation conditions. Please contact IAI for the running life.
(*2) Please refer to P.22 for more information regarding the directions of the allowable moment and overhang load length when using the double slider (option).
(*3) The value is when the straightness high precision specification (option) is specified.

· Reference for overhang load length: Ma: 600mm or less, Mb, Mc: 600mm or less



Direction of the dynamic allowable moment



Direction of the allowable overhang load length

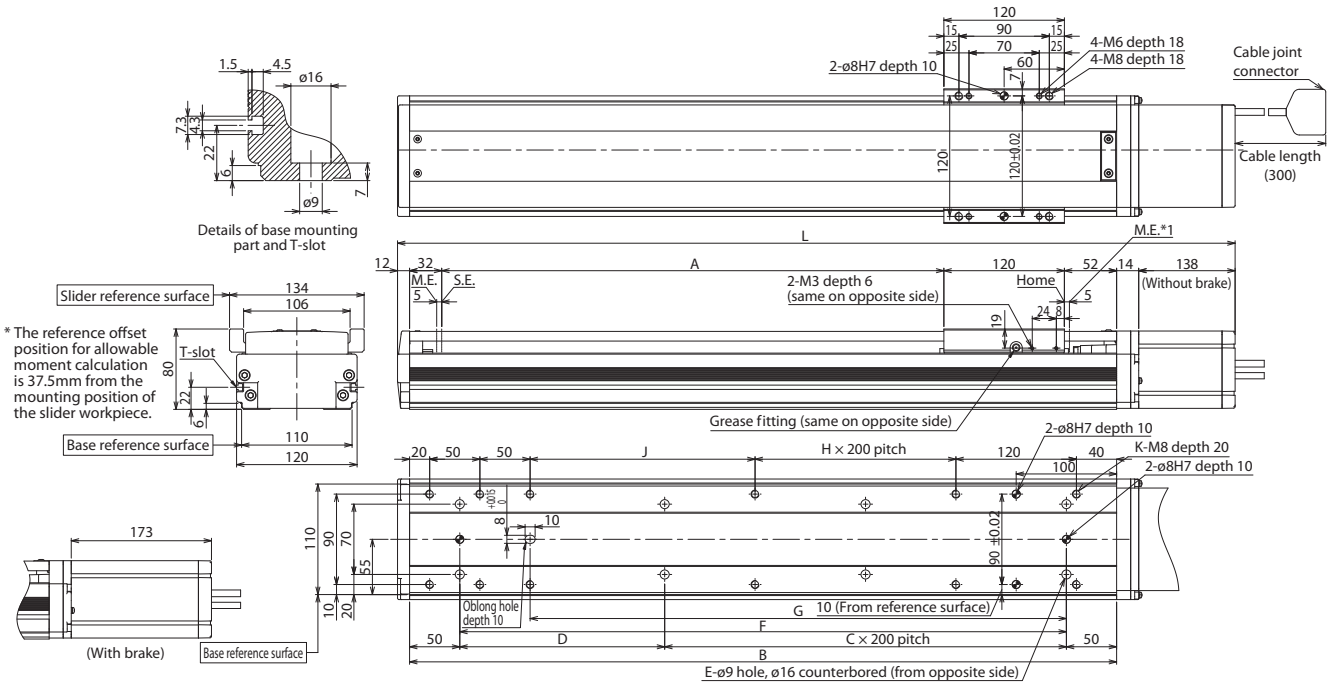
Please refer to the ISB/ISDB basic catalogue for more information regarding the directions of the allowable moment and overhang load length.

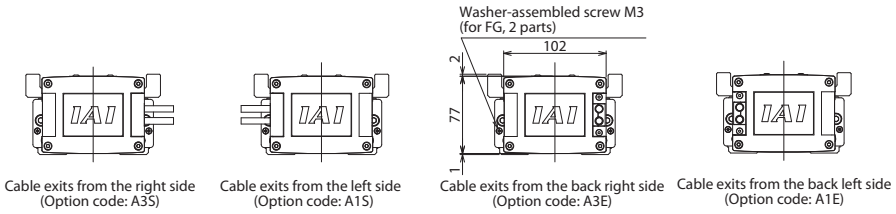
Dimensions

CAD drawings can be downloaded from our website.
www.intelligentactuator.de

*1 When the slider is returning to its home position, please be careful of interference from surrounding objects, as it will travel until it reaches the M.E.
M.E: Mechanical end
S.E: Stroke end

*2 If the home direction needs to be changed after purchase, the actuator must be returned to IAI for adjustment.





■ Dimensions and Mass by Stroke

Stroke		100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100	1150	1200	1250	1300
L	w/o brake	468	518	568	618	668	718	768	818	868	918	968	1018	1068	1118	1168	1218	1268	1318	1368	1418	1468	1518	1568	1618	1668
	w/brake	503	553	603	653	703	753	803	853	903	953	1003	1053	1103	1153	1203	1253	1303	1353	1403	1453	1503	1553	1603	1653	1703
A		100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100	1150	1200	1250	1300
B		304	354	404	454	504	554	604	654	704	754	804	854	904	954	1004	1054	1104	1154	1204	1254	1304	1354	1404	1454	1504
C		0	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6	6	6
D		204	254	104	154	204	254	104	154	204	254	104	154	204	254	104	154	204	254	104	154	204	254	104	154	204
E		4	4	6	6	6	6	8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16
F		204	254	304	354	404	454	504	554	604	654	704	754	804	854	904	954	1004	1054	1104	1154	1204	1254	1304	1354	1404
G		134	184	234	284	334	384	434	484	534	584	634	684	734	784	834	884	934	984	1034	1084	1134	1184	1234	1284	1334
H		0	0	0	0	0	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5
J		24	74	124	174	224	274	124	174	224	274	124	174	224	274	124	174	224	274	124	174	224	274	124	174	224
K		10	10	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16	16	18	18	18	18	20	20	20
Mass (kg)	w/o brake	7.0	7.6	8.3	8.9	9.5	10.2	10.8	11.4	12.1	12.7	13.3	14.0	14.6	15.2	15.9	16.5	17.2	17.8	18.4	19.1	19.7	20.3	21.0	21.6	22.2
	w/brake	7.6	8.2	8.9	9.5	10.1	10.8	11.4	12.0	12.7	13.3	13.9	14.6	15.2	15.8	16.5	17.1	17.7	18.4	19.0	19.6	20.3	20.9	21.6	22.2	22.8

Applicable Controllers

The ISB series actuators can be operated by the controllers indicated below. Please select the type depending on your intended use.

Type	External view	Max. number of controlled axes	Power supply voltage	Control method				Maximum number of positioning points	Ref. page
				Positioner	Pulse-train	Program	Network *Option		
SCON-CB/CGB		1	Single-phase 230VAC	●	●	–	DeviceNet, CC-Link, PROFIBUS, CompoNet, EtherCAT, EtherNet/IP, PROFINET	512 points (768 for network spec.)	Please contact IAI for more details
SCON-LC/LCG		1		–	–	●		512 points (768 for network spec.)	
SSEL-CS		2	Single-phase 115/230VAC	●	–	●		20000	
XSEL-P/Q		6	Single-phase 230VAC Three-phase 230VAC	–	–	●	Note: The type of compatible networks will vary depending on the controller. Please contact IAI for more details.	20000	

ISB-MXL-400

±10μm Standard | Battery-less Absolute | Medium X-axis Type | Long slider | Body Width 120 mm | 400 W

■ Model Specification Items

ISB — MXL — WA — 400 — 48 — ☐ — T2 — ☐ — ☐

Series	Type	Encoder Type	Motor Type	Lead	Stroke	Applicable Controllers	Cable Length	Options
ISB	MXL	WA: Battery-less absolute	400 : 400W	48 : 48mm	120 : 120mm ~ 1270 : 1270mm (50mm increments)	T2 : SCON SSEL XSEL-P/Q	N : None S : 3m M : 5m X☐☐ : Specified Length	Please refer to the option table below

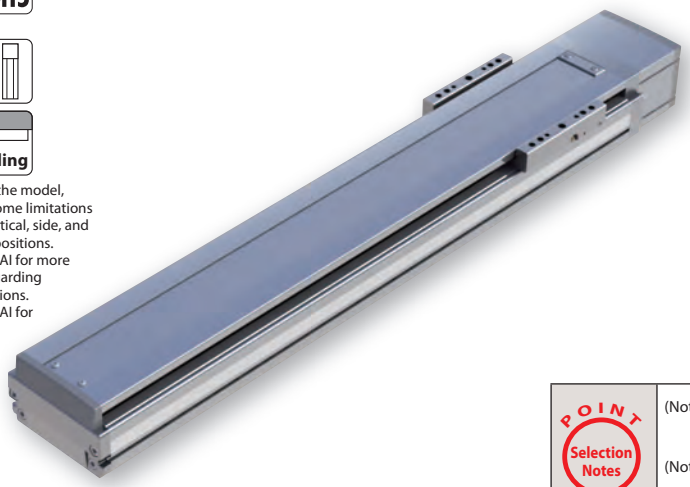
* Does not include a controller.
* Please contact IAI for more information about the model specification items.

* Be sure to specify the AQ seal (AQ) option. Be sure to select a symbol for the cable outlet direction.

CE RoHS

Horizontal | Vertical | Side | Ceiling

* Depending on the model, there may be some limitations to using the vertical, side, and ceiling mount positions. Please contact IAI for more information regarding mounting positions. Please contact IAI for more details.



POINT Selection Notes

(Note 1) The value of payload is when operating at an acceleration of 0.4G. When the acceleration is increased, the payload will be reduced. Please refer to P.21 for more information.

(Note 2) The straightness of straight line motion is the value when the straightness high precision specifications (optional) are specified.

Model/Specifications

■ Lead and Payload

Model	Motor wattage (W)	Lead (mm)	Max. payload (*1) Horizontal (kg)	Max. payload (*1) Vertical (kg)	Rated thrust (N)	Stroke (mm)
ISB-MXL-WA-400-48-①-T2-②-③	400	48	20	6	141.3	120~1270 (Every 50mm)

Legend: ① Stroke ② Cable length ③ Option

(*1) Refer to P. 21 for the relationship of acceleration and payload.

■ Stroke and Max. Speed

Stroke	120	170	220	270	320	370	420
Max. Speed	1325	1575	1825	2025	2200	2350	2400

Stroke	470	520	570	620	670	720	770
Max. Speed	2500					2270	2030

Stroke	820	870	920	970	1020	1070	1120
Max. Speed	1825	1645	1495	1365	1250	1150	1060

Stroke	1170	1220	1270
Max. Speed	980	910	845

(Unit: mm/s)

Cable Length

Type	Cable code	Standard	With LS
Standard type	**S** (3m)	○	
	M (5m)	○	
Specified length	**X06** (6m) ~**X10** (10m)	○	○
	X11 (11m) ~**X20** (20m)	○	○

* Only the robot cable is available for this model.
* Please contact IAI for more information regarding the maintenance cables.
* When using a cable of 21 to 30m, specify "N" for the cable length of the actuator model, and separately purchase the motor cable [CB-X(EU)-MA☐☐☐], encoder cable [CB-X(EU)1-PA☐☐☐-AWG24] or encoder cable with LS [CB-X(EU)1-PLA☐☐☐-AWG24]. (Please contact IAI for more details on the cable.)

Options

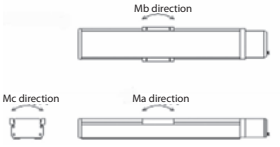
Type	Model	Ref. Page	Type	Model	Ref. Page
Cable exits from the left side	**A1S**	See P.19	Home limit switch symmetrically opposite	**LL**	See P.19
Cable exits from the back left side	**A1E**	See P.19	Master axis specified	**LM**	See P.19
Cable exits from the right side	**A3S**	See P.19	Master axis spec. (sensor symmetrically opposite)	**LLM**	See P.19
Cable exits from the back right side	**A3E**	See P.19	Non-motor end spec.	**NM**	See P.19
AQ seal (standard feature)	**AQ**	See P.19	-	-	-
Brake	**B**	See P.19	Slave axis specified	**S**	See P.19
Creep sensor	**C**	See P.19	Straightness high precision specification	**ST**	See P.20
Creep sensor symmetrically opposite	**CL**	See P.19	Double slider specification	**W**	See P.20
Home limit switch	**L**	See P.19	Round cable joint connector with screw locking	**EU**	See P.19

Actuator Specifications

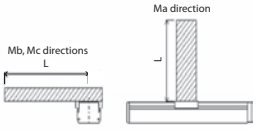
Item	Description
Positioning repeatability	±0.01mm
Drive system	Ball screw ϕ16mm, rolled C10
Lost motion	0.05mm or less
Static allowable moment	Ma: 560.3N·m Mb: 800.2N·m Mc: 1030.8N·m
Dynamic allowable moment (*1) (*2)	Ma: 123.0N·m Mb: 176.0N·m Mc: 227.0N·m
Dyn. straightness of straight line motion (*3)	0.02mm/m or less
Base	Material: Aluminum with white alumite treatment
Ambient operating temp. & humidity	0~40°C, 85% RH or less (Non-condensing)

(*1) Assumes a standard rated life of 10000km. The service life will vary depending on operation and installation conditions. Please contact IAI for the running life.
(*2) Please refer to P.22 for more information regarding the directions of the allowable moment and overhang load length when using the double slider (option).
(*3) The value is when the straightness high precision specification (option) is specified.

· Reference for overhang load length: Ma: 750mm or less, Mb, Mc: 750mm or less



Direction of the dynamic allowable moment



Direction of the allowable overhang load length

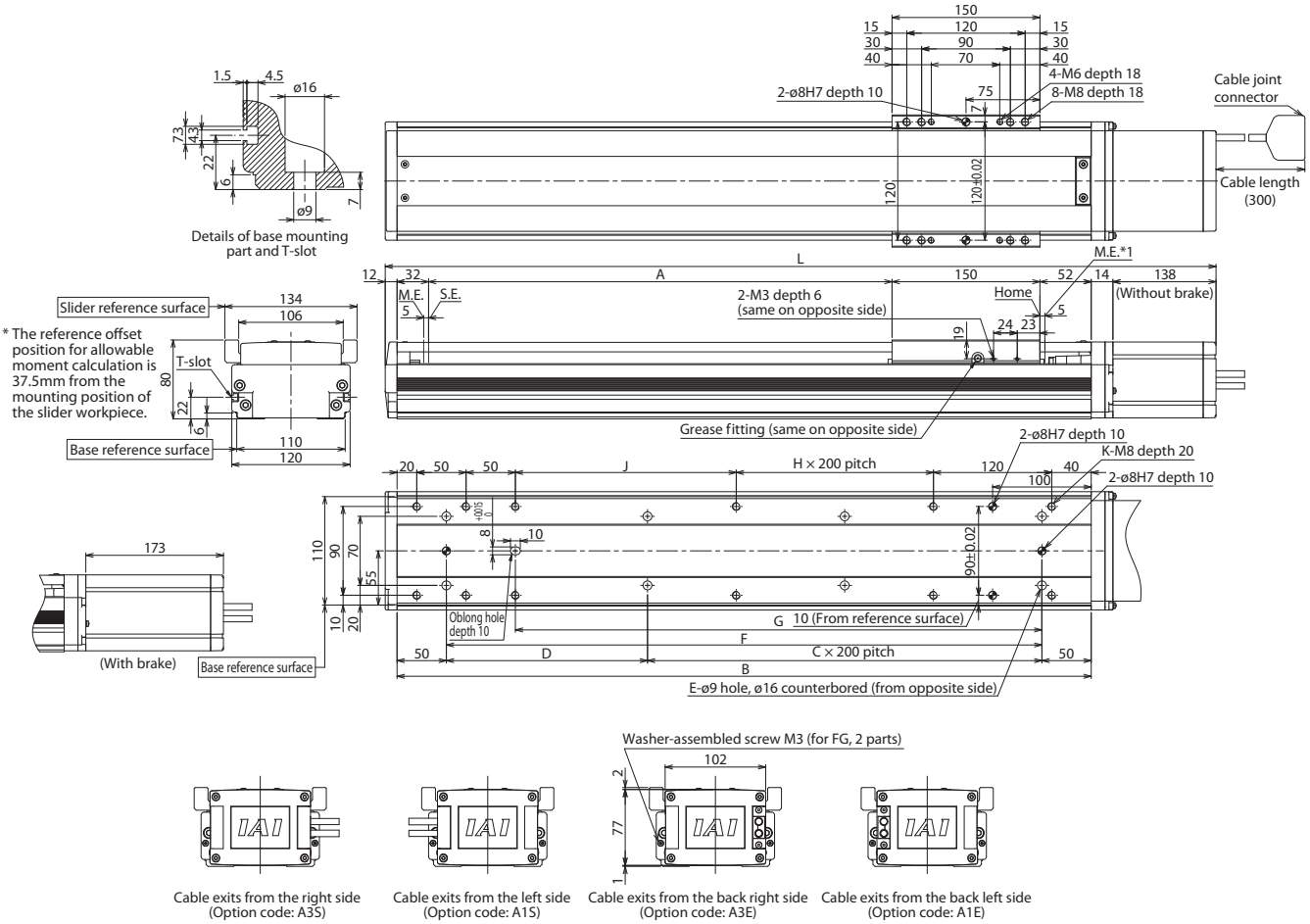
Please refer to the ISB/ISDB basic catalogue for more information regarding the directions of the allowable moment and overhang load length.

Dimensions

CAD drawings can be downloaded from our website.
www.intelligentactuator.de

*1 When the slider is returning to its home position, please be careful of interference from surrounding objects, as it will travel until it reaches the M.E.
M.E: Mechanical end
S.E: Stroke end

*2 If the home direction needs to be changed after purchase, the actuator must be returned to IAI for adjustment.



■ Dimensions and Mass by Stroke

Stroke		120	170	220	270	320	370	420	470	520	570	620	670	720	770	820	870	920	970	1020	1070	1120	1170	1220	1270
L	w/o brake	518	568	618	668	718	768	818	868	918	968	1018	1068	1118	1168	1218	1268	1318	1368	1418	1468	1518	1568	1618	1668
	w/brake	553	603	653	703	753	803	853	903	953	1003	1053	1103	1153	1203	1253	1303	1353	1403	1453	1503	1553	1603	1653	1703
A		120	170	220	270	320	370	420	470	520	570	620	670	720	770	820	870	920	970	1020	1070	1120	1170	1220	1270
B		354	404	454	504	554	604	654	704	754	804	854	904	954	1004	1054	1104	1154	1204	1254	1304	1354	1404	1454	1504
C		0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6	6	6
D		254	104	154	204	254	104	154	204	254	104	154	204	254	104	154	204	254	104	154	204	254	104	154	204
E		4	6	6	6	6	8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16
F		254	304	354	404	454	504	554	604	654	704	754	804	854	904	954	1004	1054	1104	1154	1204	1254	1304	1354	1404
G		184	234	284	334	384	434	484	534	584	634	684	734	784	834	884	934	984	1034	1084	1134	1184	1234	1284	1334
H		0	0	0	0	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5
J		74	124	174	224	274	124	174	224	274	124	174	224	274	124	174	224	274	124	174	224	274	124	174	224
K		10	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16	16	18	18	18	18	20	20	20
Mass (kg)	w/o brake	7.9	8.6	9.2	9.8	10.5	11.1	11.7	12.4	13.0	13.6	14.3	14.9	15.5	16.2	16.8	17.5	18.1	18.7	19.4	20.0	20.6	21.3	21.9	22.5
	w/brake	8.5	9.2	9.8	10.4	11.1	11.7	12.3	13.0	13.6	14.2	14.9	15.5	16.1	16.8	17.4	18.0	18.7	19.3	19.9	20.6	21.2	21.9	22.5	23.1

Applicable Controllers

The ISB series actuators can be operated by the controllers indicated below. Please select the type depending on your intended use.

Type	External view	Max. number of controlled axes	Power supply voltage	Control method				Maximum number of positioning points	Ref. page
				Positioner	Pulse-train	Program	Network *Option		
SCON-CB/CGB		1	Single-phase 230VAC	●	●	–	DeviceNet, CC-Link, PROFIBUS, CompoNet, EtherCAT, EtherNet/IP, PROFINET	512 points (768 for network spec.)	Please contact IAI for more details
SCON-LC/LCG		1		–	–	●		512 points (768 for network spec.)	
SSEL-CS		2	Single-phase 115/230VAC	●	–	●		20000	
XSEL-P/Q		6	Single-phase 230VAC Three-phase 230VAC	–	–	●	Note: The type of compatible networks will vary depending on the controller. Please contact IAI for more details.	20000	

ISB-MXMX-400

±10μm Standard | Battery-less Absolute | Medium X-axis Type | Intermediate Support Type | Body Width 120 mm | 400 W

■ Model Specification Items

Series	Type	Encoder Type	Motor Type	Lead	Stroke	Applicable Controllers	Cable Length	Options
ISB	MXMX	WA	400	48	□	T2	□	□
		WA: Battery-less absolute	400 : 400W	48 : 48mm	800 : 800mm ~ 2000 : 2000mm (50mm increments)	T2 : SCON SSEL XSEL-P/Q	N : None S : 3m M : 5m X□□ : Specified Length	Please refer to the option table below

* Does not include a controller.
* Please contact IAI for more information about the model specification items.

* Be sure to specify the AQ seal (AQ) option. Be sure to select a symbol for the cable outlet direction.

CE RoHS

Horizontal | Vertical | Side | Ceiling

* Depending on the model, there may be some limitations to using the ceiling mount positions. Please contact IAI for more information regarding mounting positions. Please contact IAI for more details.

POINT Selection Notes

(Note 1) The value of payload is when operating at an acceleration of 0.4G. Please refer to P.21 for more information.

(Note 2) The value of straightness of straight line motion is when specifying the straightness high precision specifications (optional).

Model/Specifications

■ Lead and Payload

Model	Motor wattage (W)	Lead (mm)	Max. payload (*1) Horizontal (kg)	Max. payload (*1) Vertical (kg)	Rated thrust (N)	Stroke (mm)
ISB-MXMX-WA-400-48-①-T2-②-③	400	48	20	–	141.3	800~2000 (Every 50mm)

Legend: ① Stroke ② Cable length ③ Option

(*1) Refer to P. 21 for the relationship of acceleration and payload.

■ Stroke and Max. Speed

Stroke	800	850	900	950	1000	1050	1100
Max. Speed	1700	1750	1800	1850	1900	1950	2000

Stroke	1150	1200	1250	1300	1350	1400	1450
Max. Speed	2050	2100	2150	2200	2065	1925	1805

Stroke	1500	1550	1600	1650	1700	1750	1800
Max. Speed	1690	1590	1495	1410	1335	1265	1195

Stroke	1850	1900	1950	2000
Max. Speed	1135	1080	1025	980

(Unit: mm/s)

Cable Length

Type	Cable code	Standard	With LS
Standard type	**S** (3m)	○	
	M (5m)	○	
Specified length	**X06** (6m) ~**X10** (10m)	○	○
	X11 (11m) ~**X20** (20m)	○	○

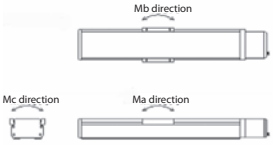
* Only the robot cable is available for this model.
* Please contact IAI for more information regarding the maintenance cables.
* When using a cable of 21 to 30m, specify "N" for the cable length of the actuator model, and separately purchase the motor cable [CB-X(EU)-MA□□□], encoder cable [CB-X(EU)1-PA□□□-AWG24] or encoder cable with LS [CB-X(EU)1-PLA□□□-AWG24]. (Please contact IAI for more details on the cable.)

Actuator Specifications

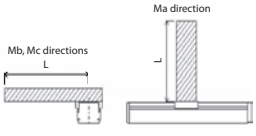
Item	Description
Positioning repeatability	±0.01mm
Drive system	Ball screw ϕ16mm, rolled C10
Lost motion	0.05mm or less
Static allowable moment	Ma: 341.5N·m Mb: 487.0N·m Mc: 796.5N·m
Dynamic allowable moment (*1)	Ma: 81.0N·m Mb: 116.0N·m Mc: 189.0N·m
Dyn. straightness of straight line motion (*2)	0.02mm/m or less
Base	Material: Aluminum with white alumite treatment
Ambient operating temp. & humidity	0~40°C, 85% RH or less (Non-condensing)

(*1) Assumes a standard rated life of 10000km. The service life will vary depending on operation and installation conditions. Please contact IAI for the running life.
(*2) The value is when the straightness high precision specification (option) is specified.

· Reference for overhang load length: Ma: 600mm or less, Mb, Mc: 600mm or less



Direction of the dynamic allowable moment



Direction of the allowable overhang load length

Please refer to the ISB/ISDB basic catalogue for more information regarding the directions of the allowable moment and overhang load length.

Options

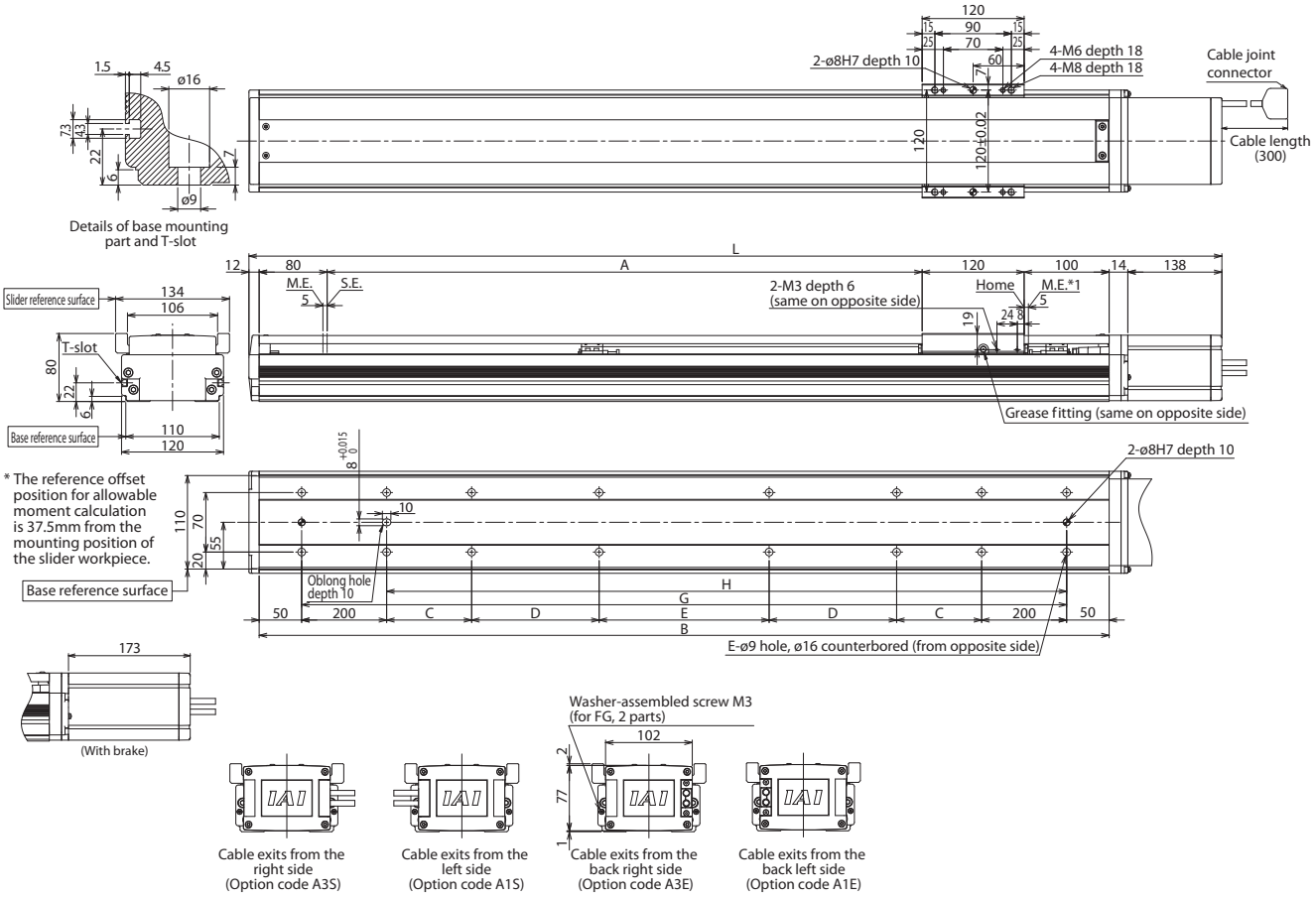
Type	Model	Ref. Page	Type	Model	Ref. Page
Cable exits from the left side	**A1S**	See P.19	Home limit switch symmetrically opposite	**LL**	See P.19
Cable exits from the back left side	**A1E**	See P.19	Master axis specified	**LM**	See P.19
Cable exits from the right side	**A3S**	See P.19	Master axis spec. (sensor symmetrically opposite)	**LLM**	See P.19
Cable exits from the back right side	**A3E**	See P.19	Non-motor end spec.	**NM**	See P.19
AQ seal (standard feature)	**AQ**	See P.19	Guide with ball retention mechanism	**RT**	See P.20
Brake	**B**	See P.19	Slave axis specified	**S**	See P.19
Creep sensor	**C**	See P.19	Straightness high precision specification	**ST**	See P.20
Creep sensor symmetrically opposite	**CL**	See P.19	-	**-**	-
Home limit switch	**L**	See P.19	Round cable joint connector with screw locking	**EU**	See P.19

Dimensions

CAD drawings can be downloaded from our website.
www.intelligentactuator.de

*1 When the slider is returning to its home position, please be careful of interference from surrounding objects, as it will travel until it reaches the M.E.
M.E: Mechanical end
S.E: Stroke end

*2 If the home direction needs to be changed after purchase, the actuator must be returned to IAI for adjustment.



■ Dimensions and Mass by Stroke

Stroke		800	850	900	950	1000	1050	1100	1150	1200	1250	1300	1350	1400	1450	1500	1550	1600	1650	1700	1750	1800	1850	1900	1950	2000
L	w/o brake	1264	1314	1364	1414	1464	1514	1564	1614	1664	1714	1764	1814	1864	1914	1964	2014	2064	2114	2164	2214	2264	2314	2364	2414	2464
	w/brake	1299	1349	1399	1449	1499	1549	1599	1649	1699	1749	1799	1849	1899	1949	1999	2049	2099	2149	2199	2249	2299	2349	2399	2449	2499
A		800	850	900	950	1000	1050	1100	1150	1200	1250	1300	1350	1400	1450	1500	1550	1600	1650	1700	1750	1800	1850	1900	1950	2000
B		1100	1150	1200	1250	1300	1350	1400	1450	1500	1550	1600	1650	1700	1750	1800	1850	1900	1950	2000	2050	2100	2150	2200	2250	2300
C		200	200	200	200	200	225	250	275	300	325	350	375	400	425	450	475	500	525	550	575	200	200	200	200	200
D		0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	400	425	450	475	500
E		200	250	300	350	400	400	400	400	400	400	400	400	400	400	400	400	400	400	400	400	400	400	400	400	400
F		12	12	12	12	12	12	12	12	12	12	12	12	12	12	12	12	12	12	12	12	16	16	16	16	16
G		1000	1050	1100	1150	1200	1250	1300	1350	1400	1450	1500	1550	1600	1650	1700	1750	1800	1850	1900	1950	2000	2050	2100	2150	2200
H		800	850	900	950	1000	1050	1100	1150	1200	1250	1300	1350	1400	1450	1500	1550	1600	1650	1700	1750	1800	1850	1900	1950	2000
Mass (kg)	w/o brake	17.1	17.7	18.4	19.0	19.6	20.3	20.9	21.5	22.2	22.8	23.4	24.1	24.7	25.4	26.0	26.6	27.3	27.9	28.5	29.2	29.8	30.4	31.1	31.7	32.3
	w/brake	17.7	18.3	19.0	19.6	20.2	20.9	21.5	22.1	22.8	23.4	24.0	24.7	25.3	25.9	26.6	27.2	27.8	28.5	29.1	29.8	30.4	31.0	31.7	32.3	32.9

Applicable Controllers

The ISB series actuators can be operated by the controllers indicated below. Please select the type depending on your intended use.

Type	External view	Max. number of controlled axes	Power supply voltage	Control method				Maximum number of positioning points	Ref. page
				Positioner	Pulse-train	Program	Network *Option		
SCON-CB/CGB		1	Single-phase 230VAC	●	●	–	DeviceNet, CC-Link, PROFIBUS, CompoNet, EtherCAT, EtherNet/IP, PROFINET	512 points (768 for network spec.)	Please contact IAI for more details
SCON-LC/LCG		1		–	–	●		512 points (768 for network spec.)	
SSEL-CS		2	Single-phase 115/230VAC	●	–	●		20000	
XSEL-P/Q		6	Single-phase 230VAC Three-phase 230VAC	–	–	●	Note: The type of compatible networks will vary depending on the controller. Please contact IAI for more details.	20000	

ISDB-S-100

±10μm Standard | Battery-less Absolute | Simple Dust-proof | Small type | Body Width 90 mm | 100 W

■ Model Specification Items

ISDB	S	WA	100	36	☐	T2	☐	☐
Series	Type	Encoder Type	Motor Type	Lead	Stroke	Applicable Controllers	Cable Length	Options
		WA: Battery-less absolute	100 : 100W	36 : 36mm	100 : 100mm ~ 800 : 800mm (50mm increments)	T2 : SCON MSCON SSEL XSEL-P/Q	N : None S : 3m M : 5m X☐☐ : Specified Length	Please refer to the option table below

* Does not include a controller.
* Please contact IAI for more information about the model specification items.

* Be sure to specify the AQ seal (AQ) option. Be sure to select a symbol for the cable outlet direction.

CE RoHS

Horizontal | Vertical | Side | Ceiling

* Depending on the model, there may be some limitations to using the vertical, side, and ceiling mount positions. Please contact IAI for more information regarding mounting positions. Please contact IAI for more details.

POINT Selection Notes

(Note 1) The value of payload is when operating at an acceleration of 0.4G. When the acceleration is increased, the payload will be reduced. Please refer to P.21 for more information.

(Note 2) The value of straightness of straight line motion is when specifying the straightness high precision specifications (optional).

Model/Specifications

■ Lead and Payload

Model	Motor wattage (W)	Lead (mm)	Max. payload (*1)		Rated thrust (N)	Stroke (mm)
			Horizontal (kg)	Vertical (kg) (*2)		
ISDB-S-WA-100-36-①-T2-②-③	100	36	10	2	47.2	100~800 (Every 50mm)

Legend: ① Stroke ② Cable length ③ Option

(*1) Refer to P. 21 for the relationship of acceleration and payload.
(*2) If the guide with ball retention mechanism (RT) is used, the vertical payload decreases by 0.5kg.

■ Stroke and Max. Speed

Stroke	100	150	200	250	300	350	400
Max. Speed	1075	1370	1620	1830	1940	1980	2000

Stroke	450	500	550	600	650	700	750
Max. Speed	2000			1825	1590	1400	1240

Stroke	800
Max. Speed	1105

(Unit: mm/s)

Cable Length

Type	Cable code	Standard	With LS
Standard type	**S** (3m)	○	
	M (5m)	○	
Specified length	**X06** (6m) ~**X10** (10m)	○	○
	X11 (11m) ~**X20** (20m)	○	○

* Only the robot cable is available for this model.
* Please contact IAI for more information regarding the maintenance cables.
* When using a cable of 21 to 30m, specify "N" for the cable length of the actuator model, and separately purchase the motor cable [CB-X(EU)-MA☐☐☐], encoder cable [CB-X(EU)1-PA☐☐☐-AWG24] or encoder cable with LS [CB-X(EU)1-PLA☐☐☐-AWG24]. (Please contact IAI for more details on the cable.)

Options

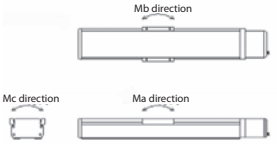
Type	Model	Ref. Page	Type	Model	Ref. Page
Cable exits from the left side	**A1S**	See P.19	Master axis specified	**LM**	See P.19
Cable exits from the back left side	**A1E**	See P.19	Master axis spec. (sensor symmetrically opposite)	**LLM**	See P.19
Cable exits from the right side	**A3S**	See P.19	Non-motor end spec.	**NM**	See P.19
Cable exits from the back right side	**A3E**	See P.19	Guide with ball retention mechanism	**RT**	See P.20
AQ seal (standard feature)	**AQ**	See P.19	Slave axis specified	**S**	See P.19
Brake	**B**	See P.19	Slider section roller specification	**SR**	See P.20
Creep sensor	**C**	See P.19	Straightness high precision specification	**ST**	See P.20
Creep sensor symmetrically opposite	**CL**	See P.19	Double slider specification	**W**	See P.20
Home limit switch	**L**	See P.19	Round cable joint connector with screw locking	**EU**	See P.19
Home limit switch symmetrically opposite	**LL**	See P.19			

Actuator Specifications

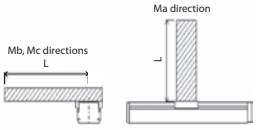
Item	Description
Positioning repeatability	±0.01mm
Drive system	Ball screw ϕ12mm, rolled C10
Lost motion	0.05mm or less
Static allowable moment	Ma: 143.8N·m Mb: 205.4N·m Mc: 336.0N·m
Dynamic allowable moment (*1) (*2)	Ma: 32.9N·m Mb: 47.0N·m Mc: 76.8N·m
Dyn. straightness of straight line motion (*3)	0.02mm/m or less
Base	Material: Aluminum with white alumite treatment
Protective structure	IP30
Ambient operating temp. & humidity	0~40°C, 85% RH or less (Non-condensing)

(*1) Assumes a standard rated life of 10000km. The service life will vary depending on operation and installation conditions. Please contact IAI for the running life.
(*2) Please refer to P.22 for more information regarding the directions of the allowable moment and overhang load length when using the double slider (option).
(*3) The value is when the straightness high precision specification (option) is specified.

· Reference for overhang load length: Ma: 450mm or less, Mb, Mc: 450mm or less



Direction of the dynamic allowable moment



Direction of the allowable overhang load length

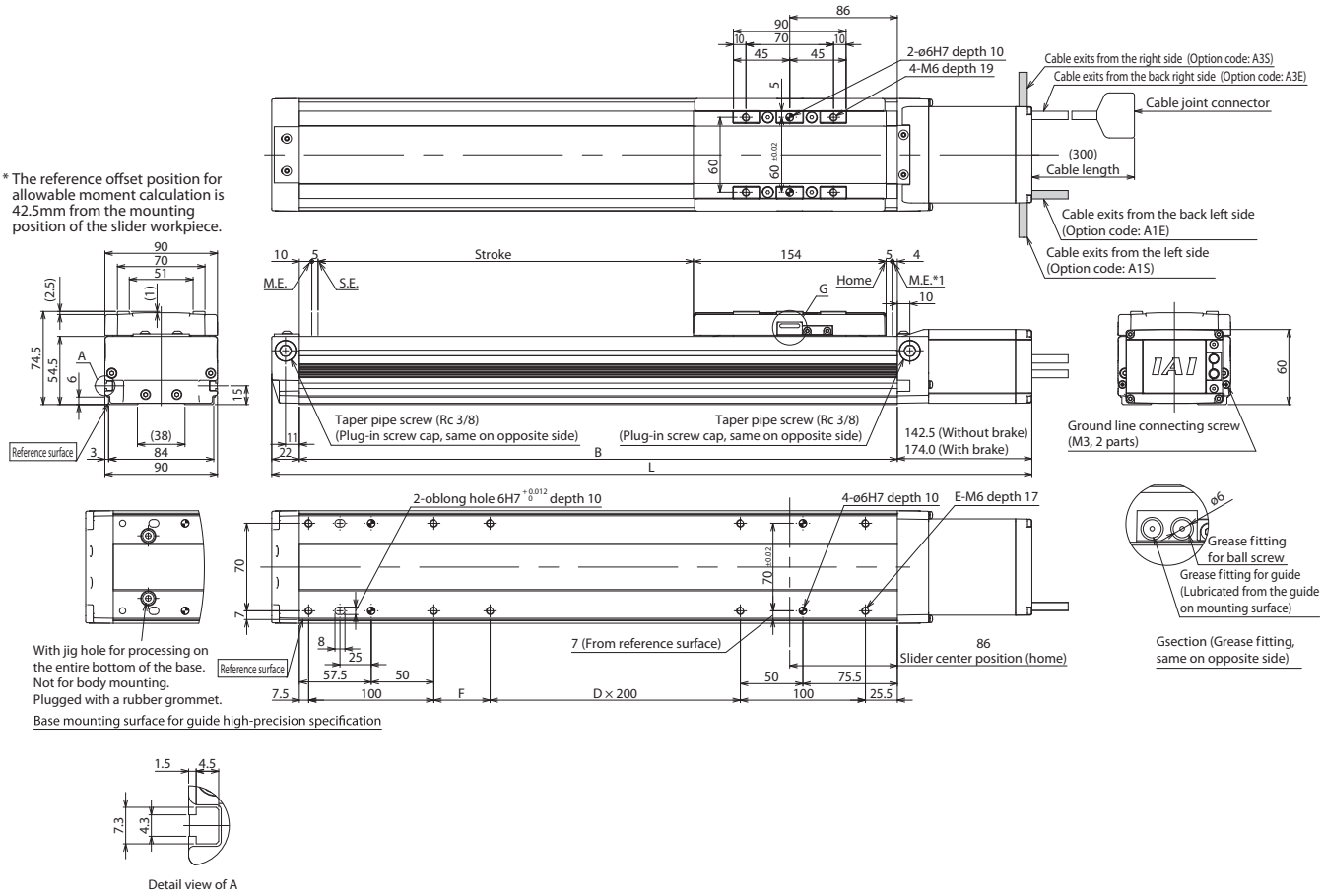
Please refer to the ISB/ISDB basic catalogue for more information regarding the directions of the allowable moment and overhang load length.

Dimensions

CAD drawings can be downloaded from our website.
www.intelligentactuator.de

*1 When the slider is returning to its home position, please be careful of interference from surrounding objects, as it will travel until it reaches the M.E.
M.E: Mechanical end
S.E: Stroke end

*2 If the home direction needs to be changed after purchase, the actuator must be returned to IAI for adjustment.



■ Dimensions and Mass by Stroke

Stroke		100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
L	w/o brake	442.5	492.5	542.5	592.5	642.5	692.5	742.5	792.5	842.5	892.5	942.5	992.5	1042.5	1092.5	1142.5
	w/brake	474	524	574	624	674	724	774	824	874	924	974	1024	1074	1124	1174
B		278	328	378	428	478	528	578	628	678	728	778	828	878	928	978
D		0	0	0	0	1	1	1	1	2	2	2	2	3	3	3
E		8	8	8	8	10	10	10	10	12	12	12	12	14	14	14
F		45	95	145	195	45	95	145	195	45	95	145	195	45	95	145
Mass (kg)	w/o brake	4.3	4.6	5.0	5.4	5.7	6.1	6.4	6.8	7.2	7.5	7.9	8.2	8.6	9.0	9.3
	w/brake	4.6	4.9	5.3	5.7	6.0	6.4	6.7	7.1	7.5	7.8	8.2	8.5	8.9	9.3	9.6

Applicable Controllers

The ISDB series actuators can be operated by the controllers indicated below. Please select the type depending on your intended use.

Type	External view	Max. number of controlled axes	Power supply voltage	Control method				Maximum number of positioning points	Ref. page
				Positioner	Pulse-train	Program	Network *Option		
SCON-CB/CGB		1	Single-phase 115/230VAC	●	●	–	DeviceNet, CC-Link, PROFIBUS, CompoNet, EtherCAT, EtherNet/IP, PROFINET	512 points (768 for network spec.)	Please contact IAI for more details
SCON-LC/LCG		1		–	–	●		512 points (768 for network spec.)	
SCON-CAL/CGAL		1		●	–	–		512 points (768 for network spec.)	
MSCON-C		6		This model is network-compatible only.				256	
SSEL-CS		2		●	–	●	Note: The type of compatible networks will vary depending on the controller. Please contact IAI for more details.	20000	
XSEL-P/Q		6	Single-phase 230VAC Three-phase 230VAC	–	–	●		20000	

ISDB-M-400

±10μm Standard | Battery-less Absolute | Simple Dust-proof | Medium type | Body Width 120 mm | 400 W

■ Model Specification Items

ISDB	M	WA	400	48	□	T2	□	□
Series	Type	Encoder Type	Motor Type	Lead	Stroke	Applicable Controllers	Cable Length	Options
		WA: Battery-less absolute	400 : 400W	48 : 48mm	100 : 100mm ~ 1100 : 1100mm (50mm increments)	T2 : SCON SSEL XSEL-P/Q	N : None S : 3m M : 5m X□□ : Specified Length	Please refer to the option table below

* Does not include a controller.
* Please contact IAI for more information about the model specification items.

* Be sure to specify the AQ seal (AQ) option. Be sure to select a symbol for the cable outlet direction.

CE RoHS

Horizontal | Vertical | Side | Ceiling

* Depending on the model, there may be some limitations to using the vertical, side, and ceiling mount positions. Please contact IAI for more information regarding mounting positions. Please contact IAI for more details.

POINT Selection Notes

(Note 1) The value of payload is when operating at an acceleration of 0.4G. When the acceleration is increased, the payload will be reduced. Please refer to P.21 for more information.

(Note 2) The value of straightness of straight line motion is when specifying the straightness high precision specifications (optional).

Model/Specifications

■ Lead and Payload

Model	Motor wattage (W)	Lead (mm)	Max. payload (*1) Horizontal (kg)	Max. payload (*1) Vertical (kg)	Rated thrust (N)	Stroke (mm)
ISDB-M-WA-400-48-①-T2-②-③	400	48	20	6	141.3	100~1100 (Every 50mm)

Legend: ① Stroke ② Cable length ③ Option

(*1) Refer to P. 21 for the relationship of acceleration and payload.

■ Stroke and Max. Speed

Stroke	100	150	200	250	300	350	400
Max. Speed	980	1270	1520	1740	1930	2050	2125

Stroke	450	500	550	600	650	700	750
Max. Speed	2200						2145

Stroke	800	850	900	950	1000	1050	1100
Max. Speed	1920	1730	1570	1430	1305	1195	1105

(Unit: mm/s)

Cable Length

Type	Cable code	Standard	With LS
Standard type	**S** (3m)	○	
	M (5m)	○	
Specified length	**X06** (6m) ~**X10** (10m)	○	○
	X11 (11m) ~**X20** (20m)	○	○

* Only the robot cable is available for this model.
* Please contact IAI for more information regarding the maintenance cables.
* When using a cable of 21 to 30m, specify "N" for the cable length of the actuator model, and separately purchase the motor cable [CB-X(EU)-MA□□□], encoder cable [CB-X(EU)1-PA□□□-AWG24] or encoder cable with LS [CB-X(EU)1-PLA□□□-AWG24]. (Please contact IAI for more details on the cable.)

Options

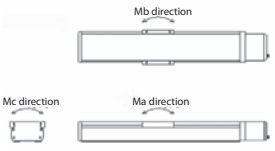
Type	Model	Ref. Page	Type	Model	Ref. Page
Cable exits from the left side	**A1S**	See P.19	Master axis specified	**LM**	See P.19
Cable exits from the back left side	**A1E**	See P.19	Master axis spec. (sensor symmetrically opposite)	**LLM**	See P.19
Cable exits from the right side	**A3S**	See P.19	Non-motor end spec.	**NM**	See P.19
Cable exits from the back right side	**A3E**	See P.19	Guide with ball retention mechanism	**RT**	See P.20
AQ seal (standard feature)	**AQ**	See P.19	Slave axis specified	**S**	See P.19
Brake	**B**	See P.19	Slider section roller specification	**SR**	See P.20
Creep sensor	**C**	See P.19	Straightness high precision specification	**ST**	See P.20
Creep sensor symmetrically opposite	**CL**	See P.19	Double slider specification	**W**	See P.20
Home limit switch	**L**	See P.19	Round cable joint connector with screw locking	**EU**	See P.19
Home limit switch symmetrically opposite	**LL**	See P.19			

Actuator Specifications

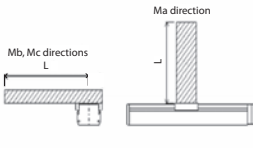
Item	Description
Positioning repeatability	±0.01mm
Drive system	Ball screw ϕ16mm, rolled C10
Lost motion	0.05mm or less
Static allowable moment	Ma: 341.5N·m Mb: 487.0N·m Mc: 796.5N·m
Dynamic allowable moment (*1) (*2)	Ma: 81.0N·m Mb: 116.0N·m Mc: 189.0N·m
Dyn. straightness of straight line motion (*3)	0.02mm/m or less
Base	Material: Aluminum with white alumite treatment
Protective structure	IP30
Ambient operating temp. & humidity	0~40°C, 85% RH or less (Non-condensing)

(*1) Assumes a standard rated life of 10000km. The service life will vary depending on operation and installation conditions. Please contact IAI for the running life.
(*2) Please refer to P.22 for more information regarding the directions of the allowable moment and overhang load length when using the double slider (option).
(*3) The value is when the straightness high precision specification (option) is specified.

· Reference for overhang load length: Ma: 600mm or less, Mb, Mc: 600mm or less



Direction of the dynamic allowable moment



Direction of the allowable overhang load length

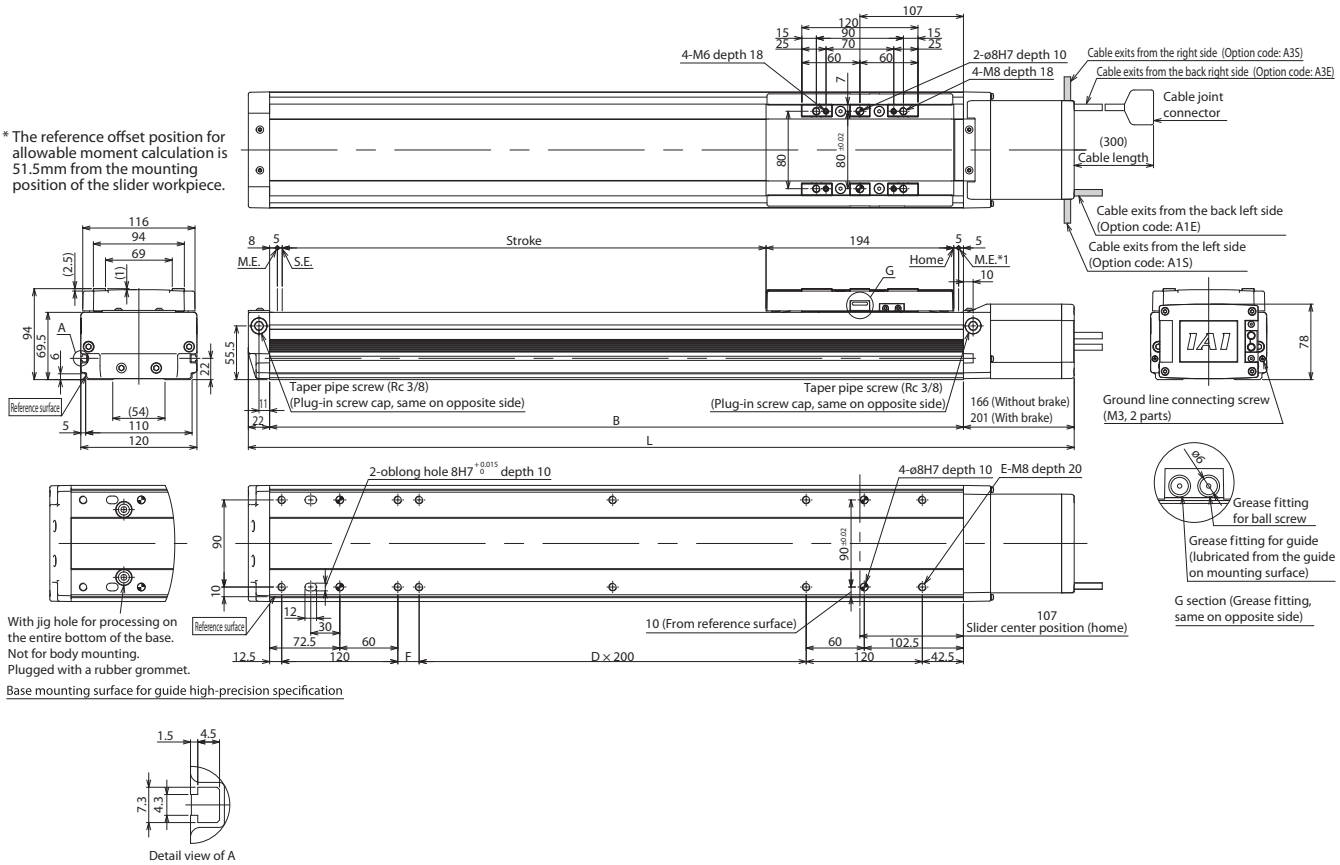
Please refer to the ISB/ISDB basic catalogue for more information regarding the directions of the allowable moment and overhang load length.

Dimensions

CAD drawings can be downloaded from our website.
www.intelligentactuator.de

*1 When the slider is returning to its home position, please be careful of interference from surrounding objects, as it will travel until it reaches the M.E.
M.E: Mechanical end
S.E: Stroke end

*2 If the home direction needs to be changed after purchase, the actuator must be returned to IAI for adjustment.



■ Dimensions and Mass by Stroke

Stroke		100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100
L	w/o brake	505	555	605	655	705	755	805	855	905	955	1005	1055	1105	1155	1205	1255	1305	1355	1405	1455	1505
	w/brake	540	590	640	690	740	790	840	890	940	990	1040	1090	1140	1190	1240	1290	1340	1390	1440	1490	1540
B		317	367	417	467	517	567	617	667	717	767	817	867	917	967	1017	1067	1117	1167	1217	1267	1317
D		0	0	0	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5
E		8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16	16	18
F		22	72	122	172	22	72	122	172	22	72	122	172	22	72	122	172	22	72	122	172	22
Mass (kg)	w/o brake	8.5	9.1	9.7	10.3	11.0	11.6	12.2	12.9	13.5	14.1	14.8	15.4	16.0	16.6	17.3	17.9	18.5	19.2	19.8	20.4	21.1
	w/brake	9.0	9.7	10.3	10.9	11.6	12.2	12.8	13.5	14.1	14.7	15.3	16.0	16.6	17.2	17.9	18.5	19.1	19.8	20.4	21.0	21.6

Applicable Controllers

The ISDB series actuators can be operated by the controllers indicated below. Please select the type depending on your intended use.

Type	External view	Max. number of controlled axes	Power supply voltage	Control method				Maximum number of positioning points	Ref. page
				Positioner	Pulse-train	Program	Network *Option		
SCON-CB/CGB		1	Single-phase 230VAC	●	●	–	DeviceNet, CC-Link, PROFIBUS, CompoNet, EtherCAT, EtherNet/IP, PROFINET	512 points (768 for network spec.)	Please contact IAI for more details
SCON-LC/LCG		1		–	–	●		512 points (768 for network spec.)	
SSEL-CS		2	Single-phase 115/230VAC	●	–	●		20000	
XSEL-P/Q		6	Single-phase 230VAC Three-phase 230VAC	–	–	●	Note: The type of compatible networks will vary depending on the controller. Please contact IAI for more details.	20000	

ISDB-MX-400

±10μm Standard | Battery-less Absolute | Simple Dust-proof | Medium type | Intermediate Support Type | Body Width 120 mm | 400 W

■ Model Specification Items

ISDB — MX — WA — 400 — 48 — □ — T2 — □ — □

Series	Type	Encoder Type	Motor Type	Lead	Stroke	Applicable Controllers	Cable Length	Options
		WA: Battery-less absolute	400 : 400W	48 : 48mm	800 : 800mm ~ 1600 : 1600mm (50mm increments)	T2 : SCON SSEL XSEL-P/Q	N : None S : 3m M : 5m X□□ : Specified Length	Please refer to the option table below

* Does not include a controller.
* Please contact IAI for more information about the model specification items.

* Be sure to specify the AQ seal (AQ) option. Be sure to select a symbol for the cable outlet direction.

CE RoHS

Horizontal | Vertical | Side | Ceiling

* Please contact IAI for more details on the installation method.

POINT Selection Notes

(Note 1) The value of payload is when operating at an acceleration of 0.4G. Please refer to P.21 for more information.

(Note 2) The value of straightness of straight line motion is when specifying the straightness high precision specifications (optional).

Model/Specifications

■ Lead and Payload

Model	Motor wattage (W)	Lead (mm)	Max. payload (*1) Horizontal (kg)	Max. payload (*1) Vertical (kg)	Rated thrust (N)	Stroke (mm)
ISDB-MX-WA-400-48-①-T2-②-③	400	48	20	–	141.3	800~1600 (Every 50mm)

Legend: ① Stroke ② Cable length ③ Option

(*1) Refer to P. 21 for the relationship of acceleration and payload.

■ Stroke and Max. Speed

Stroke	800	850	900	950	1000	1050	1100
Max. Speed	1700	1750	1800	1850	1900	1950	2000

Stroke	1150	1200	1250	1300	1350	1400	1450
Max. Speed	2050	2100	2150	2200	1990	1860	1745

Stroke	1500	1550	1600
Max. Speed	1640	1540	1450

(Unit: mm/s)

Cable Length

Type	Cable code	Standard	With LS
Standard type	**S** (3m)	○	
	M (5m)	○	
Specified length	**X06** (6m) ~**X10** (10m)	○	○
	X11 (11m) ~**X20** (20m)	○	○

* Only the robot cable is available for this model.
* Please contact IAI for more information regarding the maintenance cables.
* When using a cable of 21 to 30m, specify "N" for the cable length of the actuator model, and separately purchase the motor cable [CB-X(EU)-MA□□□], encoder cable [CB-X(EU)1-PA□□□-AWG24] or encoder cable with LS [CB-X(EU)1-PLA□□□-AWG24]. (Please contact IAI for more details on the cable.)

Options

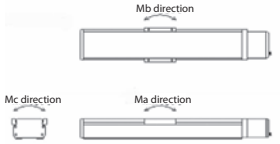
Type	Model	Ref. Page	Type	Model	Ref. Page
Cable exits from the left side	**A1S**	See P.19	Home limit switch symmetrically opposite	**LL**	See P.19
Cable exits from the back left side	**A1E**	See P.19	Master axis specified	**LM**	See P.19
Cable exits from the right side	**A3S**	See P.19	Master axis spec. (sensor symmetrically opposite)	**LLM**	See P.19
Cable exits from the back right side	**A3E**	See P.19	Non-motor end spec.	**NM**	See P.19
AQ seal (standard feature)	**AQ**	See P.19	Guide with ball retention mechanism	**RT**	See P.20
Brake	**B**	See P.19	Slave axis specified	**S**	See P.19
Creep sensor	**C**	See P.19	Straightness high precision specification	**ST**	See P.20
Creep sensor symmetrically opposite	**CL**	See P.19	-	**-**	-
Home limit switch	**L**	See P.19	Round cable joint connector with screw locking	**EU**	See P.19

Actuator Specifications

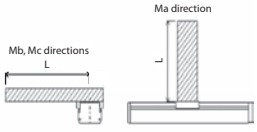
Item	Description
Positioning repeatability	±0.01mm
Drive system	Ball screw ϕ16mm, rolled C10
Lost motion	0.05mm or less
Static allowable moment	Ma: 341.5N·m Mb: 487.0N·m Mc: 796.5N·m
Dynamic allowable moment (*1)	Ma: 81.0N·m Mb: 116.0N·m Mc: 189.0N·m
Dyn. straightness of straight line motion (*2)	0.02mm/m or less
Base	Material: Aluminum with white alumite treatment
Protective structure	IP30
Ambient operating temp. & humidity	0~40°C, 85% RH or less (Non-condensing)

(*1) Assumes a standard rated life of 10000km. The service life will vary depending on operation and installation conditions. Please contact IAI for the running life.
(*2) The value is when the straightness high precision specification (option) is specified.

· Reference for overhang load length: Ma: 600mm or less, Mb, Mc: 600mm or less



Direction of the dynamic allowable moment



Direction of the allowable overhang load length

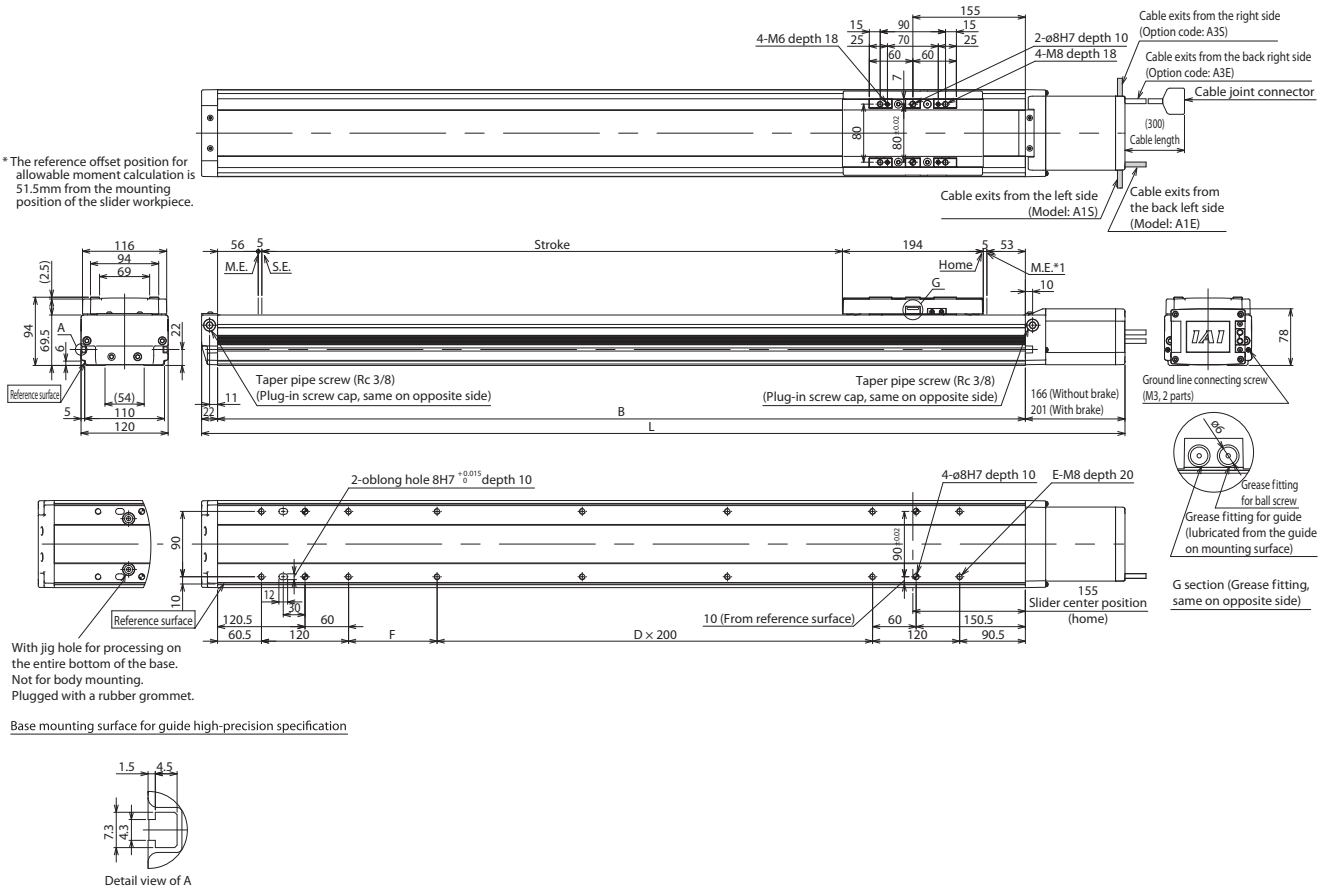
Please refer to the ISB/ISDB basic catalogue for more information regarding the directions of the allowable moment and overhang load length.

Dimensions

CAD drawings can be downloaded from our website.
www.intelligentactuator.de

*1 When the slider is returning to its home position, please be careful of interference from surrounding objects, as it will travel until it reaches the M.E.
M.E: Mechanical end
S.E: Stroke end

*2 If the home direction needs to be changed after purchase, the actuator must be returned to IAI for adjustment.



■ Dimensions and Mass by Stroke

Stroke		800	850	900	950	1000	1050	1100	1150	1200	1250	1300	1350	1400	1450	1500	1550	1600
L	w/o brake	1301	1351	1401	1451	1501	1551	1601	1651	1701	1751	1801	1851	1901	1951	2001	2051	2101
	w/brake	1336	1386	1436	1486	1536	1586	1636	1686	1736	1786	1836	1886	1936	1986	2036	2086	2136
B		1113	1163	1213	1263	1313	1363	1413	1463	1513	1563	1613	1663	1713	1763	1813	1863	1913
D		3	3	3	3	4	4	4	4	5	5	5	5	6	6	6	6	7
E		14	14	14	14	16	16	16	16	18	18	18	18	20	20	20	20	22
F		122	172	222	272	122	172	222	272	122	172	222	272	122	172	222	272	122
Mass (kg)	w/o brake	18.9	19.5	20.2	20.8	21.4	22.1	22.7	23.4	24.0	24.6	25.3	25.9	26.6	27.2	27.8	28.5	29.1
	w/brake	19.5	20.1	20.7	21.4	22.0	22.7	23.3	23.9	24.6	25.2	25.9	26.5	27.1	27.8	28.4	29.1	29.7

Applicable Controllers

The ISDB series actuators can be operated by the controllers indicated below. Please select the type depending on your intended use.

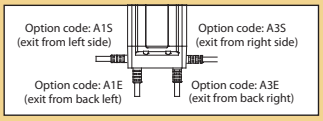
Type	External view	Max. number of controlled axes	Power supply voltage	Control method				Maximum number of positioning points	Ref. page
				Positioner	Pulse-train	Program	Network *Option		
SCON-CB/CGB		1	Single-phase 230VAC	●	●	–	DeviceNet, CC-Link, PROFIBUS, CompoNet, EtherCAT, EtherNet/IP, PROFINET	512 points (768 for network spec.)	Please contact IAI for more details
SCON-LC/LCG		1		–	–	●		512 points (768 for network spec.)	
SSEL-CS		2	Single-phase 115/230VAC	●	–	●		20000	
XSEL-P/Q		6	Single-phase 230VAC Three-phase 230VAC	–	–	●	Note: The type of compatible networks will vary depending on the controller. Please contact IAI for more details.	20000	

Options

Cable exit direction

Option code A1S/A1E/A3S/A3E

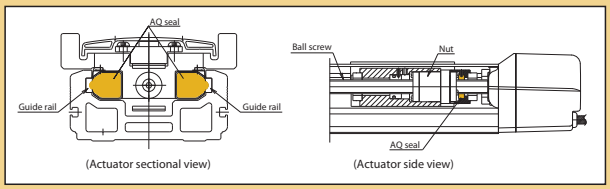
Description The extraction direction of the actuator cable can be selected from back left, left, back right and right.
* It is required to select an extraction direction.



AQ seal

Option code AQ

Description AQ seal is a lubricant unit that uses a lubricating member made of lubricating oil solidified with resin.
Because it is a porous member that contains a large amount of lubricating oil, the oil seeps out on the surface through capillary action. Lubricating oil is supplied by pressing the AQ seal on the surface of the guide and ball screw (steel ball rolling surface), enabling long-term use without maintenance in a synergistic effect by the combined use of the grease.



Brake

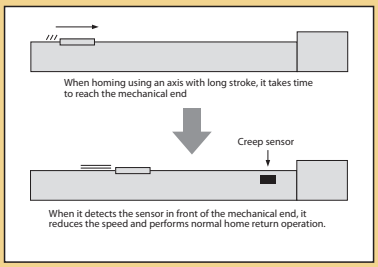
Option code B

Description This is a holding mechanism that prevents the slider from falling and damaging any attached fittings when the power or servo is turned off.

Creep sensor

Option code C (Standard) CL (Mounted on opposite side)

Description A sensor for performing homing at high speed.
As homing is normally done by pressing the slider against the stopper on the motor side stroke end and reversing, the homing speed is kept to 10~20mm/s.
Therefore, units with long stroke take time until homing is completed. In order to shorten this, this proximity sensor is used to return the slider at high speed halfway through then drop the speed to normal homing return speed just before the home.
The mounting position of the sensor is by default at the right side of the actuator body as viewed from the motor side (Option code: C).
It comes with the same cover on the outside of the sensor as the limit switch.
When installing a sensor on the opposite side, be sure to select CL (mounting position on opposite side).



Round cable joint connector with screw locking

Option code EU

Description Option for a motor/encoder cable with round cable plugs with screw locking. Without this option flat plugs are default.

Home limit switch

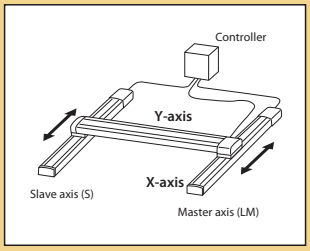
Option code L (Standard) LL (Mounted on opposite side)

Description When performing home-return, the pressing method determines the home position upon pressing against the mechanical end and reversing. This is an option for triggering the reversion using the sensor.
When L option is specified, 3 proximity sensors including HOME (for home detection), +OT (overtravel on opposite motor side) and -OT (overtravel on the motor side) will be installed. (HOME and -OT are integrated twin sensors)
Use it to fine-tune the inverted position or enhance the certitude.
(Please note that moving the home sensor excessively may shorten the stroke)
The home limit switch and mounting position of the cover is by default at the right side of the actuator body as viewed from the motor side (Option code: L).
When installing a sensor on the opposite side, be sure to select LL (mounting position on opposite side).

Master axis specification/Slave axis specification in synchronous operation

Option code LM (Limit master axis specification) LLM (Mounted on opposite side) S (Slave axis specified)

Description One of the features of the XSEL controller is "synchronous operation".
This feature is used to operate the two axes of actuators at the same time. With one axis used as the master (M) and another as the slave (S), the slave follows the master in ultra-high-speed control in order to operate at the same time.
Two axes of actuators that run synchronously need to have the same specifications (type, lead, motor wattage and stroke).
When performing synchronous operation, the master axis needs to have the limit switch specification. Be sure to specify LM (limit specification master axis) for the option code of master axis and S for slave axis. The mounting position of the limit switch and cover is standardly at the right side of the actuator body as viewed from the motor side. When installing the limit switch of the master axis on the opposite side (symmetrically opposite), be sure to select LLM.



Non-motor end specification

Option code NM

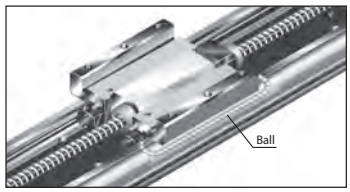
Description The normal home position is set to the motor side, but this is the option to set the home position on the other side in order to accommodate variations in equipment layout, etc. (Please note that changing the home position after the actuators are shipped may require the products to be sent back to IAI for re-setting.)

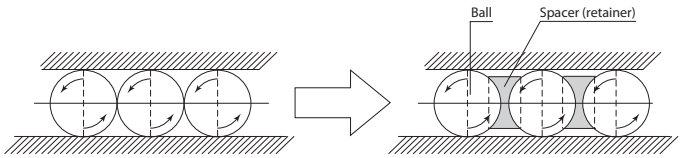
Guide with ball retention mechanism

Option code RT

Description A spacer (retainer) is placed between steel balls of the guide to achieve low noise and long life.
It eliminates metallic noise due to balls colliding with each other, reducing harsh noise.
It reduces wear caused by friction of balls, extending the life of the guide.
It eliminates the interference between balls and smoothens the movement, improving the operability of the slider.

* It cannot be used with ISB-SXL/MXL
* When using ISB/ISDB guide with ball retention mechanism in vertical orientation, the vertical payload may differ for some models. Please refer to the pages of each type for details.





Slider section roller specification

Option code SR

Description Changes the slider structure of the standard slider type to the same roller structure of the cleanroom specification.
Changing to roller specification will make the external view and dimensions of the slider cover the same as the cleanroom specification.

Straightness high-precision specification

Option code ST

Description A precision actuator that defines the running accuracy of slider parallelism of motion (horizontal/vertical) and straightness of straight line motion (horizontal/vertical) at a high level.
Respective running accuracy is defined for each stroke of the actuator. The table below shows standard values per 1m.
For the method of calculating the standard value for each stroke, please refer to the calculation example.

		Aluminum base	
		Without straightness high-precision specification	With straightness high-precision specification (*)
1	Parallelism of motion [mm/m or less]	0.05 [Stroke of 500mm or less is uniformly 0.025mm]	0.03 [Stroke of 500mm or less is uniformly 0.015mm]
2	Straightness of straight line motion [mm/m or less]	0.05 [Stroke of 500mm or less is uniformly 0.025mm]	0.020 [Stroke of 500mm or less is uniformly 0.01mm]

(*) The precision measurement method depends on the IAI inspection criteria.

Calculation example (with straightness high-precision specification)

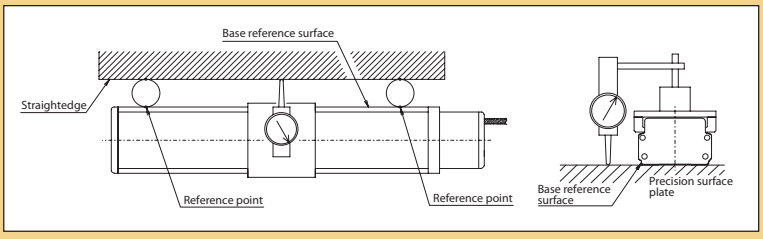
① **Aluminum base ISB/ISDB Series**

Example: For 1500mm stroke
Parallelism of motion → 0.03mm (standard value per 1m) x 1.5m (stroke) = 0.045mm
Straightness of straight line motion → 0.02mm (standard value per 1m) x 1.5m (stroke) = 0.03mm
* Rounded up to four decimal places

1 Parallelism of motion (Horizontal/Vertical)

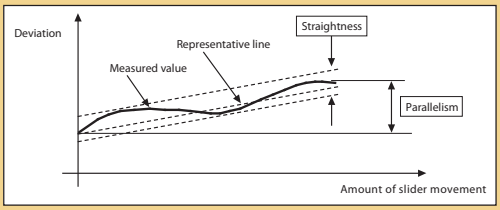
①Parallelism of base reference surface and slider movement (Horizontal)
It represents the maximum difference between measured values when moving the entire stroke with the indicator on the slider placed on the straightedge placed in parallel with both ends of the base reference surface while fixing the base on the precision surface plate.

②Parallelism of base mounting surface and slider movement (Vertical)
It represents the maximum difference between measured values when moving the entire stroke with the indicator on the slider placed on the surface plate while fixing the base on the precision surface plate.



2 Straightness of straight line motion (Horizontal/Vertical)

It represents the amount of deviation from the representative line in slider movement measured using a straightedge or autocollimator while the base is fixed to the precision surface plate.



Double slider specification

Option code W

Description This option has an additional free slider that is not connected to a ball screw or drive belt.
By doubling the slider, the moment and overhang load length can be increased.
* It cannot be used with the intermediate support (MXMX/MX). Please refer to P.22 for more information regarding the directions of the allowable moment and overhang load length when using the double slider.

■Tables of Payload by Acceleration

: Standard specification : Off-board tuning specifications

Series	Type	Motor Number of W	Lead	Max. Speed	Installation	Tables of Payload per Acceleration/Deceleration (kg)																										
						0.4	0.5	0.6	0.7	0.8	0.9	1.0	1.1	1.2	1.3	1.4	1.5	1.6	1.7	1.8	1.9	2.0	2.1	2.2	2.3	2.4	2.5	2.6	2.7	2.8	2.9	3.0
ISB	SXM/SXL	100	36	2160	Horizontal	10.0	9.0	8.2	7.5	6.7	6.0	5.5	5.0	4.5	4.3	4.1	4.0	3.9	3.8	3.7	3.6	3.5	3.2	2.9	2.6	2.3	2.0	1.9	1.8	1.7	1.6	1.5
					Vertical	2	2	2	2	2	2	2	2	2	2	2	2	2														
	MXM/MXL	400	48	2500	Horizontal	20.0	19.1	18.2	17.3	16.4	15.5	14.6	13.8	13.0	12.6	12.2	11.8	11.4	11.0	10.8	10.4	10.0	9.4	8.8	8.2	7.6	7.0	6.6	6.2	5.8	5.4	5.0
					Vertical	6	6	6	6	6	6	6	6	6	6	6	6	6														
	MXMX			2200	Horizontal	20.0																										
					Vertical	—																										
ISDB	S	100	36	2000	Horizontal	10.0	9.0	8.1	7.2	6.3	5.4	4.5	4.3	4.1	4.0	3.9	3.8	3.7	3.6	3.5	3.2	2.9	2.6	2.4	2.2	2.0	1.9	1.8	1.7	1.6	1.5	1.4
					Vertical	2	2	2	2	2	2	2	2	2	2	2	2	2														
	M	400	48	2200	Horizontal	20.0	18.8	17.6	16.4	15.2	14.0	13.0	12.6	12.2	11.8	11.4	11.0	10.6	10.3	10.0	9.5	9.0	8.5	8.0	7.5	7.0	6.6	6.2	5.9	5.6	5.3	5.0
					Vertical	6	6	6	6	6	6	6	6	6	6	6	6	6														
	MX			2200	Horizontal	20.0																										
					Vertical	—																										

(Note) When using ISB-SXM and ISDB-S guide with ball retention mechanism (RT), the vertical payload will be -0.5kg.

■ Off-board Tuning

Improves the carrying capacity of the actuator

Off-board tuning is a function that improves the carrying capacity and shortens the tact time by automatically setting the optimal gain according to the transport load and improving the payload and acceleration/deceleration.

PC Compatible Software
ver.11.00.02.00 or later

Off-board tuning allows you to obtain the following three effects.

(1) It can transport over the rated payload by setting the acceleration/deceleration low.
(2) If the transport weight is smaller than the rated payload, the acceleration/deceleration can be improved.
(3) The max. speed can be improved.

Off-board tuning is enabled when combined with the SCON-CB/MSCON controller.
Please see the PC software manual or contact IAI for more details.

■ Directions of the Allowable Moment and Overhang Load Length When Using the Double Slider

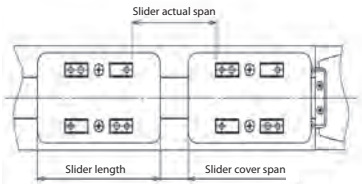
Please check the following specification table and notes when selecting the double slider.

Series name	Model	Dynamic allowable moment						Overhang load length (mm)	Slider mass to be added (kg)	Slider length (mm)	Minimum stroke for double slider (mm)	Minimum nominal stroke (mm) *	Maximum. nominal stroke (mm) *
		Standard rated life (km)	Slider actual span (mm)	Slider cover span (mm)	Ma direction (N·m)	Mb direction (N·m)	Mc direction (N·m)	Ma direction Mb/Mc direction					
ISB	SXM	10000	Min.: 30	–	140	200	125	1015	1.5	90	100	250	1100
			Max.: 90	–	228	325	125	1350					
	SXL		Min.: 30	–	188	269	145	1250		110	130	280	1080
			Max.: 90	–	286	409	145	1550					
	MXM		Min.: 35	–	332	475	307	1375	2.5	120	100	300	1300
			Max.: 120	–	561	801	307	1800					
	MXL		Min.: 35	–	481	687	368	1675		150	120	320	1270
			Max.: 120	–	743	1060	368	2100					
ISDB	S	10000	110	46	259	370	125	1050	1.5	154	100	300	1100
	M		Min.: 80	6	448	640	307	1375	2.5	194	100	300	1300
			Max.: 120	46	561	801	307	1800					

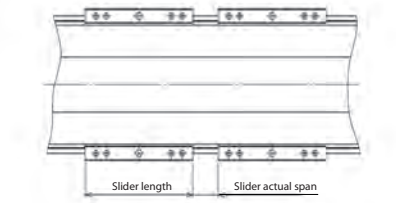
* Min. stroke/max. stroke indicated on the model.

Double slider view

● With slider cover (ISDB Series)



● Without slider cover (ISB Series)



■ Notes in Using Double Slider

(1) Required stroke length
If the double slider option is specified, the actual operable stroke is the value where slider length + slider actual span (slider cover span) is subtracted from the stroke of the model. Be sure to select the stroke where the length in the table above is added to the required stroke. Also, make sure that the required stroke is higher than the "minimum stroke for double slider".
The selectable stroke is higher than the "minimum nominal stroke" and under the "maximum nominal stroke" in 50mm increments.

NO.	Actuator shape	Stroke length to be prepared
①	Models with slider cover	Greater than or equal to the length of "required stroke" + "slider cover span" + "slider length"
②	Models without slider cover	Greater than or equal to the length of "required stroke" + "slider actual span" + "slider length"

Example ① ISDB-S (With slider cover)
Required stroke: 200mm, slider cover span: 46mm, slider length: 154mm
Set to 200mm + 46mm + 154mm = 400mm or more

Example ② ISB-SXM (Without slider cover)
Required stroke: 200mm, slider actual span: 30mm, slider length: 90mm
Set to 200mm + 30mm + 90mm = 320mm or more

(2) Payload
The value where "added slider weight" is subtracted from the catalog specification value is the max. value.

(3) Max. Speed
Please refer to the specification values of the nominal stroke.

(4) When non-motor end specification is selected
Be sure to perform home-return operation upon connecting the drive slider and free slider.

ISB/ISDB Series
High-speed Type
Catalogue No. 0117-E

The information contained in this catalog is subject to change without notice for the purpose of product inprovement

INTELLIGENT ACTUATOR

IAI
Quality and Innovation

IAI Industrieroboter GmbH
Ober der Röth 4
D-65824 Schwalbach / Frankfurt
Germany
Tel.:+49-6196-8895-0
Fax:+49-6196-8895-24
E-Mail: info@IAI-GmbH.de
Internet: http://www.eu.IAI-GmbH.de

IAI America, Inc.
2690 W. 237th Street, Torrance, CA 90505, U.S.A
Phone: +1-310-891-6015, Fax: +1-310-891-0815

IAI (Shanghai) Co., Ltd
Shanghai Jiahua Business Center A8-303, 808,
Hongqiao Rd., Shanghai 200030, China
Phone: +86-21-6448-4753, Fax: +86-21-6448-3992

IAI CORPORATION
577-1 Obane, Shimizu-Ku, Shizuoka, 424-0103 Japan
Phone: +81-543-64-5105, Fax: +81-543-64-5192

IAI Robot (Thailand) Co., Ltd
825 PhairojKijja Tower 12th Floor, Bangna-Trad RD.,
Bangna, Bangna, Bangkok 10260, Thailand
Phone: +66-2-361-4457, Fax: +66-2-361-4456