### **SD6 Drive Controller**



Maximum dynamics and precision for CODESYS controlled axes





### Ready for anything with 32-bit Dual-Core processor



# Precise precision control of servo axes with EnDat<sup>®</sup> 2.2 encoders

With the speed feedback via EnDat<sup>®</sup> 2.2 encoders, 33 million positions per revolution can be determined.

The 32-bit Dual-Core processor on the SD6 drive controller processes the encoder data with maximum accuracy and speed. With its high computing capacity, the SD6 drive controller can also be used with future encoder systems with higher resolution.

A 32-bit format is available for the reference value/actual value interface. So positions can be represented with high precision and a large position range.

### SPEED | FLEXIBILITY | DESIGN

### **Specially for motion control solutions**

### The 32-bit Dual-Core control performance gives a new dimension to motion precision and smoothness

Position, speed and torque control of the servo axes are calculated at a cycle time of  $62.5 \ \mu$ s (16 kHz).

This allows extremely high dynamics and precision of the drives due to very short settling times for fast reference values and load changes.

The new SD6 drive controller offers the possibility of a significant and impressive increase in precision and productivity in automation engineering and tooling machines despite the ever-increasing complexity of the functions.

With the high performance SD6 drive controller, the constant customer demands for faster cycle times and an increase in output can be convincingly and reliably met.

# The new STOBER 6<sup>th</sup> generation device

The completely redesigned STOBER 6<sup>th</sup> generation device starts with the SD6 drive controller and MC6 motion controller.

Based on a combination of the two devices, the drive controller is operated in Controller Based Mode (CBM).

### EtherCAT<sup>®</sup> and CANopen<sup>®</sup> device communication

The STOBER CBM application is based on the internationally standardized device profile CiA 402 for electric drives and motion control.

The SD6 drive is controlled by the CiA 402 compliant control words, status words, reference values and actual values.



6<sup>th</sup> generation device

### The SD6 drive controller operating modes

 Interpolated position mode (CANopen<sup>®</sup>)

Cyclic position input by the motion controller – the drive follows in position control

- Cyclic synchronous position mode (EtherCAT<sup>®</sup>)
   Cyclic position input by the motion controller – the drive follows in position control
- Cyclic synchronous velocity mode (EtherCAT<sup>®</sup>)
   Cyclic speed input by the motion controller – the drive follows in speed control
- Cyclic synchronous torque mode (EtherCAT<sup>®</sup>)
   Cyclic torque input by the motion controller – the drive follows in torque control
- Type/STOBER specific mode
  Control-independent travel
  of the drive e.g. for set up
  functions and emergency mode

Homing mode Control-independent referencing by the drive – the drive calculates the necessary travel profiles independently

### For drive axes from 0.37 to 50 kW



SD6 Size 3 for motors up to 50 kW

### New look design

The dark front glazing with the multiline text and graphic display, operation by control pad and the striking Softline housing are features of the quality design of the new SD6 series.

### **EMC protection**

The sheet steel housing design is part of the STOBER EMC strategy to shield against electromagnetic interference. This construction increases RFI immunity and reduces emitted interference.

#### **Cabinet installation**

With a housing depth of 194 mm respectively 284 mm, sizes 0, 1 and 2 are also suitable for installation in compact cabinets 300 mm deep.



G6 power board

### Modular flexibility and options

The SD6 drive controller stands out for its proven board architecture and its universal options.

So every single system axis in the configuration can have the best design.

A control for a 24V holding brake is integrated (<= 2.5 A)

A non-wearing, fully electronic interface is provided as standard for the *Safe Torque Off* (STO) safety function (response time < 10 ms).



Safety board connector (developed jointly with Pilz GmbH & Co. KG)



The connections for motor, DC link, braking resistor and holding brake are located on the underside of the device



A technically innovative solution

allows the STO safety function to

work without interruptive system tests and their documentation. In

practice this means impressively

On multiaxis applications with SD6

drive controllers, it is possible sim-

ply to loop through the STO safety

Functional safety data are provided

for standard market calculation tools

The safety relevant functions were

developed jointly with Pilz GmbH &

for system safety (e.g. Sistema,

increased availability.

function.

Pascal).

Co. KG.

The quick mains or 24V connection is made from above through plug-in terminal strips



SD6 size 0 – housing cover removed to show terminal boards Terminal board X16 (left), terminal board IO6 and RI6 in preparation



EtherCAT<sup>®</sup> connection for motion control operation



Paramodul with micro SD card for storage of all device data

### **Designed for multiaxis operation**



Drive controller in multiaxis operation, controlled by the STOBER MC6 motion controller via EtherCAT $^{\circ}$ 

### High performance – for complex motion profiles of the drive axes

In multiaxis operation every geared motor has its task and conditions. Multiaxis applications with high dynamics can only be achieved if the drive controllers are capable of guaranteeing precision and timing in all circumstances.

The high performance SD6 drive controller is ideal for these applications.



... perfectly coordinated with synchronous servo motors from STOBER

With this extensive hardware range, virtually all requirements in machine manufacture and automation can be met.

A selection of the servo drive product range from STOBER

### Options for energy use of a DC link connection

All the SD6 drive controller series have a DC link connection facility.

With this technology the regenerative energy from one servo drive can be absorbed and used by another motoring servo drive on the same DC link line.

Regenerative energy occurs when a load drives the motor and energy is returned to the drive controller.

If operating conditions change frequently or regularly from motoring to regenerative mode, it can make sense to feed the surplus energy generated to one or more drive controllers or servo drives. This is done through the DC link connection referred to.



with concealed busbar for DC link connection, with an added brake resistor

Safe and reliable through motion control

### **Quick DC Link**

The Quick DC Link rear-mounted module was developed to offer a secure and efficient bus connection for a common DC link configuration. The contact between the SD6 drive controllers is made by standard busbars (5 x 12). They are installed without tools by quick-fix clamps. The Quick DC Link modules come with an integral fuse.

Typical uses can be found in winding For optimized use of the 'self-gentechnology, storage and retrieval units, conveyor and handling systems and installations with vertical axes.

A common DC link configuration can also be a consideration if several drives with braking resistors are used or planned in an installation.

erated' energy, it is necessary to coordinate the drive sequences and motion profiles and control them via the MC6 motion controller.

### DriveControlSuite

The DriveControlSuite commissioning software version 6 has all the functions for efficient use of drive controllers in multiaxis applications.

Commissioning is made easy, for example by a multiaxis oscilloscope.

### Integrated bus (IGB)

The IGB network makes real time control of a variety of communication and diagnosis concepts between several drive controllers and interfaces possible.

This interface is ideal for direct connection between PC and drive controller.

# CODESYS – the software for multiaxis operation

CODESYS – from 3S-Smart Software Solutions – is a hardware independent programming software or a complete programming system for the international standard PLC languages according to IEC 61131-3.

The centralization of all the axis parameters in one program operation makes it easier to program complex multiaxis applications. Examples of these are path travel, CNC and robotic functions.

Due to its wide popularity, this software tool represents the market standard for hardware independent development systems. Many users, particularly in the automation industry, are perfectly familiar with CODESYS.

The new MC6 motion controller from STOBER (see separate brochure) is already equipped with the new CODESYS V3 version.

### Complete solutions in combination with the MC6 motion controller from STOBER

With the development of the new MC6 motion controller and its integration in the STOBER product portfolio, slim, user friendly engineering solutions can be offered for drive engineering systems from a single source.

Using the MC6 motion controller in combination with SD6 drive controllers makes programming easier in many cases. This also applies to complex functions with high timing and precision specifications.

Added to this is STOBER's experience in optimum design of each individual axis.

Commissioning and program maintenance are carried out centrally on the motion controller.

# Application support and tailor-made services

STOBER offers you support and services specially matched to your requirements.

You can also make use of the STOBER technology support for troubleshooting or optimization of an existing system.

With the design and programming of a *Tailor Made Application* by STOBER, you are given uncompromising, optimized solutions as a complete package ready to run.

Integrated bus interface



### **Commissioning & parameterization**

# User seminars for CODESYS and DriveControlSuite

STOBER offers a multistage program of seminars which focuses mainly on application programming of the MC6 motion controller and SD6 drive controller.

The courses take place at the STOBER seminar centre but can also be held locally for specific projects.

After attending the basic and advanced courses, you will be able to utilise the potential of the MC6 motion controller to the full and carry out commissioning efficiently.

Further information can be found in the MC6 Motion Controller brochure and on the website www.stober.com (Services).



Additional fine-tuning of parameter settings directly on the SD6 drive controller

# Flexible handling as required

For system configuration and parameterization the SD6 drive controller can be addressed directly via the DriveControlSuite device software.

And finally, the display in combination with the control pad, allows for fine-tuning of settings directly on the device.



Central commissioning of a CODESYS multiaxis application

### **Customer benefits and facts**

### High performance equipment for challenging applications

- Dual-Core RISC processor (200 MHz) with floating point unit 32-bit current, speed and position controllers 62.5 µs
- Power stage for 250 % accelerating current
- Thermistor motor protection by PTC or KTY
- Control system with maximum EnDat<sup>®</sup> 2.2 encoder resolution (25 bits per turn)

### Easy to use

#### clear added value for total cost considerations

- Ethernet-based interface For programming and parameterization – and for the IGB network for communication with multiaxis systems and remote maintenance via the internet.
- Paramodul plug-in memory module

With integrated microSD card (suitable for industrial use). Ideal medium for storage of additional project data and documentation. Can be used for direct processing on the PC.

All terminals are the spring

tions are in separate places.

Easily accessible EMC plate for simple shield connection of the

Supply and motor cable connec-

loaded plug-in type.

Easy to install

motor cable.

Illuminated keypad and graphics compatible display (128 x 64 characters). **Reference value input** in user units

Display and keypad with new

one touch save button

- Guarantees easy and transparent use.
- Live firmware update
- Windows software DriveControlSuite

### Adaptable to many different drive tasks

- Flexible control mode Adaptable to the operation of synchronous servo motors and to asynchronous motors in the operating modes (V/f, sensorless VC, VC).
- Encoder interfaces
  - Absolute encoders EnDat<sup>®</sup> 2.1 or 2.2 with electronic name plate and SSI
  - Incremental encoders (HTL, TTL)
  - Resolvers

#### Fieldbus modules

- EtherCAT<sup>®</sup> (EC6)
- CANopen<sup>®</sup> (CA6)
- PROFIBUS/PROFINET (under preparation)
- I/O terminal modules Terminal board XI6 (IO6 and RI6 in preparation)
- **Braking resistors**

UL compliant, available as submounted modules or for separate cabinet installation.

- Ratings from 40 W to 8000 W
- Enclosure up to IP54





#### Dimensions









Size 1 + 2



# Safety integrated (ST6)

#### • Competence

Cooperation with PILZ GmbH & Co. KG, the industry leader in safety engineering.

STO

Non-wearing electronic safety function.

The STO safety function ensures that no torque-generating energy is supplied to the motor and the drive is reliably torquefree.

This function forms the basis for many other safety functions.

Response time < 10 ms</li>

TÜV certified in accordance with:

SIL3 (HF1)
 According to EN 61800-5-2

PLe (cat. 4)
 According to EN ISO 13849

PLe (cat. 4) Allows use of the SD6 drive controller in challenging safetyrelated applications

### D link connection with Quick DC Link

### More energy efficient

If the potential exists for reciprocal use of braking energy, the energy efficiency can be increased by a D link coupling.

- Simple D link connection with Quick DC Link.
- Can reduce energy consumption in multiaxis applications.
- No additional control cabinet space required due to the rear-mounted module design
- All the SD6 drive controller sizes can be interconnected via the Quick DC Link.
- Every Quick DC Link module is separately fused.

### Conformity

### **CE compliant**

All SD6 drive controllers comply with the EMC Directives and meet the criteria of the Low Voltage Directives. The units come with an effective system package as standard – including an integrated EMC filter and the high end galvanized sheet steel housing. Levels and terms are defined to IEC 1131. All SD6 drive controllers have the CE mark.

#### UL compliant

The UL and cUL ("Canada UL") listed SD6 drive controllers meet the requirements of standards UL 508C and UL 840.

#### Technical data

B    Type    Recommended motor power    Input voltage    Input voltage    Rated current IN    Maximum current Imax    Switching frequency    Overvoltage limit    Braking resistor RBr min    Braking resistor PBr max      0    SD6 A02    0.75 kW    (L1-N) 1 x 230 V + 20 %/-40 %, 50/60 Hz    3.0 A    7.5 A    8 kHz    440 V    100 0hm    1.8 kW      506 A04    0.75 kW    (L1-L3) 3 x 400 V, +32 %/-50 %, 50 Hz (L1-L3) 3 x 480 V, +10 %/-58 %, 60 Hz    1.7 A    4.2 A    8 kHz    830 V    100 0hm    6.4 kW      3.0 A    3.6 A    15.0 A    8 kHz    830 V    100 0hm    6.4 kW      1    SD6 A14    4.00 kW    (L1-L3) 3 x 400 V, +32 %/-50 %, 50 Hz (L1-L3) 3 x 400 V, +32 %/-50 %, 50 Hz (L1-L3) 3 x 400 V, +32 %/-50 %, 50 Hz (L1-L3) 3 x 400 V, +32 %/-50 %, 50 Hz (L1-L3) 3 x 400 V, +32 %/-50 %, 50 Hz (L1-L3) 3 x 400 V, +32 %/-50 %, 50 Hz (L1-L3) 3 x 400 V, +32 %/-50 %, 50 Hz (L1-L3) 3 x 400 V, +10 %/-58 %, 60 Hz    6.0 A    15.0 A    8 kHz    830 V    47 0hm    6.4 kW      10.0 A    25.0 A    10.0 A    25.0 A    10.0 A    13.6 kW								
SD6 A04    0.75 kW    (L1-L3) 3 x 400 V, +32 %/-50 %, 50 Hz (L1-L3) 3 x 480 V, +10 %/-58 %, 60 Hz    1.7 A    4.2 A    8 kHz    830 V    100 0hm    6.4 kW      SD6 A06    1.50 kW    (L1-L3) 3 x 480 V, +10 %/-58 %, 60 Hz    1.7 A    4.2 A    8 kHz    830 V    100 0hm    6.4 kW      1    SD6 A14    4.00 kW    (L1-L3) 3 x 480 V, +32 %/-50 %, 50 Hz (L1-L3) 3 x 480 V, +10 %/-58 %, 60 Hz    6.0 A    15.0 A    8 kHz    830 V    47 0hm    6.4 kW	Size	frequency limit resistor	rrent current	current			Туре	Size
SD6 A06      1.50 kW      (L1-L3) 3 x 480 V, +10 %/-58 %, 60 Hz      3.4 A      8.5 A        1      SD6 A14      4.00 kW      (L1-L3) 3 x 400 V, +32 %/-50 %, 50 Hz      6.0 A      15.0 A      8 kHz      830 V      47 0 hm      6.4 kW	0	8 kHz 440 V 100 0hm	3.0 A 7.5 A	3.0 A	(L1-N) 1 x 230 V + 20 %/- 40 %, 50/60 Hz	0.75 kW	SD6 A02	0
SD6 A06      1.50 kW      1.50 kW      3.4 A      8.5 A        1      SD6 A14      4.00 kW      (L1-L3) 3 x 400 V, +32 %/-50 %, 50 Hz (L1-L3) 3 x 480 V, +10 %/-58 %, 60 Hz      6.0 A      15.0 A      8 kHz      830 V      47 0 hm      6.4 kW		8 kHz 830 V 100 Ohm	1.7 A 4.2 A	1.7 A		0.75 kW	SD6 A04	
(L1-L3) 3 x 480 V, +10 %/-58 %, 60 Hz			3.4 A 8.5 A	3.4 A		1.50 kW	SD6 A06	
SD6 A16      7.50 kW      (L1-L3) 3 x 480 V, +10 %/-58 %, 60 Hz      10.0 A      25.0 A      13.6 kW	1	8 kHz 830 V 47 Ohm	6.0 A 15.0 A	6.0 A		4.00 kW	SD6 A14	1
			10.0 A 25.0 A	10.0 A	(L1-L3) 3 x 480 V, +10 %/-58 %, 60 Hz	7.50 kW	SD6 A16	
2 SD6 A24 11.00 kW (L1-L3) 3 x 400 V, + 32 %/-50 %, 50 Hz 14.0 A 35.0 A 8 kHz 830 V 22 0 hm 29.1 kW	2	8 kHz 830 V 22 0hm	14.0 A 35.0 A	14.0 A		11.00 kW	SD6 A24	2
SD6 A26      15.00 kW      (L1-L3) 3 x 480 V, +10 %/-58 %, 60 Hz      20.0 A      50.0 A			20.0 A 50.0 A	20.0 A	(LT-L3) 3 X 480 V, + 10 %/- 58 %, 60 HZ	15.00 kW	SD6 A26	
3      SD6 A34      22.00 kW      (L1-L3) 3 x 400 V, +32 %/-50 %, 50 Hz      30.0 A      75.0 A      8 kHz      830 V      15 0 hm      42.0 kW	3	8 kHz 830 V 15 0hm	30.0 A 75.0 A	30.0 A		22.00 kW	SD6 A34	3
SD6 A36      37.00 kW      (L1-L3) 3 x 480 V, +10 %/-58 %, 60 Hz      50.0 A      125.0 A			50.0 A 125.0 A	50.0 A	(LT-L3) 3 X 480 V, +10 %/-58 %, 60 Hz	37.00 kW	SD6 A36	
<b>SD6 A38</b> 50.00 kW 72.0 A 160.0 A			72.0 A 160.0 A	72.0 A		50.00 kW	SD6 A38	

### www.stober.com



### STOBER offers consistent solutions

As a system supplier STOBER has a complete product range for digital drive technology. The MC6 motion controller uses the CODESYS programming software to keep up with the trend towards open systems in the world of automation.

In combination with digital servo axes, STOBER solutions can be used for small or more extensive drive applications.

## Note on the design of axes and drives

For optimum axis design, it makes sense to focus primarily on the gear units or geared motors. A useful aid is the design software SERVOsoft<sup>®</sup>.

For an overall approach, use the specific expertise of the STOBER application consultants.

Contact and advice: applications@stoeber.de

### Service

The STOBER service system comprises 38 expert partners in Germany and more than 80 companies in the STOBER SERVICE NETWORK worldwide.

This service concept guarantees local expertise and availability when needed. In general, the service specialists can be reached at any time via a 24/7 service hotline.

When necessary, a problem can be addressed immediately.

24/7 service hotline +49 180 5 786323

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