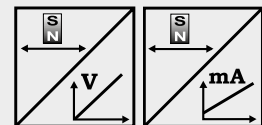




**POSICHRON® position sensor in a stainless steel pressure tube**

- Protection class IP67/69K, IP68
- Underwater applications, permanent pressure-proof up to 15 bar
- Measurement range 0 ... 100 to 0 ... 5750 mm
- Absolute position measurement
- Contact-free
- Seawater-proof
- Analog output



Specifications	Output	Voltage Current
	Resolution	Refer to output specification
Sampling rate	Up to 1 kHz, depending on the measurement range	
Linearity	Ranges >500 mm: L10 = ±0.10 % f.s. L02 = ±0.02 % f.s. Ranges ≤500 mm: L10 = ±0.5 mm L02MM = ±0.2 mm	
Repeatability	±3 µm	
Housing material	Stainless steel 1.4404	
Protection class	IP68 (permanent pressure-proof up to 15 bar), IP67/69K	
Shock	EN 60068-2-27:1993, 50 g 11 ms, 100 shocks	
Vibration	EN 60068-2-6:1995, 20 g 10 Hz-2 kHz, 10 cycles	
Connection	Cable 2 m	
EMC, temperature	Refer to output specification	

Order code position magnet (see page 5)

**PCMAG5**

**Order Code PCRP32**

1 or 2 channel,  
configurable

PCRP32 - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

**Model name**

**Measurement range (in mm)**

100 ... 5750 in 10 mm increments

**Output**

U2 = 0.5 ... 10 V signal conditioner

U2/U, U2/H = U2 with AlarmLOW, U2 with AlarmHOLD (see page 77)

U8 = 0.5 ... 4.5 V signal conditioner

I1 = 4 ... 20 mA signal conditioner (3 wire)

I1/U, I1/H = I1 with AlarmLOW, I1 with AlarmHOLD (see page 77)

**Function and characteristics output 1**

P1A = Position magnet 1, increasing

P1D = Position magnet 1, decreasing

PMU = Start value, direction & end value adjustable by the customer (1 channel only)

DA = Difference magnet 1/2, increasing (2 magnets required)

DD = Difference magnet 1/2, decreasing (2 magnets required)

**Function and characteristics output 2 (option)**

P2A = Position magnet 2, increasing

P2D = Position magnet 2, decreasing

DA = Difference magnet 1/2, increasing

DD = Difference magnet 1/2, decreasing

} 2 magnets required

VZx.x = Velocity with direction detection (with 1 magnet only)

VZx.x = Velocity in steps of 0.1 m/s

Example: VZ1.5 towards start position towards end position

	-1.5 m/s	0	+1.5 m/s
--	----------	---	----------

Output U2:	0.5 V	5.25 V	10 V
------------	-------	--------	------

Output I1:	4 mA	12 mA	20 mA
------------	------	-------	-------

VAx.x = Velocity without direction detection (with 1 magnet only)

VAx.x = Velocity in steps of 0.1 m/s

Example: VA1.5 towards start position towards end position

	-1.5 m/s	0	+1.5 m/s
--	----------	---	----------

Output U2:	10 V	0.5 V	10 V
------------	------	-------	------

Output I1:	20 mA	4 mA	20 mA
------------	-------	------	-------

**Linearity**

L02 / L02MM / L10 (for definition see "Specifications" above)

**Connection**

KAB2M = Cable, standard length 2 m, other lengths upon request

**1. Order example: PCRP32 - 1000 - U2 - P1D - L02 - KAB2M**

Round profile, measurement range 1000 mm, 1 voltage output 0.5 ... 10 V (U2)

Output 1: Position magnet 1, decreasing signal (P1D)

Output 2: Not used

**2. Order example: PCRP32 - 1000 - I1 - P1A - P2D - L02 - KAB2M**

Round Profile, measurement range 1000 mm, 2 current outputs 4 ... 20 mA (I1)

Output 1: Position magnet 1, increasing signal (P1A)

Output 2: Position magnet 2, decreasing signal (P2D)

**3. Order example: PCRP32 - 1000 - U2 - P1A - VZ1.0 - L02 - KAB2M**

Round Profile, measurement range 1000 mm, 2 voltage outputs 0.5 ... 10 V (U2)

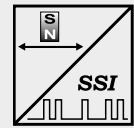
Output 1: Position magnet 1, increasing signal (P1A)

Output 2: Velocity magnet 1, -1 m/s ... 1 m/s for range 0.5 ... 10 V (VZ1.0)



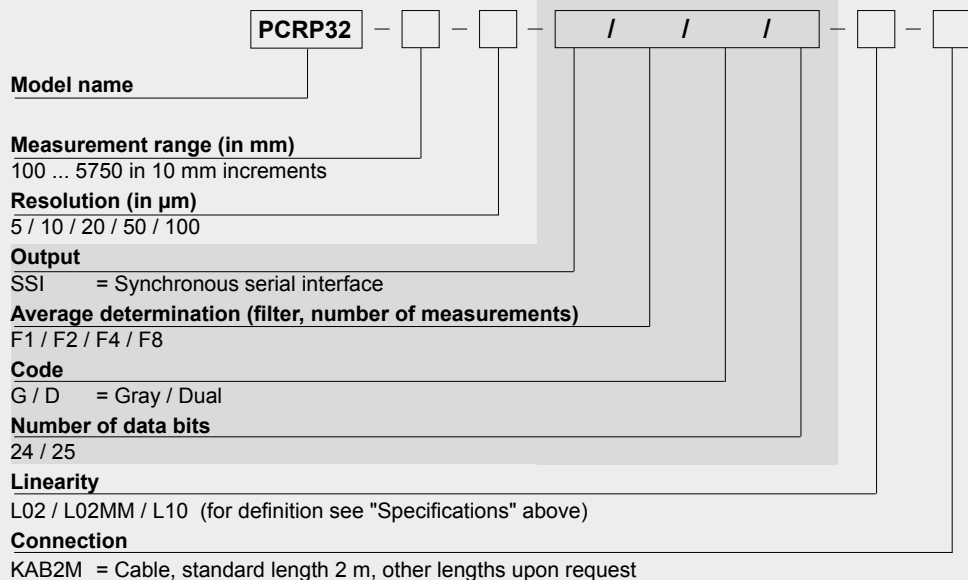
**POSICHRON® position sensor in a stainless steel pressure tube**

- Protection class IP67/69K, IP68
- Underwater applications, permanent pressure-proof up to 15 bar
- Measurement range 0 ... 100 to 0 ... 5750 mm
- Absolute position measurement
- Contact-free
- Seawater-proof
- Synchronous serial interface (SSI)



Specifications		
Output	Synchronous serial (SSI)	
Resolution	5, 10, 20, 50, 100 µm	
Sampling rate	Up to 1 kHz, depending on the measurement range	
Linearity	Ranges >500 mm: L10 = ±0.10 % f.s. L02 = ±0.02 % f.s. Ranges ≤500 mm: L10 = ±0.5 mm L02MM = ±0.2 mm	
Repeatability	±3 µm	
Housing material	Stainless steel 1.4404	
Protection class	IP68 (permanent pressure-proof up to 15 bar), IP67/69K	
Shock	EN 60068-2-27:1993, 50 g 11 ms, 100 shocks	
Vibration	EN 60068-2-6:1995, 20 g 10 Hz-2 kHz, 10 cycles	
Connection	Cable 2 m	
EMC, temperature	Refer to output specification	

**Order Code PCR32**

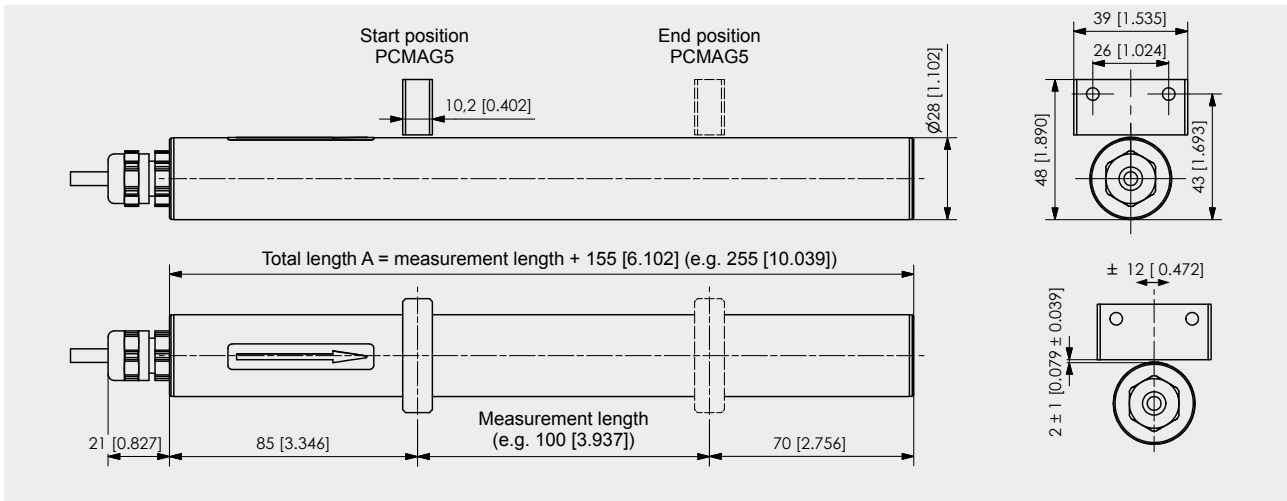


Order code position magnet (see page 5)

**PCMAG5**

**Order example: PCR32 - 2000 - 5 - SSI/F8/G/24 - L02 - KAB2M**

**POSICHRON<sup>®</sup>**  
**PCRP32**  
**Round Profile Housing**



Dimensions in mm [inch]

Dimensions informative only.

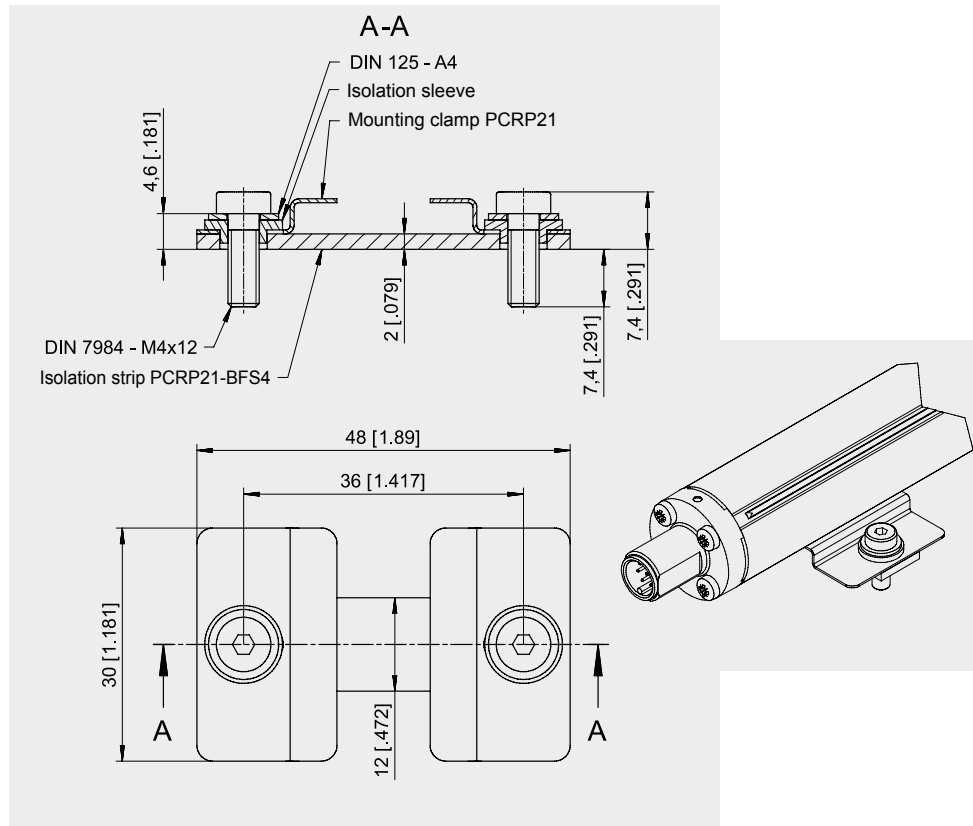
For guaranteed dimensions consult factory.

Other designs can be realized on request

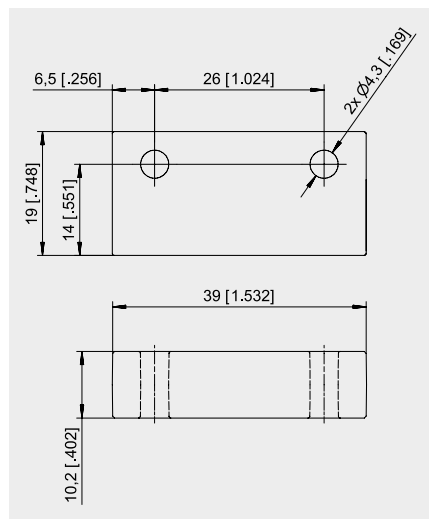
# POSICHRON® PCRP Mounting set - Magnets



## PCRP21-BFS4 Mounting set



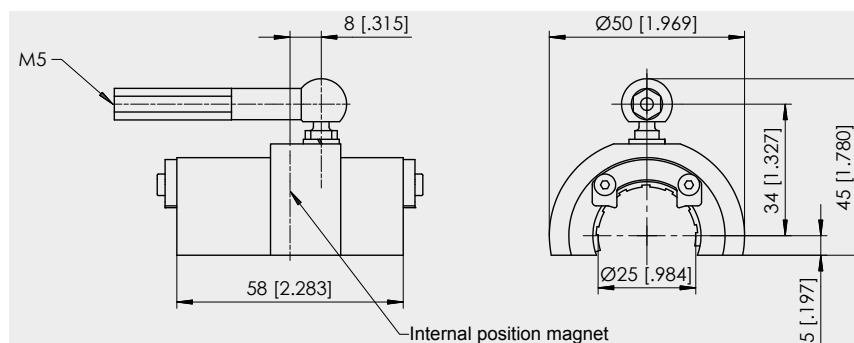
## PCMAG5 Standard magnet



Dimensions in mm [inch]

Dimensions informative only.  
For guaranteed dimensions consult factory.

## PCRPMAG6 Guided magnet slider for PCR21 with internal position magnet



Not to be used for a large number of operation cycles!

# POSICHRON®

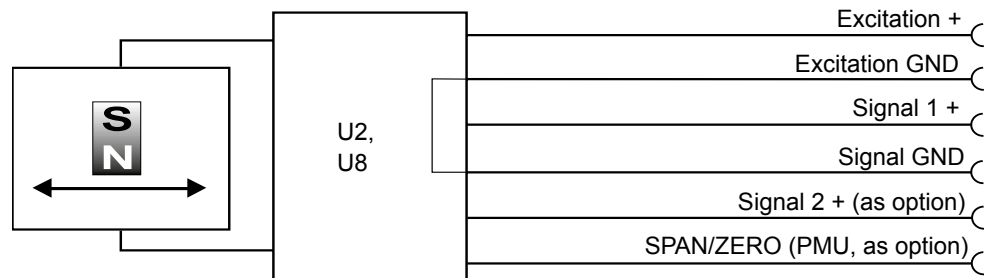
## Output Specification U2, U8 and I1

### Configurable, 1 or 2 channels



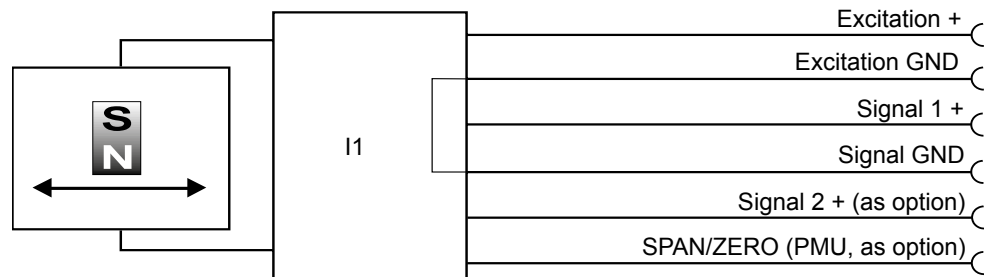
<b>Signal conditioner</b> <b>U2, U8</b> Voltage output 	Excitation voltage	U2: 18 ... 27 V DC; U8: 10 ... 36 V
	Excitation current	Typ. 35 mA, 80 mA max.
	Output voltage	U2: 0.5 ... 10 V; U8: 0.5 ... 4.5 V
	Output current	2 mA max.
	Output load	> 5 kΩ
	Resolution	16 bit
	Stability (temperature)	$\pm 50 \times 10^{-6} / ^\circ\text{C}$ f.s.
	Protection	Reverse polarity, short circuit
	Output noise	0.5 mV <sub>RMS</sub>
	Operating temperature	-40 ... +85 °C
Immunity to interference (EMC)	According to EN 61326:2004	

#### Signal diagram



<b>Signal conditioner</b> <b>I1</b> Current output (3 wire) 	Excitation voltage	18 ... 27 V DC
	Excitation current	Typ. 60 mA, 80 mA max.
	Load resistor	350 Ω max.
	Output current	4 ... 20 mA, 30 mA max (at failure)
	Resolution	16 bit
	Stability (temperature)	$\pm 50 \times 10^{-6} / ^\circ\text{C}$ f.s.
	Protection	Reverse polarity, short circuit
	Output noise	0.5 mV <sub>RMS</sub>
	Operating temperature	-40 ... +85 °C
Immunity to interference (EMC)	According to EN 61326:2004	

#### Signal diagram



Signal wiring	Output sigals U2, U8, I1	Connector pin	Cable output, wire color (not for PCST27 and PCRP32)
	Excitation +	1	white
	Excitation GND	2	brown
	Signal 1 +	3	green
	Signal GND	4	yellow
	Signal 2 + (as option *)	5	grey
	SPAN/ZERO (PMU **, as option)	6	pink

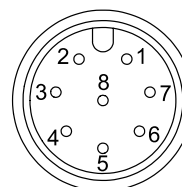
\* When using multiple magnets the distance between two magnets must be min. 70 mm to identify the single magnets definitely.

\*\* Description page 59

#### Connection

Mating connector

View to  
sensor  
connector



CONN-M12-8M

# POSICHRON®

## Description of Output Options



### Option - PMU for analog output U2, U8 and I1

Programming of the start and end value by the customer:

The option PMU allows to program the start value and the end value of the output range by a programming signal SPAN/ZERO available at the connector. This Signal SPAN/ZERO must be connected with GND via a push button, then position magnet of the sensor must be moved to the start resp. end position. Pushing the button between 1 and 4 seconds sets the actual position as start position, pushing the button more than 5 seconds sets the actual position as end position. The values will be stored and are available after switching off the sensor.

To reset the sensor to the factory values the button must be pushed when the sensor is switched on.

### Diagnostic signal on error for U2 and I1

#### The analog signal output in case of error

In case of error (e.g. magnet missing) the analog output signal will assume a state according to the following options:

Standard (w/o marking): Alarm_HIGH:	The output voltage resp. the output current is at HIGH level (overrange)
Option /U: Alarm_LOW:	The output voltage resp. the output current is at LOW level (underrange)
Option /H: Alarm_HOLD:	The output voltage resp. the output current will keep the last valid state

### Option F1/F2/F4/F8 for SSI output

#### Filter function of the SSI interface

The option „Filter“ Fn calculates the floating average over a sample of measurement values. With the sample size the settling time of the measured value will be extended. Suitable sample sizes are 2, 4 and 8.

### Error signal for SSI output

If the sensor cannot detect a magnet the position value will assume the maximum value (0xFFFFFFFF)

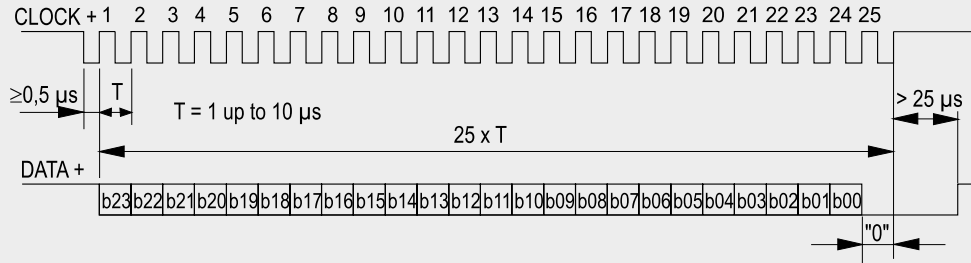
# POSICHRON® Output Specification SSI



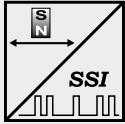
## Description

The data transmission takes place by means of the two signals CLOCK and DATA. The processing unit (PLC, microcomputer) sends pulse sequences which clock the data transmission at the required transfer rate. With the first falling edge of the pulse sequence the position of the sensor is recorded and stored. The following rising edges control the bit-by-bit transfer of the data word. After a delay time the next new position information can be transmitted.

## Data format (Train of 26 pulses)

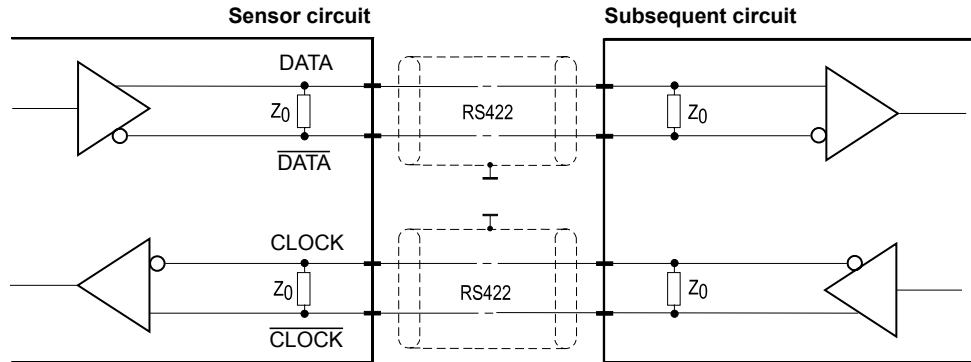


## Synchronous serial interface SSI



Output	RS422
Excitation voltage	18 ... 27 V DC, residual ripple 10 mV <sub>SS</sub>
Excitation current	Typ. 80 mA, 150 mA max.
Clock frequency	100 kHz ... 1 MHz
Code	Gray code, dual code
Resolution	≥ 5 µm
Delay between pulse trains	>25 µs
Filter	Average determination, see page 59
Stability (temperature)	±50 x 10 <sup>-6</sup> / °C f.s.
Operating temperature	-40 ... +85 °C
Immunity to interference EMC	According to EN 61326:2004

## Signal diagram



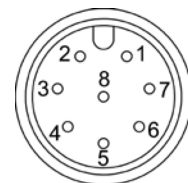
Cable length	Baud rate
50 m	100-1000 kHz
100 m	100-300 kHz

**Note:**  
Extension of the cable length will reduce the maximum transmission rate.  
The signals CLOCK/CLOCK and DATA/DATA must be connected in a twisted pair cable, common shielded.

## Signal wiring

Signal name	Connector pin	Cable output color (not for PCST27 and PCR32)
Excitation +	1	white
Excitation GND	2	brown
CLOCK	3	green
CLOCK	4	yellow
DATA	5	grey
DATA	6	pink

View to sensor connector



CONN-M12-8M

Filter option F1/F2/F4/F8 and error indication see page 7.



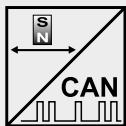
# POSICHRON® Output Specification CANopen



## Description

CANopen interface with process data for position and cam functions, programmable are preset, resolution, filtering and cam switching points.

### Interface CANOP



Communication profile	CANopen CiA 301 V 4.02, Slave
Encoder profile	Encoder CiA 406 V 3.2
Error Control	Node Guarding, Heartbeat, Emergency Message
Node ID	Adjustable via LSS or via object dictionary
PDO	4 TxPDO, 0 RxPDO, no linking, static mapping
PDO Modes	Event-/Time triggered, Remote-request, Sync cyclic/acyclic
SDO	1 server, 0 client
CAM	2 cams
Certified	Yes
Transmission rates	50 kBaud to 1 MBaud, adjustable via LSS or via object dictionary
Nodes	127 max.
Bus connection	M12 connector, 5 pins
Integrated bus terminating resistor	As option (output CANOP/R)
Bus, galvanic isolated	No

### Specifications

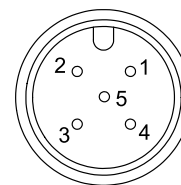
Excitation voltage	18 ... 36 V DC
Excitation current	Typ. 20 mA for 24 V, max. 100 mA
Number of position magnets	1 ... 4
Resolution	50 µm
Measuring rate	1 kHz (asynchronous)
Stability (temperature)	±50 x 10 <sup>-6</sup> / °C f.s.
Repeatability	1 LSB
Operating temperature	-40 ... +85 °C
Protection	Reverse polarity, short circuit
Dielectric strength	500 V (V AC, 50 Hz, 1 min.)
Environment - EMC Automation	EN 61326-1:2006

When using multiple magnets the distance between two magnets must be min. 70 mm to identify the single magnets definitely.

### Signal wiring / connection

Signal name	Connector pin (color)
Shield	1 (grey)
Excitation +	2 (white)
GND	3 (brown)
CAN-H	4 (green)
CAN-L	5 (yellow)

View to sensor connector



# POSICHRON® Output Specification CAN SAE J1939



<b>Interface J1939</b> 	CAN specification	ISO 11898, Basic and Full CAN 2.0 B
	Transceiver	24V-compliant, not isolated
	Communication profile	SAE J1939
	Baud rate	250 kbit/s
	Internal termination resistor	120 Ω
	Address	Default 247d, configurable

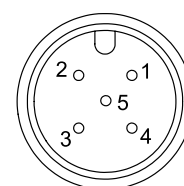
<b>NAME Fields</b>	Arbitrary address capable	1	Yes
	Industry group	0	Global
	Vehicle system	7Fh (127d)	Non specific
	Vehicle system instance	0	
	Function	FFh (255d)	Non specific
	Function instance	0	
	ECU instance	0	
	Manufacturer	145h (325d)	Manufacturer ID
	Identity number	0nnn	Serial number 21 bit

<b>Parameter Group Numbers (PGN)</b>	Configuration data	PGN EF00h	Proprietary-A (PDU1 peer-to-peer)
	Process data	PGN FFnnh	Proprietary-B (PDU2 broadcast); nn Group Extension (PS) configurable

<b>Specifications</b>	Excitation voltage	18 ... 36 V DC
	Excitation current	Typ. 20/40 mA for 24/12 V, max. 100 mA
	Measuring rate	1 kHz (asynchronous)
	Stability (temperature)	±50 x 10 <sup>-6</sup> / °C f.s.
	Repeatability	1 LSB
	Operating temperature	-40 ... +105 °C
	Protection	Reverse polarity, short circuit
	Dielectric strength	500 V (V AC, 50 Hz, 1 min.)
	EMC	EN 61326-1:2006

Signal wiring / connection	Signal name	Connector pin no.
	Shield	1
	Excitation +	2
	GND	3
	CAN-H	4
	CAN-L	5

View to sensor connector



# POSICHRON® Accessories Connector Cables



**Connector cable for POSICHRON® position sensors**  
8 pin M12

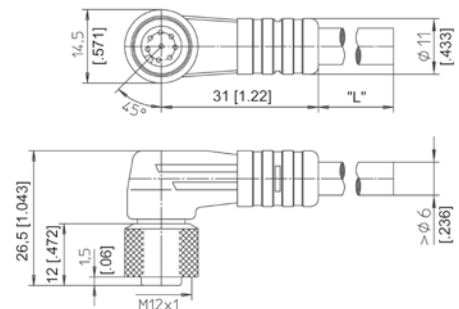
The 8-lead shielded cable is supplied with a mating 8-pin 90° M12 connector at one end and 8 wires at the other end. Available lengths are 2, 5 and 10 m. Wire: cross sectional area 0.25 mm².

Order code:

**KAB - XM - M12/8F/W - LITZE**

**IP69K: KAB - XM - M12/8F/W/69K - LITZE**

Length in m



**Connector cable for POSICHRON® position sensors**  
8 pin M12

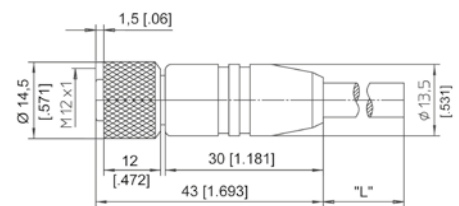
The 8-lead shielded cable is supplied with a mating 8-pin M12 connector at one end and 8 wires at the other end. Available lengths are 2, 5 and 10 m. Wire: cross sectional area 0.25 mm².

Order code:

**KAB - XM - M12/8F/G - LITZE**

**IP69K: KAB - XM - M12/8F/G/69K - LITZE**

Length in m



**Connector cable wiring - M12, 8 pin**

**Connector pin / cable color**

1	2	3	4	5	6	7	8
White	Brown	Green	Yellow	Grey	Pink	Blue	Red

**Connector cable for POSICHRON® position sensors**  
4 pin M8

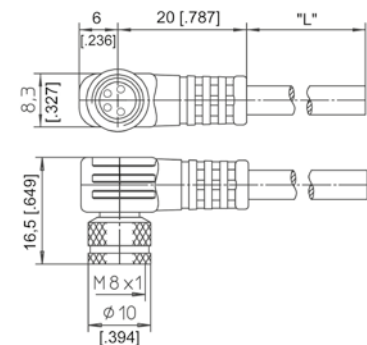
The 4-lead shielded cable is supplied with a mating 4-pin 90° M8 connector at one end and 4 wires at the other end. Available lengths are 2, 5 and 10 m. Wire: cross sectional area 0.14 mm².

Order code:

**KAB - XM - M8/4F/W - LITZE**

**IP69K: KAB - XM - M8/4F/W/69K - LITZE**

Length in m



**Connector cable for POSICHRON® position sensors**  
4 pin M8

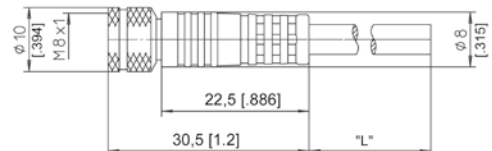
The 4-lead shielded cable is supplied with a mating 4-pin M8 connector at one end and 4 wires at the other end. Available lengths are 2, 5 and 10 m. Wire: cross sectional area 0.14 mm².

Order code:

**KAB - XM - M8/4F/G - LITZE**

**IP69K: KAB - XM - M8/4F/G/69K - LITZE**

Length in m



**Connector cable wiring - M8, 4 pin**

**Connector pin / cable color**

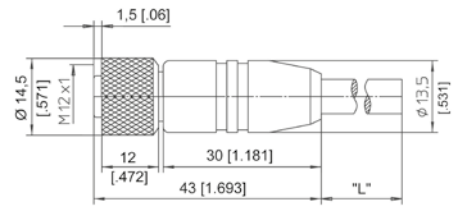
1	2	3	4
Brown	White	Blue	Black

# POSICHRON® Accessories Connector Cables



**Connector/bus cable  
for POSICHRON®  
position sensors**  
5 pin M12  
CAN bus

The 5-lead shielded cable is supplied with a female 5-pin M12 connector at one end and a male 5-pin M12 connector at the other end. Available lengths are 0.3 m, 2 m, 5 m and 10 m.



Order code:

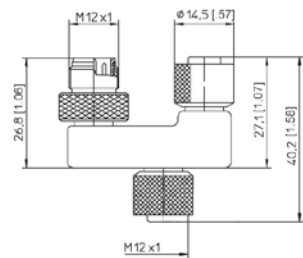
**KAB - XM - M12/5F/G - M12/5M/G - CAN**

**IP69K: KAB - XM - M12/5F/G/69K - M12/5M/G/69K - CAN**

Length in m ↑

**T-piece for bus cable**  
5 pin M12  
CAN bus

**KAB - TCONN - M12/5M - 2M12/5F - CAN**



**Terminating  
resistance**  
5 pin M12  
CAN bus

**KAB - RTERM - M12/5M/G - CAN**

