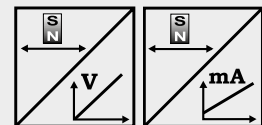




POSICHRON® position sensor in round profile

- Protection class IP64
- Measurement range 0 ... 100 to 0 ... 5750 mm
- Absolute position measurement
- Contact-free
- Large guiding tolerance for the positioning magnet
- Analog output



Specifications	Output	Voltage Current
	Resolution	
Sampling rate		Up to 1 kHz, depending on the measurement range
Linearity		Ranges >500 mm: L10 = ±0.10 % f.s. L02 = ±0.02 % f.s. Ranges ≤500 mm: L10 = ±0.5 mm L02MM = ±0.2 mm
Repeatability		±3 µm
Housing material		AlMgSi1 / Zn / V4A
Protection class		IP64 (with mating connector only)
Shock		EN 60068-2-27:1993, 50 g 11 ms, 100 shocks
Vibration		EN 60068-2-6:1995, 20 g 10 Hz-2 kHz, 10 cycles
Connection		8 pin socket M12 / cable 2 m
EMC, temperature		Refer to output specification

Order code mounting set (see page 6)

Order code position magnets (see page 6)

Order code mating connecting cable (see page 12/13)

PCRP21-BFS4

PCMAG ...

KAB-...M-M12/8F/G-LITZE



Order Code PCR21

**1 or 2 channel,
configurable**

PCRP21 - [] - [] - [] - [] - [] - []

Model name

Measurement range (in mm)

100 ... 5750 in 10 mm increments

Output

U2 = 0.5 ... 10 V signal conditioner

U2/U, U2/H = U2 with AlarmLOW, U2 with AlarmHOLD (see page 77)

U8 = 0.5 ... 4.5 V signal conditioner

I1 = 4 ... 20 mA signal conditioner (3 wire)

I1/U, I1/H = I1 with AlarmLOW, I1 with AlarmHOLD (see page 77)

Function and characteristics output 1

P1A = Position magnet 1, increasing

P1D = Position magnet 1, decreasing

PMU = Start value, direction & end value adjustable by the customer (1 channel only)

DA = Difference magnet 1/2, increasing (2 magnets required)

DD = Difference magnet 1/2, decreasing (2 magnets required)

Function and characteristics output 2 (option)

P2A = Position magnet 2, increasing

P2D = Position magnet 2, decreasing

DA = Difference magnet 1/2, increasing

DD = Difference magnet 1/2, decreasing

} 2 magnets required

VZx.x = Velocity with direction detection (with 1 magnet only)

VZx.x = Velocity in steps of 0.1 m/s

<u>Example: VZ1.5</u>	towards start position		towards end position
	-1.5 m/s	0	+1.5 m/s

Output U2:	0.5 V	5.25 V	10 V
------------	-------	--------	------

Output I1:	4 mA	12 mA	20 mA
------------	------	-------	-------

VAx.x = Velocity without direction detection (with 1 magnet only)

VAx.x = Velocity in steps of 0.1 m/s

<u>Example: VA1.5</u>	towards start position		towards end position
	-1.5 m/s	0	+1.5 m/s

Output U2:	10 V	0.5 V	10 V
------------	------	-------	------

Output I1:	20 mA	4 mA	20 mA
------------	-------	------	-------

Linearity

L02 / L02MM / L10 (for definition see "Specifications" above)

Connection

M12 = Connector M12, 8 pin

KAB2M = Cable, standard length 2 m, other lengths upon request

1. Order example: PCR21 - 1000 - U2 - P1D - L10 - M12

Round profile, measurement range 1000 mm, 1 voltage output 0.5 ... 10 V (U2)

Output 1: Position magnet 1, decreasing signal (P1D)

Output 2: Not used

2. Order example: PCR21 - 1000 - I1 - P1A - P2D - L10 - M12

Round Profile, measurement range 1000 mm, 2 current outputs 4 ... 20 mA (I1)

Output 1: Position magnet 1, increasing signal (P1A)

Output 2: Position magnet 2, decreasing signal (P2D)

3. Order example: PCR21 - 1000 - U2 - P1A - VZ1.0 - L10 - M12

Round Profile, measurement range 1000 mm, 2 voltage outputs 0.5 ... 10 V (U2)

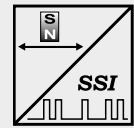
Output 1: Position magnet 1, increasing signal (P1A)

Output 2: Velocity magnet 1, -1 m/s ... 1 m/s for range 0.5 ... 10 V (VZ1.0)



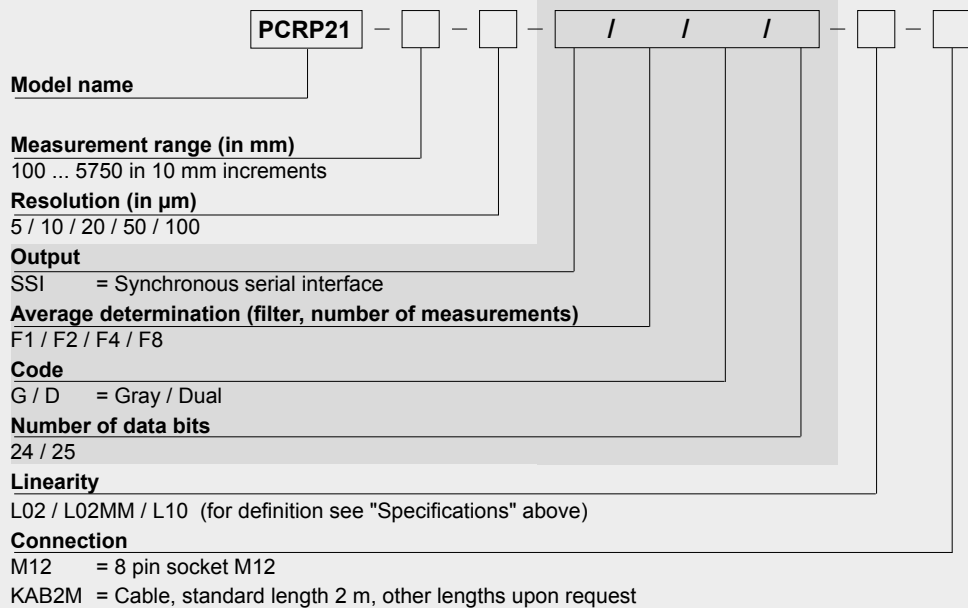
POSICHRON® position sensor in round profile

- Protection class IP64
- Measurement range 0 ... 100 to 0 ... 5750 mm
- Absolute position measurement
- Wear- and maintenance-free
- Superior shock and vibration resistance
- Large guiding tolerance for the positioning magnet
- Synchronous serial interface (SSI)



Specifications	Output	Synchronous serial interface (SSI)
	Resolution	5, 10, 20, 50, 100 µm
	Sampling rate	Up to 1 kHz, depending on the measurement range
	Linearity	Ranges >500 mm: L10 = ±0.10 % f.s. L02 = ±0.02 % f.s. Ranges ≤500 mm: L10 = ±0.5 mm L02MM = ±0.2 mm
	Repeatability	±3 µm
	Housing material	AlMgSi1 / Zn / V4A
	Protection class	IP64 (with mating connector only)
	Shock	EN 60068-2-27:1993, 50 g 11 ms, 100 shocks
	Vibration	EN 60068-2-6:1995, 20 g 10 Hz-2 kHz, 10 cycles
	Connection	8 pin socket M12 / cable 2 m
EMC, temperature	Refer to output specification	

Order Code PCR21



Order code mounting set (see page 6)

PCRP21-BFS4

Order code position magnets (see page 6)

PCMAG ...

Order code mating connecting cable (see page 12/13)

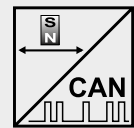
KAB-...M-M12/8F/G-LITZE

Order example: PCR21 - 1000 - 5 - SSI/F8/G/24 - L10 - M12



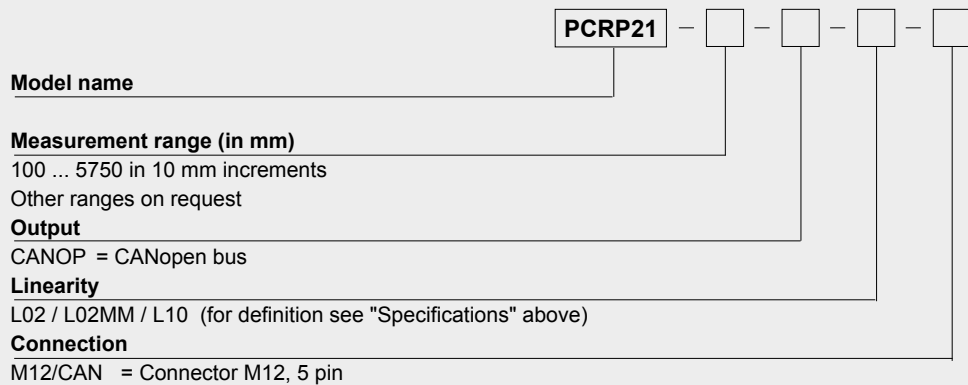
POSICHRON® position sensor in round profile

- Protection class up to IP65
- Measurement range 0 ... 100 to 0 ... 5750 mm
- Absolute position measurement
- Contact-free
- Large guiding tolerance for the positioning magnet
- CANopen bus



Specifications		
Output		CANopen bus
Resolution		50 µm
Sampling rate		Up to 1 kHz, depending on the measurement range
Linearity		Ranges >500 mm: L10 = ±0.10 % f.s. L02 = ±0.02 % f.s. Ranges ≤500 mm: L10 = ±0.5 mm L02MM = ±0.2 mm
Repeatability		±3 µm
Housing material		AlMgSi1 / Zn / V4A
Protection class		Up to IP65 (with mating connector only)
Shock		EN 60068-2-27:1993, 50 g 11 ms, 100 shocks
Vibration		EN 60068-2-6:1995, 20 g 10 Hz-2 kHz, 10 cycles
Connection		5 pin socket M12
EMC, temperature		Refer to output specification

Order Code PCRP21



Order code mounting set (see page 6)

PCRP21-BFS4

Order code position magnet (see page 6)

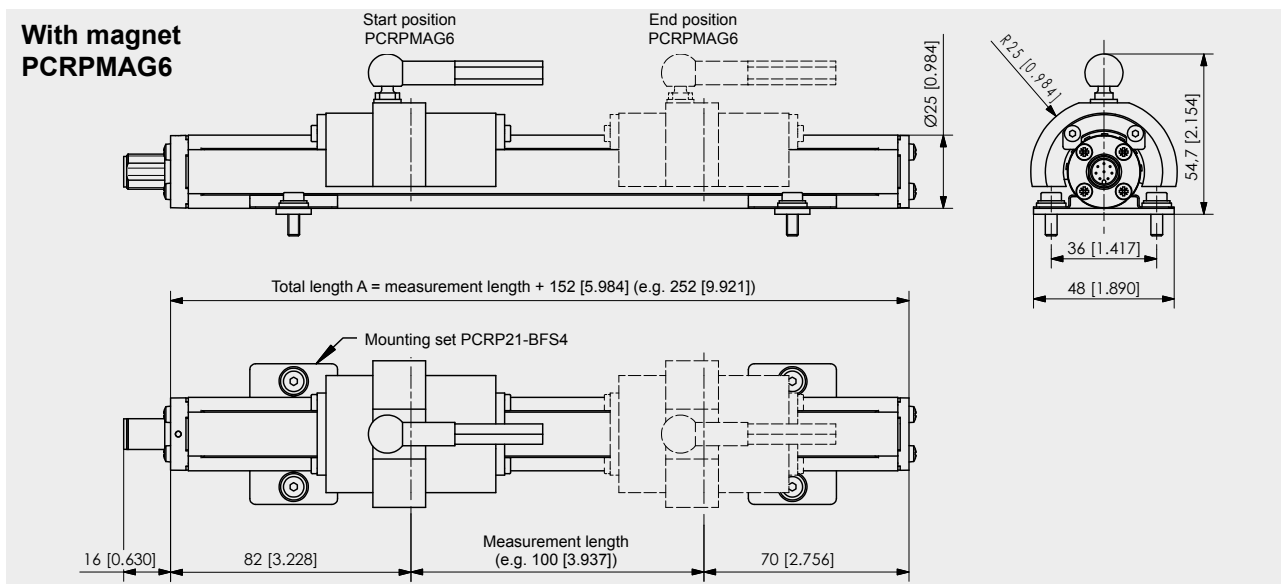
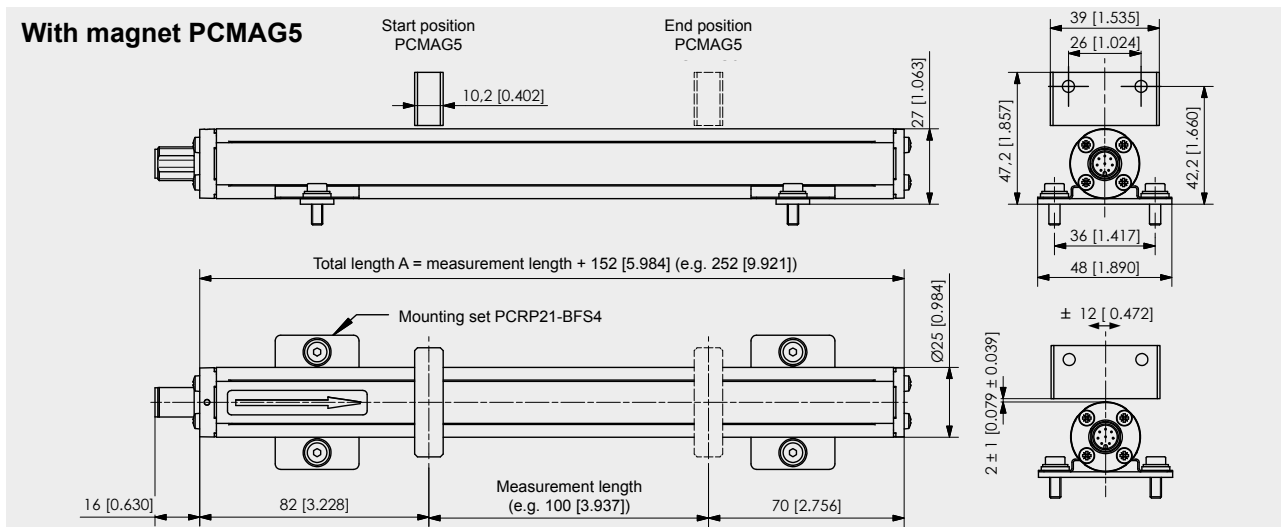
PCMAG ...

Order code bus cable (see page 13)

KAB-...M-M12/5F/G-M12/5M/G - CAN

Order example: PCRP21 - 1000 - CANOP - L10 - M12/CAN

POSICHRON® PCRP21 Round Profile Housing



Dimensions in mm [inch]

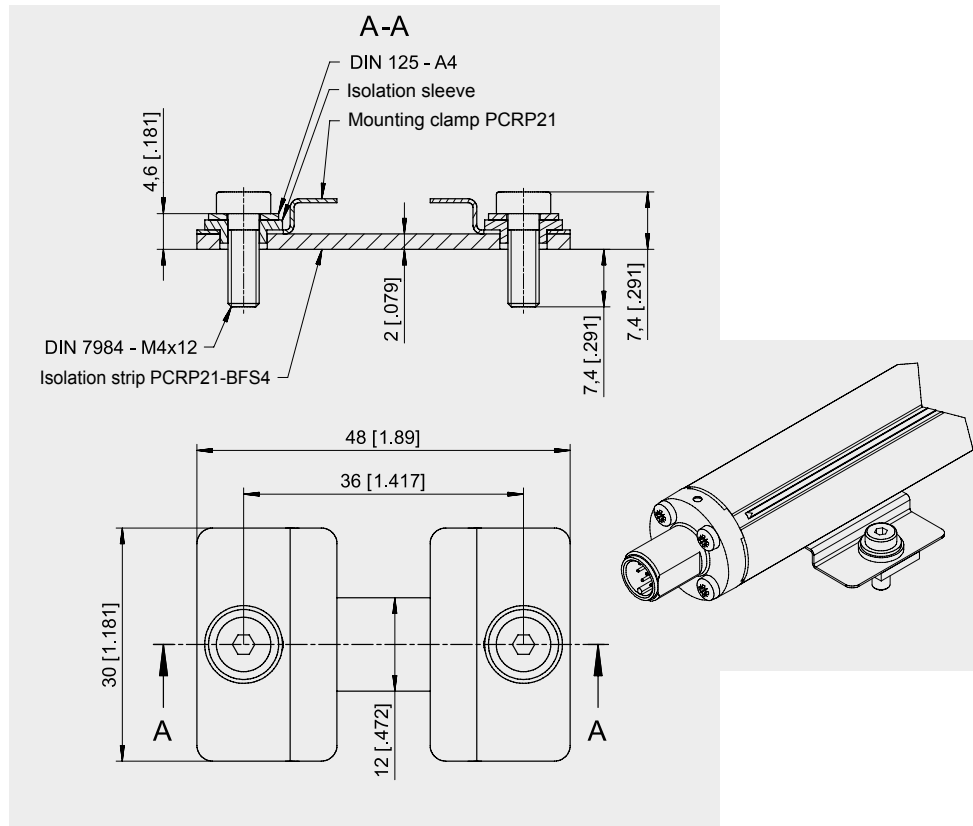
Dimensions informative only.

For guaranteed dimensions consult factory.

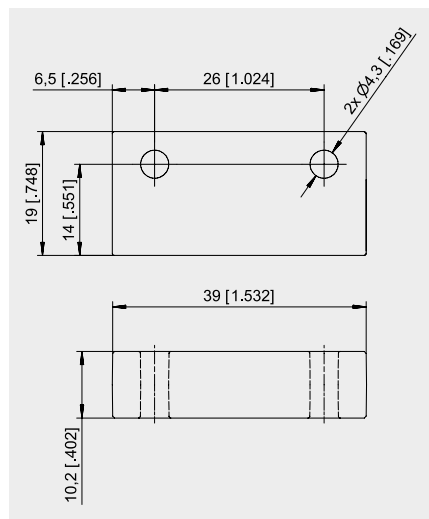
POSICHRON® PCRP Mounting set - Magnets



PCRP21-BFS4 Mounting set



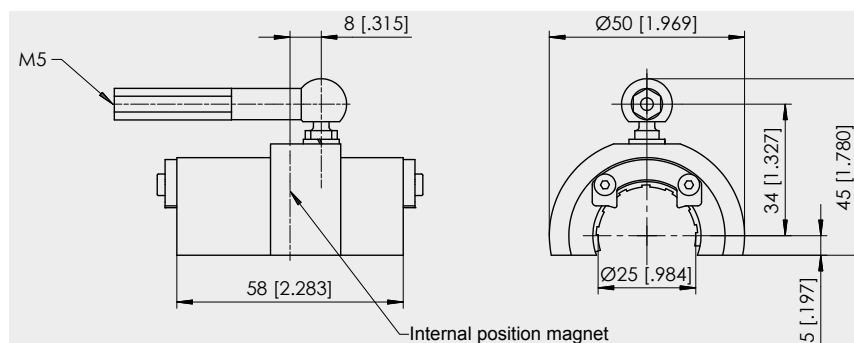
PCMAG5 Standard magnet



Dimensions in mm [inch]

Dimensions informative only.
For guaranteed dimensions consult factory.

PCRPMAG6 Guided magnet slider for PCR21 with internal position magnet



Not to be used for a large number of operation cycles!

POSICHRON®

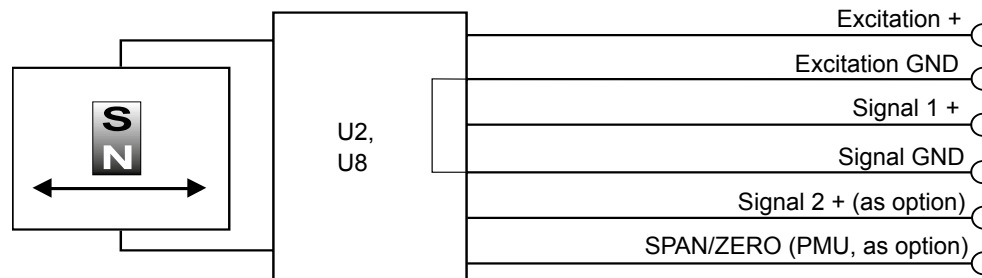
Output Specification U2, U8 and I1

Configurable, 1 or 2 channels



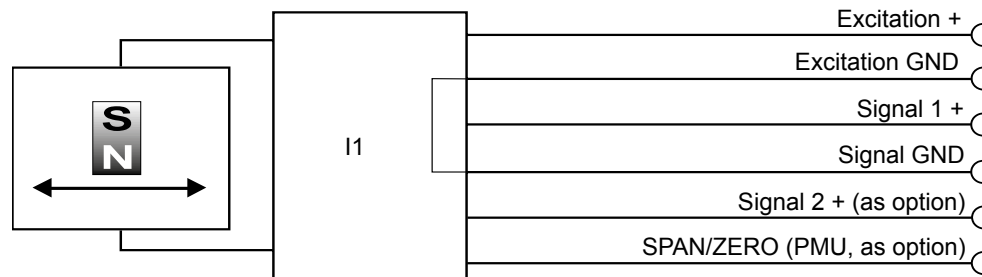
Signal conditioner U2, U8 Voltage output 	Excitation voltage	U2: 18 ... 27 V DC; U8: 10 ... 36 V
	Excitation current	Typ. 35 mA, 80 mA max.
	Output voltage	U2: 0.5 ... 10 V; U8: 0.5 ... 4.5 V
	Output current	2 mA max.
	Output load	> 5 kΩ
	Resolution	16 bit
	Stability (temperature)	$\pm 50 \times 10^{-6} / ^\circ\text{C}$ f.s.
	Protection	Reverse polarity, short circuit
	Output noise	0.5 mV _{RMS}
	Operating temperature	-40 ... +85 °C
Immunity to interference (EMC)	According to EN 61326:2004	

Signal diagram



Signal conditioner I1 Current output (3 wire) 	Excitation voltage	18 ... 27 V DC
	Excitation current	Typ. 60 mA, 80 mA max.
	Load resistor	350 Ω max.
	Output current	4 ... 20 mA, 30 mA max (at failure)
	Resolution	16 bit
	Stability (temperature)	$\pm 50 \times 10^{-6} / ^\circ\text{C}$ f.s.
	Protection	Reverse polarity, short circuit
	Output noise	0.5 mV _{RMS}
	Operating temperature	-40 ... +85 °C
	Immunity to interference (EMC)	According to EN 61326:2004

Signal diagram



Signal wiring	Output sigals U2, U8, I1	Connector pin	Cable output, wire color (not for PCST27 and PCR32)
	Excitation +	1	white
	Excitation GND	2	brown
	Signal 1 +	3	green
	Signal GND	4	yellow
	Signal 2 + (as option *)	5	grey
	SPAN/ZERO (PMU **, as option)	6	pink

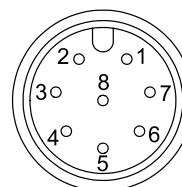
* When using multiple magnets the distance between two magnets must be min. 70 mm to identify the single magnets definitely.

** Description page 59

Connection

Mating connector

View to
sensor
connector



CONN-M12-8M

Option - PMU for analog output U2, U8 and I1

Programming of the start and end value by the customer:

The option PMU allows to program the start value and the end value of the output range by a programming signal SPAN/ZERO available at the connector. This Signal SPAN/ZERO must be connected with GND via a push button, then position magnet of the sensor must be moved to the start resp. end position. Pushing the button between 1 and 4 seconds sets the actual position as start position, pushing the button more than 5 seconds sets the actual position as end position. The values will be stored and are available after switching off the sensor.

To reset the sensor to the factory values the button must be pushed when the sensor is switched on.

Diagnostic signal on error for U2 and I1

The analog signal output in case of error

In case of error (e.g. magnet missing) the analog output signal will assume a state according to the following options:

Standard (w/o marking): Alarm_HIGH:	The output voltage resp. the output current is at HIGH level (overrange)
Option /U: Alarm_LOW:	The output voltage resp. the output current is at LOW level (underrange)
Option /H: Alarm_HOLD:	The output voltage resp. the output current will keep the last valid state

Option F1/F2/F4/F8 for SSI output

Filter function of the SSI interface

The option „Filter“ Fn calculates the floating average over a sample of measurement values. With the sample size the settling time of the measured value will be extended. Suitable sample sizes are 2, 4 and 8.

Error signal for SSI output

If the sensor cannot detect a magnet the position value will assume the maximum value (0xFFFFFFFF)

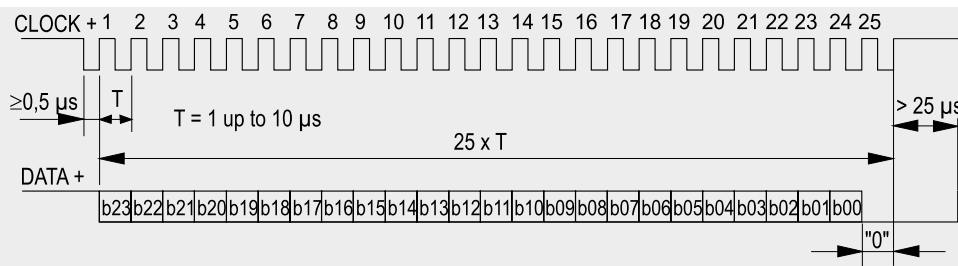
POSICHRON® Output Specification SSI



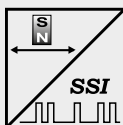
Description

The data transmission takes place by means of the two signals CLOCK and DATA. The processing unit (PLC, microcomputer) sends pulse sequences which clock the data transmission at the required transfer rate. With the first falling edge of the pulse sequence the position of the sensor is recorded and stored. The following rising edges control the bit-by-bit transfer of the data word. After a delay time the next new position information can be transmitted.

Data format (Train of 26 pulses)

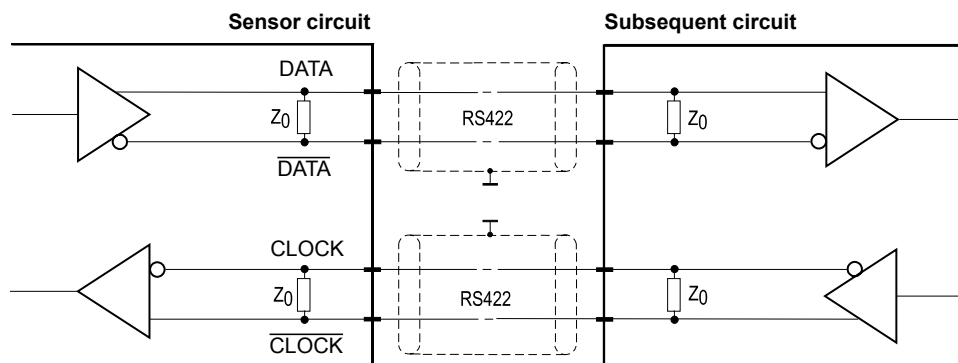


Synchronous serial interface SSI



Output	RS422
Excitation voltage	18 ... 27 V DC, residual ripple 10 mV _{SS}
Excitation current	Typ. 80 mA, 150 mA max.
Clock frequency	100 kHz ... 1 MHz
Code	Gray code, dual code
Resolution	≥ 5 μm
Delay between pulse trains	>25 μs
Filter	Average determination, see page 59
Stability (temperature)	±50 x 10 ⁻⁶ / °C f.s.
Operating temperature	-40 ... +85 °C
Immunity to interference EMC	According to EN 61326:2004

Signal diagram



Cable length	Baud rate
50 m	100-1000 kHz
100 m	100-300 kHz

Note:
Extension of the cable length will reduce the maximum transmission rate.
The signals CLOCK/CLOCK and DATA/DATA must be connected in a twisted pair cable, common shielded.

Signal wiring

Signal name	Connector pin	Cable output color (not for PCST27 and PCR32)
Excitation +	1	white
Excitation GND	2	brown
CLOCK	3	green
CLOCK	4	yellow
DATA	5	grey
DATA	6	pink

View to sensor connector



CONN-M12-8M

Filter option F1/F2/F4/F8 and error indication see page 8.

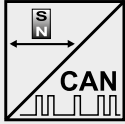
POSICHRON® Output Specification CANopen



Description

CANopen interface with process data for position and cam functions, programmable are preset, resolution, filtering and cam switching points.

Interface CANOP



Communication profile	CANopen CiA 301 V 4.02, Slave
Encoder profile	Encoder CiA 406 V 3.2
Error Control	Node Guarding, Heartbeat, Emergency Message
Node ID	Adjustable via LSS or via object dictionary
PDO	4 TxPDO, 0 RxPDO, no linking, static mapping
PDO Modes	Event-/Time triggered, Remote-request, Sync cyclic/acyclic
SDO	1 server, 0 client
CAM	2 cams
Certified	Yes
Transmission rates	50 kBaud to 1 MBaud, adjustable via LSS or via object dictionary
Nodes	127 max.
Bus connection	M12 connector, 5 pins
Integrated bus terminating resistor	As option (output CANOP/R)
Bus, galvanic isolated	No

Specifications

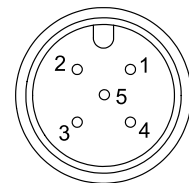
Excitation voltage	18 ... 36 V DC
Excitation current	Typ. 20 mA for 24 V, max. 100 mA
Number of position magnets	1 ... 4
Resolution	50 µm
Measuring rate	1 kHz (asynchronous)
Stability (temperature)	±50 x 10 ⁻⁶ / °C f.s.
Repeatability	1 LSB
Operating temperature	-40 ... +85 °C
Protection	Reverse polarity, short circuit
Dielectric strength	500 V (V AC, 50 Hz, 1 min.)
Environment - EMC Automation	EN 61326-1:2006

When using multiple magnets the distance between two magnets must be min. 70 mm to identify the single magnets definitely.

Signal wiring / connection

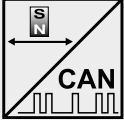
Signal name	Connector pin (color)
Shield	1 (grey)
Excitation +	2 (white)
GND	3 (brown)
CAN-H	4 (green)
CAN-L	5 (yellow)

View to sensor connector



POSICHRON® Output Specification CAN SAE J1939



Interface J1939 	CAN specification	ISO 11898, Basic and Full CAN 2.0 B
	Transceiver	24V-compliant, not isolated
	Communication profile	SAE J1939
	Baud rate	250 kbit/s
	Internal termination resistor	120 Ω
	Address	Default 247d, configurable

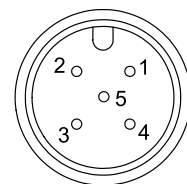
NAME Fields	Arbitrary address capable	1	Yes
	Industry group	0	Global
	Vehicle system	7Fh (127d)	Non specific
	Vehicle system instance	0	
	Function	FFh (255d)	Non specific
	Function instance	0	
	ECU instance	0	
	Manufacturer	145h (325d)	Manufacturer ID
	Identity number	0nnn	Serial number 21 bit

Parameter Group Numbers (PGN)	Configuration data	PGN EF00h	Proprietary-A (PDU1 peer-to-peer)
	Process data	PGN FFnnh	Proprietary-B (PDU2 broadcast); nn Group Extension (PS) configurable

Specifications	Excitation voltage	18 ... 36 V DC
	Excitation current	Typ. 20 mA for 24 V, max. 100 mA
	Measuring rate	1 kHz (asynchronous)
	Stability (temperature)	±50 x 10 ⁻⁶ / °C f.s.
	Repeatability	1 LSB
	Operating temperature	-40 ... +105 °C
	Protection	Reverse polarity, short circuit
	Dielectric strength	500 V (V AC, 50 Hz, 1 min.)
EMC	EN 61326-1:2006	

Signal wiring / connection	Signal name	Connector pin no.
	Shield	1
	Excitation +	2
	GND	3
	CAN-H	4
	CAN-L	5

View to sensor connector



POSICHRON® Accessories Connector Cables



Connector cable for POSICHRON® position sensors
8 pin M12

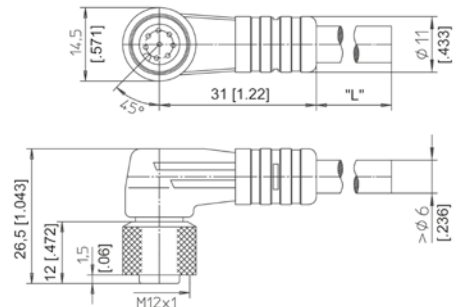
The 8-lead shielded cable is supplied with a mating 8-pin 90° M12 connector at one end and 8 wires at the other end. Available lengths are 2, 5 and 10 m. Wire: cross sectional area 0.25 mm².

Order code:

KAB - XM - M12/8F/W - LITZE

IP69K: KAB - XM - M12/8F/W/69K - LITZE

Length in m



Connector cable for POSICHRON® position sensors
8 pin M12

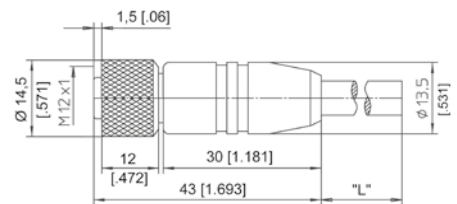
The 8-lead shielded cable is supplied with a mating 8-pin M12 connector at one end and 8 wires at the other end. Available lengths are 2, 5 and 10 m. Wire: cross sectional area 0.25 mm².

Order code:

KAB - XM - M12/8F/G - LITZE

IP69K: KAB - XM - M12/8F/G/69K - LITZE

Length in m



Connector cable wiring - M12, 8 pin	Connector pin / cable color							
	1	2	3	4	5	6	7	8
	White	Brown	Green	Yellow	Grey	Pink	Blue	Red

Connector cable for POSICHRON® position sensors
4 pin M8

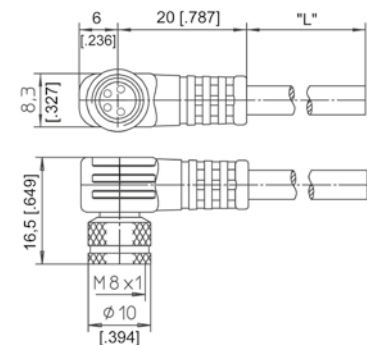
The 4-lead shielded cable is supplied with a mating 4-pin 90° M8 connector at one end and 4 wires at the other end. Available lengths are 2, 5 and 10 m. Wire: cross sectional area 0.14 mm².

Order code:

KAB - XM - M8/4F/W - LITZE

IP69K: KAB - XM - M8/4F/W/69K - LITZE

Length in m



Connector cable for POSICHRON® position sensors
4 pin M8

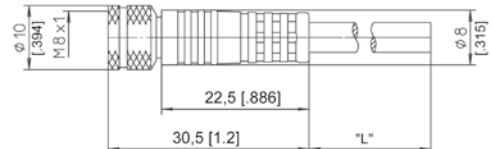
The 4-lead shielded cable is supplied with a mating 4-pin M8 connector at one end and 4 wires at the other end. Available lengths are 2, 5 and 10 m. Wire: cross sectional area 0.14 mm².

Order code:

KAB - XM - M8/4F/G - LITZE

IP69K: KAB - XM - M8/4F/G/69K - LITZE

Length in m



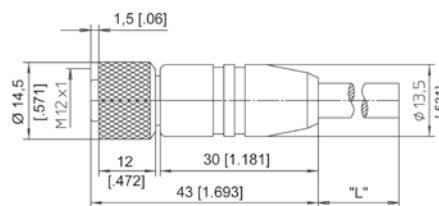
Connector cable wiring - M8, 4 pin	Connector pin / cable color			
	1	2	3	4
	Brown	White	Blue	Black

POSICHRON® Accessories Connector Cables



**Connector/bus cable
for POSICHRON®
position sensors**
5 pin M12
CAN bus

The 5-lead shielded cable is supplied with a female 5-pin M12 connector at one end and a male 5-pin M12 connector at the other end. Available lengths are 0.3 m, 2 m, 5 m and 10 m.



Order code:

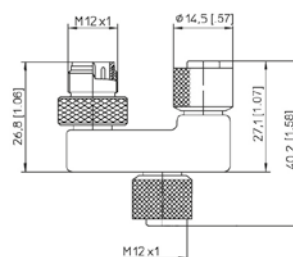
KAB - XM - M12/5F/G - M12/5M/G - CAN

IP69K: KAB - XM - M12/5F/G/69K - M12/5M/G/69K - CAN

Length in m ↑

T-piece for bus cable
5 pin M12
CAN bus

KAB - TCONN - M12/5M - 2M12/5F - CAN



**Terminating
resistance**
5 pin M12
CAN bus

KAB - RTERM - M12/5M/G - CAN

