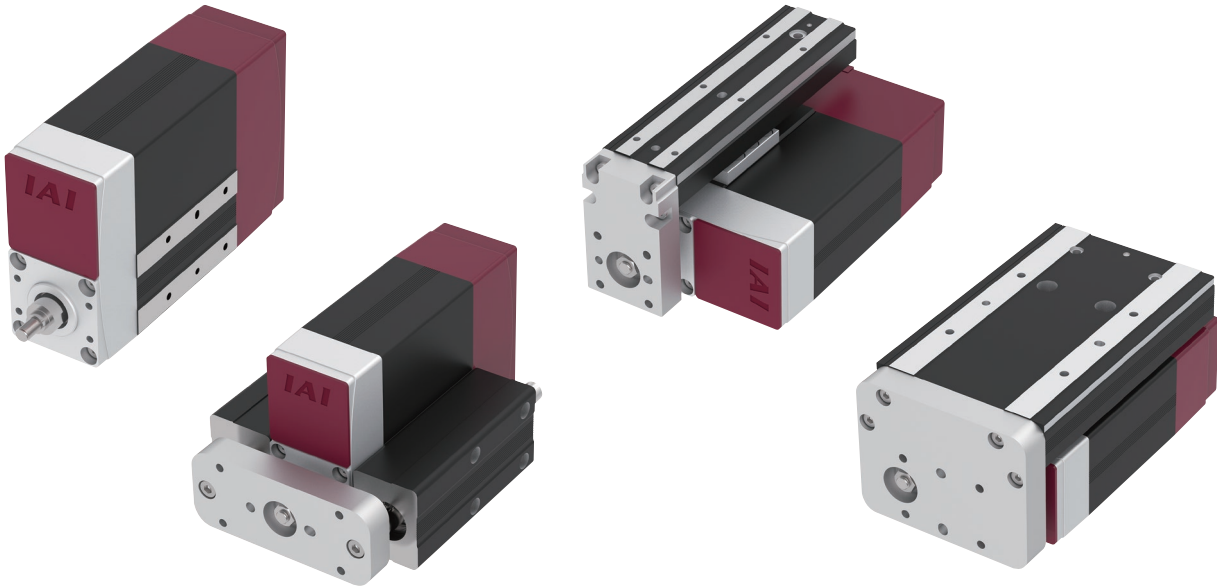


**Additional Mini Types Catalog**  
with more Stroke, Speed, and Power

**ELECYLINDER® mini type rods/tables**

**EC-RP5**  
**EC-GD5**  
**EC-TC5**  
**EC-TW5**



Simple & Wireless Operation  
2 Position Actuator

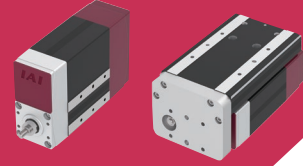


# Compact and powerful!! New additions to our mini type lineup!

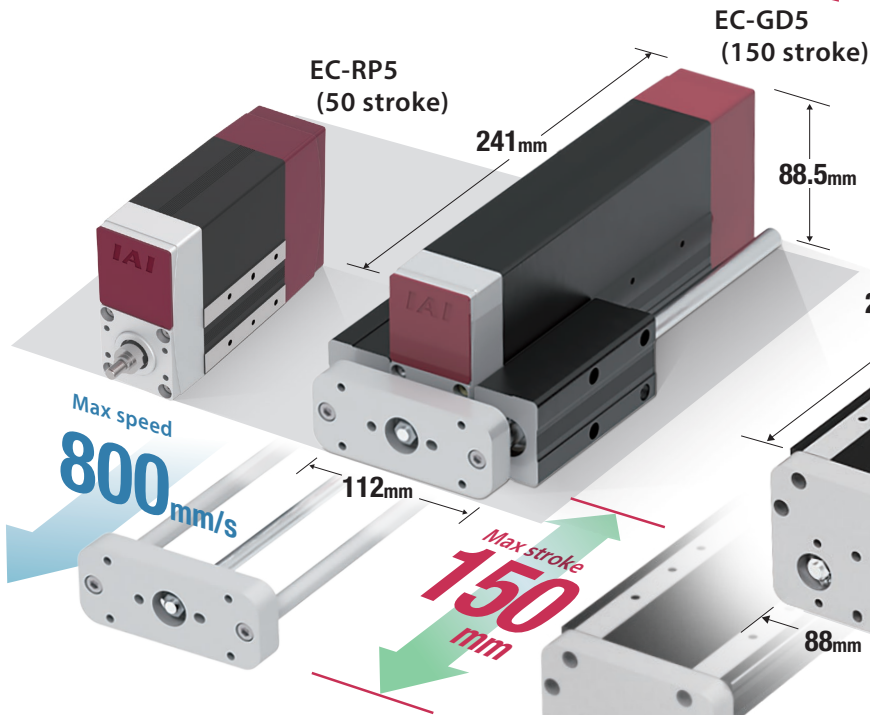


## Mini ELECYLINDER®

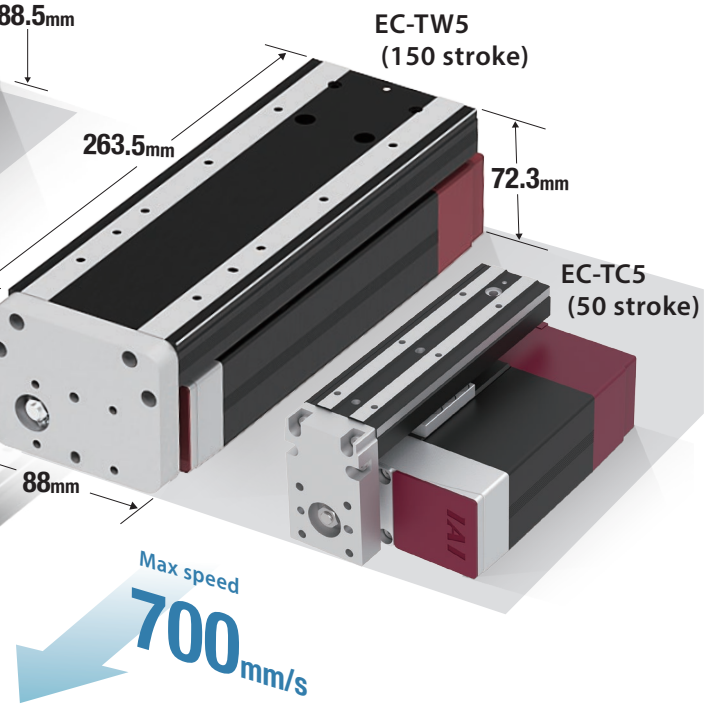
ELECYLINDER® EC-RP5/GD5/TC5/TW5 with more Stroke, Speed, and Power



### Rod type

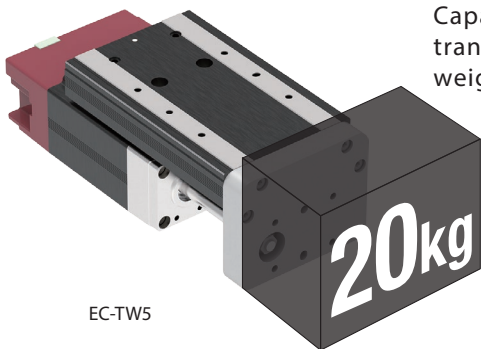


### Table type

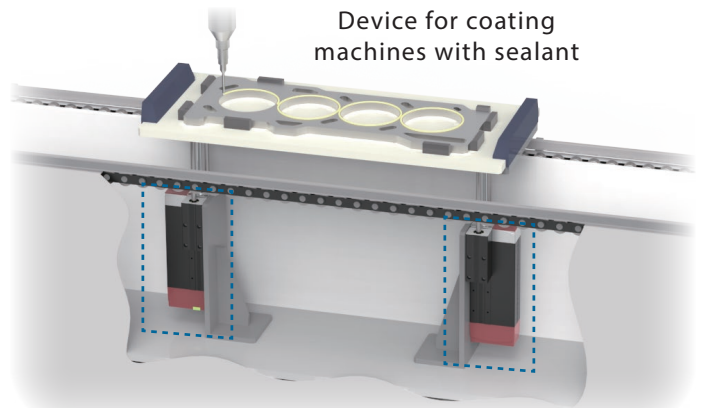


Small but powerful!!

Ideal for reducing space required by devices



Capable of transporting objects weighing up to 20kg



# Model Specification Items

**ELECYLINDER®**

**EC** Series - Type - Lead - Stroke - Cable length - (Options)

<b>RP5</b>	Rod type Side-mounted motor specification 45mm wide
<b>GD5</b>	Rod type Side-mounted motor specification 112mm wide (with double guide)
<b>TC5</b>	Table type Table 40mm wide
<b>TW5</b>	Table type Table 88mm wide

<b>S</b>	Lead 16mm
<b>H</b>	Lead 10mm
<b>M</b>	Lead 5mm
<b>L</b>	Lead 2.5mm

<b>0</b>	Without cable
<b>(S) 1</b>	1m
<b>?</b>	?
<b>(S) 10</b>	10m

(Every 1m)

<b>50</b>	50mm
<b>100</b>	100mm
<b>150</b>	150mm

<b>Left blank</b>	Incremental encoder specification, NPN specification, no option
<b>ACR</b>	RCON-EC connection specification
<b>B</b>	Brake
<b>G5</b>	Designated grease specification
<b>GT2</b>	Table right mount
<b>GT3</b>	Table bottom mount
<b>GT4</b>	Table left mount
<b>NM</b>	Non-motor end specification
<b>PN</b>	PNP specification
<b>TMD2</b>	Split motor and controller power supply specification
<b>WA</b>	Battery-less absolute encoder specification
<b>WL</b>	Wireless communication specification
<b>WL2</b>	Wireless axis operation specification

\*The range of selections varies according to the actuator type. Please refer to the pages of each type for details.

## Mini type specification tables

Type	Type	Lead		Stroke (mm) and max speed (mm/s)				Max. push force (N)	Max. payload (kg)		Reference Page
		Model	mm	*Length of band = Stroke, * Numbers in band = Maximum speed by stroke, Numbers in <> are for vertical specification					Horizontal	Vertical	
				30	50	100	150				
Rod	RP4	H-	6	300				30	2.5	1	Refer to ELECYLINDER® General Catalog 2020
		M-	4	200				45	4	1.5	
		L-	2	100				90	8	2.5	
	<b>NEW</b> RP5	S-	16	800				46	6.5	1.5	P.5
		H-	10	600				73	16	2.5	
		M-	5	300				150	25	6.5	
		L-	2.5	150<135>				310	35	6.5	
	GS4	H-	6	300				30	2.5	1	Refer to ELECYLINDER® General Catalog 2020
		M-	4	200				45	4	1.5	
		L-	2	100				90	8	2.5	
	GD4	H-	6	300				30	2.5	1	Refer to ELECYLINDER® General Catalog 2020
		M-	4	200				45	4	1.5	
L-		2	100				90	8	2.5		
<b>NEW</b> GD5	S-	16	800				46	6.5	1.5	P.9	
	H-	10	600				73	16	2.5		
	M-	5	300				150	25	6.5		
	L-	2.5	150<135>				310	35	6.5		
Table	TC4	H-	6	300				30	2.5	1	Refer to ELECYLINDER® General Catalog 2020
		M-	4	200				45	4	1.5	
		L-	2	100				90	8	2.5	
	<b>NEW</b> TC5	S-	16	420<280>				46	6.5	1.5	P.13
		H-	10	435<350>				73	12.5	2.5	
		M-	5	300<260>				150	12.5	5	
		L-	2.5	150<135>				310	12.5	6.5	
	TW4	H-	6	300				30	2.5	1	Refer to ELECYLINDER® General Catalog 2020
		M-	4	200				45	4	1.5	
		L-	2	100				90	8	2.5	
	<b>NEW</b> TW5	S-	16	420<280>				46	6.5	1.5	P.17
		H-	10	435<350>				73	16	2.5	
M-		5	300<260>				150	20	5		
L-		2.5	135				310	20	6.5		

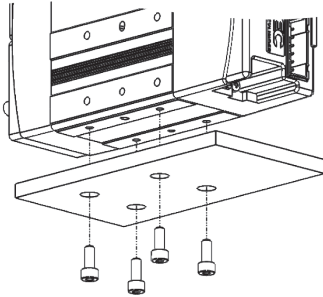
# Mounting method

Mount according to the mounting method for the applicable type.

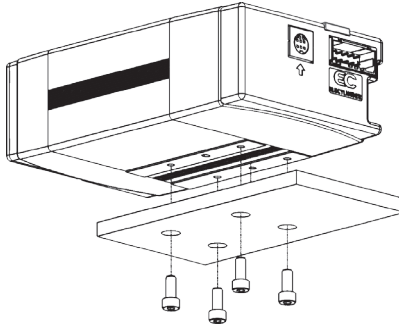
## Rod type (RP/GD)

### ● RP

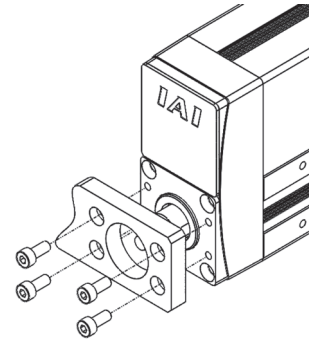
Use the mounting holes on the bottom surface of the body



Use the mounting holes on the side surface of the body

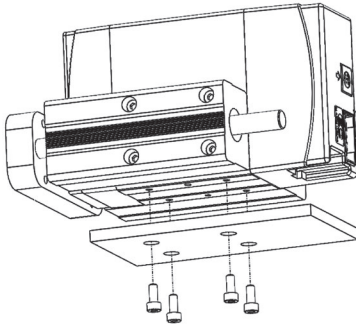


Use the mounting holes on the front bracket



### ● GD

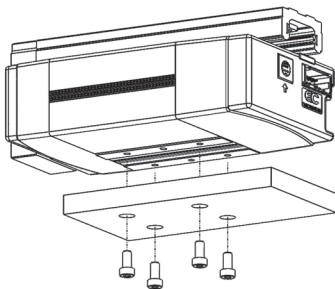
Use the mounting holes on the bottom surface of the body



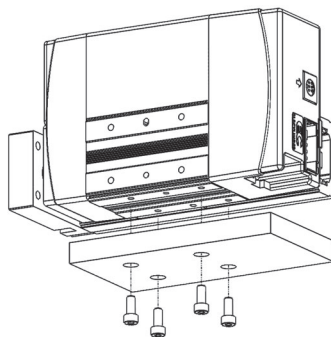
## Table type (TC/TW)

### ● TC

Use the mounting holes on the bottom surface of the body

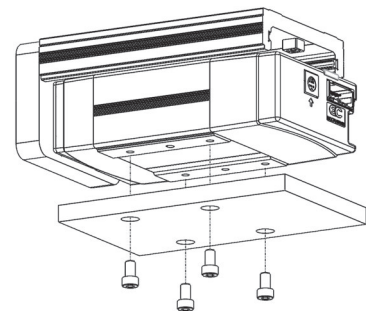


Use the mounting holes on the side surface of the body



### ● TW

Use the mounting holes on the bottom surface of the body



# Precautions for installation

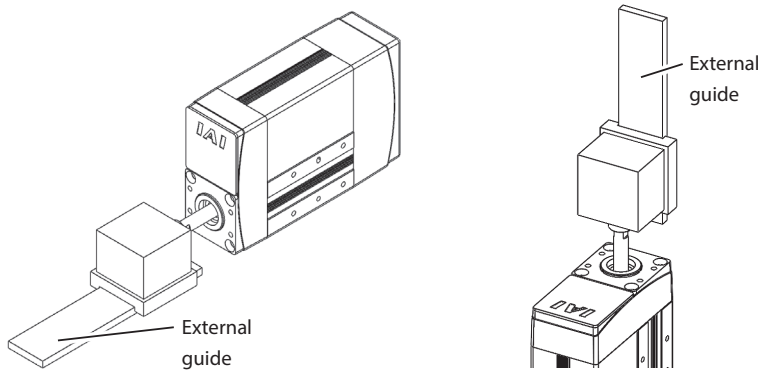
## ● External guide fixing method

Even when parallelism of the guide and the actuator has been adjusted, incorrect fixing risks premature damage to the actuator. See below:

### Rod type (RP5)

"Rigid attachment" is recommended to secure the product to an external guide. Be sure to perform home return after external guide mounting.

Rotation stop rod type actuators cannot bear the rotational force of the rod, so the rotation direction of the rod must be restricted. A "floating joint" does not restrict rotation of the rod. This causes ball screw misalignment, which can result in premature damage to the actuator. (Floating joints with rotation direction restrictions are acceptable.)



### Rod type, table type

Keep the body installation surface and part mounting surface flatness at 0.05mm/m or lower.

Uneven flatness will increase the sliding resistance of the rod/table and may cause a malfunction.

# Mounting orientation

○: Can be mounted

			Mounting orientation			
Classification	Series	Type	Horizontal mounting on flat surface	Vertical mounting	Side mounting	Ceiling mounting
Rod type	EC	RP5	○	○	○	○
		GD5	○	○	○	○
Table type		TCS/TW5	○	○	○	○

# EC-RP5

Mini

Rod Type

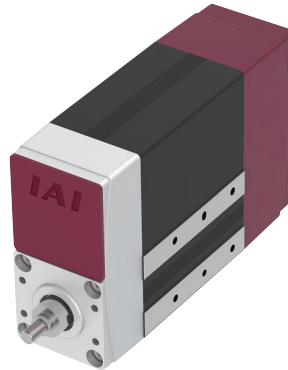
Side-mounted Motor

Body Width  
**50 mm**

**24v**  
Stepper Motor

**Model Specification Items**

<b>EC</b>	<b>RP5</b>				
Series	Type	Lead	Stroke	Power / I/O cable length	Options
		S 16mm	50 50mm	See power / I/O cable length below	See options below
		H 10mm	100 100mm		
		M 5mm	150 150mm		
		L 2.5mm			



Stroke	
Stroke (mm)	EC-RP5
<b>50</b>	<input type="radio"/>
<b>100</b>	<input type="radio"/>
<b>150</b>	<input type="radio"/>

Option * Please check the Options reference pages to confirm each option.		
Name	Option code	Reference page
RCON-EC connection specification (Note 1)	<b>ACR</b>	21
Brake	<b>B</b>	21
Designated grease specification (Note 2)	<b>G5</b>	21
PNP specification	<b>PN</b>	21
Split motor and controller power supply specification	<b>TMD2</b>	21
Battery-less absolute encoder specification	<b>WA</b>	21
Wireless communication specification	<b>WL</b>	22
Wireless axis operation specification	<b>WL2</b>	22

(Note 1) If the RCON-EC connection specification (ACR) is selected, the PNP specification (PN) and split motor and controller power supply specification (TMD2) cannot be selected.  
 (Note 2) The operating temperature environment for designated grease specification (G5) is 10°C to 40°C.

POINT  
Selection Notes

(1) The feed screw has no rotation stop mechanism. Add a rotation stop mechanism such as a guide to the tip of the feed screw when in use. (If there is no rotation stop, the feed screw will rotate instead of traveling back and forth.) Also, do not use floating joints when connecting the rotation stop mechanism to the rod. Please refer to P. 4 for more information on the mounting method and conditions.

(2) "Main Specifications" displays the payload's maximum value.

(3) The value of the horizontal payload assumes that there is an external guide. Do not apply external force to the rod in a direction other than the moving direction.

(4) If performing push-motion operations, refer to the "Correlation between Torque and Current Limit" diagram. The torques listed are only reference values. Please refer to P. 22 for applicable notes.

(5) Pay close attention to the installation orientation. Please refer to P. 4 for details.

### Power / I/O cable length

Cable code	Cable length	User wiring specification (flying leads)	RCON-EC connection specification (Note 4) (with connectors on both ends)
		CB-EC-PWBIO□□□-RB supplied	CB-REC-PWBIO□□□-RB supplied
<b>0</b>	No cable	<input type="radio"/> (Note 3)	<input type="radio"/>
<b>1 ~ 3</b>	1~3m	<input type="radio"/>	<input type="radio"/>
<b>4 ~ 5</b>	4 ~ 5m	<input type="radio"/>	<input type="radio"/>
<b>6 ~ 7</b>	6 ~ 7m	<input type="radio"/>	<input type="radio"/>
<b>8 ~ 10</b>	8 ~ 10m	<input type="radio"/>	<input type="radio"/>

(Note 3) Only terminal block connector is supplied. Please refer to P. 25 for details.  
 (Note 4) If RCON-EC connection specification (ACR) is selected as an option.  
 (Note) The robot cable is standard.

### 4-way connector cable

Cable code	Cable length	User wiring specification (flying leads)	RCON-EC connection specification (Note 5) (with connectors on both ends)
		CB-EC2-PWBIO□□□-RB supplied	CB-REC2-PWBIO□□□-RB supplied
<b>S1 ~ S3</b>	1~3m	<input type="radio"/>	<input type="radio"/>
<b>S4 ~ S5</b>	4 ~ 5m	<input type="radio"/>	<input type="radio"/>
<b>S6 ~ S7</b>	6 ~ 7m	<input type="radio"/>	<input type="radio"/>
<b>S8 ~ S10</b>	8 ~ 10m	<input type="radio"/>	<input type="radio"/>

(Note 5) If RCON-EC connection specification (ACR) is selected as an option.  
 (Note) The robot cable is standard.

**Main Specifications**

Item		Description				
Lead	Ball screw lead (mm)	16	10	5	2.5	
Horizontal	Payload	Max. payload (kg) (energy-saving disabled)	6.5	16	25	35
		Max. payload (kg) (energy-saving enabled)	6.5	15	25	35
	Speed/acceleration/deceleration	Max. speed (mm/s)	800	600	300	150
		Min. speed (mm/s)	40	30	7	4
Vertical	Payload	Max. payload (kg) (energy-saving disabled)	1.5	2.5	6.5	6.5
		Max. payload (kg) (energy-saving enabled)	1	2.5	5	6.5
	Speed/acceleration/deceleration	Max. speed (mm/s)	800	600	300	135
		Min. speed (mm/s)	40	30	7	4
Push	Max. push force (N)	46	73	150	310	
	Max. push speed (mm/s)	40	30	20	20	
Brake	Brake specification	Non-excitation actuating solenoid brake				
	Brake holding force (kgf)	1.5	2.5	6.5	6.5	
Stroke	Min. stroke (mm)	50	50	50	50	
	Max. stroke (mm)	150	150	150	150	
	Stroke pitch (mm)	50	50	50	50	

Item	Description
Driving system	Ball screw, φ8mm, rolled C10
Positioning repeatability	±0.05mm
Lost motion	- (two-point positioning function; cannot be represented)
Rod non-rotation precision	-
Service life	5000km
Ambient operating temperature, humidity	0 ~ 40°C, 85%RH or less (Non-condensing)
Degree of protection	IP20
Vibration & shock resistance	4.9m/s <sup>2</sup>
Overseas standards	CE marking, RoHS directive
Motor type	Stepper motor
Encoder type	Incremental/battery-less absolute
Number of encoder pulses	800 pulse/rev

**Table of Payload by Speed/Acceleration**

**Energy-saving setting disabled** The unit for payload is kg. If blank, operation is not possible.

**Lead 16**

Orientation	Acceleration (G)					
	Horizontal		Vertical			
Speed (mm/s)	0.3	0.5	0.7	1	0.3	0.5
0	6.5	4	3	2	1.5	1.25
140	6.5	4	3	2	1.5	1.25
280	6.5	4	3	2	1.5	1.25
420	6.5	4	2.5	1.5	1.5	1.25
560	5	3	2	1	1	1
700	3.5	1.5	1	0.5	1	1
800		1	1	0.5		0.5

**Lead 10**

Orientation	Acceleration (G)					
	Horizontal		Vertical			
Speed (mm/s)	0.3	0.5	0.7	1	0.3	0.5
0	16	11	7	4.5	2.5	2
175	16	11	7	4.5	2.5	2
350	12.5	7	4	2.5	2.5	2
435	9.5	5	3	1.5	2	2
525	5	4	2	1	1.5	1
600	4.5	2	1	0.5	0.5	

**Lead 5**

Orientation	Acceleration (G)			
	Horizontal		Vertical	
Speed (mm/s)	0.3	0.5	0.3	0.5
0	25	22	6.5	4.5
85	25	22	6.5	4.5
130	25	20	5	4.5
215	15	15	4	4
260	10	10	2	2
300	5	5	1.5	1.5

**Lead 2.5**

Orientation	Acceleration (G)	
	Horizontal	Vertical
Speed (mm/s)	0.3	0.3
0	35	6.5
40	35	6.5
85	35	6.5
105	35	6.5
135	30	2
150	10	

**Energy-saving setting enabled** The unit for payload is kg. If blank, operation is not possible.

**Lead 16**

Orientation	Acceleration (G)		
	Horizontal	Vertical	
Speed (mm/s)	0.3	0.7	0.3
0	6.5	2.5	1
140	6.5	2.5	1
280	5	2	1
420	4	1	0.5
560	2.5	0.5	0.5

**Lead 10**

Orientation	Acceleration (G)		
	Horizontal	Vertical	
Speed (mm/s)	0.3	0.7	0.3
0	15	5.5	2.5
175	15	5.5	2.5
350	6	2	1.5
435	4.5	1.5	0.5
525	0.5		

**Lead 5**

Orientation	Acceleration (G)	
	Horizontal	Vertical
Speed (mm/s)	0.3	0.3
0	25	5
85	25	5
130	25	5
215	8	2

**Lead 2.5**

Orientation	Acceleration (G)	
	Horizontal	Vertical
Speed (mm/s)	0.3	0.3
0	35	6.5
40	35	6.5
85	34	6.5
105	25	1

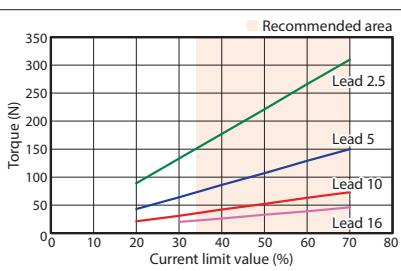
**Stroke and Max Speed**

Lead (mm)	Energy-saving setting	50 ~ 150 (Every 50mm)
16	Disabled	800
	Enabled	560
10	Disabled	600
	Enabled	525 <435>
5	Disabled	300
	Enabled	215
2.5	Disabled	150 <135>
	Enabled	105

(Unit: mm/s)

(Note) Values in < > are for vertical use.

**Correlation between Torque and Current Limit**











# EC-GD5

Mini

Rod Type

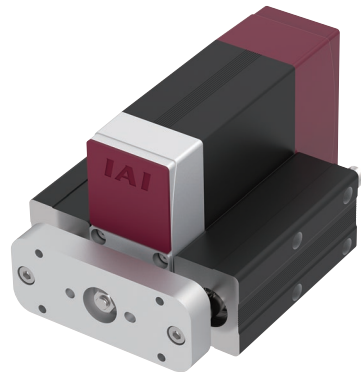
Side-mounted Motor

Body Width  
110  
 mm

24v  
 Stepper  
 Motor

**Model Specification Items**

<b>EC</b>	<b>GD5</b>																		
Series	Type	Lead	Stroke	Power / I/O cable length	Options														
		<table border="1" style="width: 100%; border-collapse: collapse; font-size: 0.7em;"> <tr><td>S</td><td>16mm</td></tr> <tr><td>H</td><td>10mm</td></tr> <tr><td>M</td><td>5mm</td></tr> <tr><td>L</td><td>2.5mm</td></tr> </table>	S	16mm	H	10mm	M	5mm	L	2.5mm	<table border="1" style="width: 100%; border-collapse: collapse; font-size: 0.7em;"> <tr><td>50</td><td>50mm</td></tr> <tr><td>100</td><td>100mm</td></tr> <tr><td>150</td><td>150mm</td></tr> </table>	50	50mm	100	100mm	150	150mm	<div style="border: 1px solid gray; padding: 2px; font-size: 0.7em;">See power / I/O cable length below</div>	<div style="border: 1px solid gray; padding: 2px; font-size: 0.7em;">See options below</div>
S	16mm																		
H	10mm																		
M	5mm																		
L	2.5mm																		
50	50mm																		
100	100mm																		
150	150mm																		



Horizontal

Vertical

Side

Ceiling

Stroke	EC-GD5
Stroke (mm)	
<b>50</b>	<input type="radio"/>
<b>100</b>	<input type="radio"/>
<b>150</b>	<input type="radio"/>

Option	Option code	Reference page
* Please check the Options reference pages to confirm each option.		
RCON-EC connection specification (Note 1)	<b>ACR</b>	21
Brake	<b>B</b>	21
Designated grease specification (Note 2)	<b>G5</b>	21
PNP specification	<b>PN</b>	21
Split motor and controller power supply specification	<b>TMD2</b>	21
Battery-less absolute encoder specification	<b>WA</b>	21
Wireless communication specification	<b>WL</b>	22
Wireless axis operation specification	<b>WL2</b>	22

(Note 1) If the RCON-EC connection specification (ACR) is selected, the PNP specification (PN) and split motor and controller power supply specification (TMD2) cannot be selected.  
 (Note 2) The operating temperature environment for designated grease specification (G5) is 10°C to 40°C.

POINT  
Selection Notes

(1) "Main Specifications" displays the payload's maximum value.

(2) Horizontal payload is the value when also using a guide so that radial and moment loads are not applied to the rod. If not installing a guide, refer to "Radial Load and Service Life."

(3) If performing push-motion operations, refer to the "Correlation between Torque and Current Limit" diagram. The torques listed are only reference values. Please refer to P. 22 for applicable notes.

(4) Pay close attention to the installation orientation. Please refer to P4 for more information.

### Power / I/O cable length

Cable code	Cable length	User wiring specification (flying leads)	RCON-EC connection specification (Note 4) (with connectors on both ends)
		CB-EC-PWBIO□□□-RB supplied	CB-REC-PWBIO□□□-RB supplied
<b>0</b>	No cable	<input type="radio"/> (Note 3)	<input type="radio"/>
<b>1 ~ 3</b>	1~3m	<input type="radio"/>	<input type="radio"/>
<b>4 ~ 5</b>	4 ~ 5m	<input type="radio"/>	<input type="radio"/>
<b>6 ~ 7</b>	6 ~ 7m	<input type="radio"/>	<input type="radio"/>
<b>8 ~ 10</b>	8 ~ 10m	<input type="radio"/>	<input type="radio"/>

(Note 3) Only terminal block connector is supplied. Please refer to P. 25 for details.  
 (Note 4) If RCON-EC connection specification (ACR) is selected as an option. (Note) The robot cable is standard.

### 4-way connector cable

Cable code	Cable length	User wiring specification (flying leads)	RCON-EC connection specification (Note 5) (with connectors on both ends)
		CB-EC2-PWBIO□□□-RB supplied	CB-REC2-PWBIO□□□-RB supplied
<b>S1 ~ S3</b>	1~3m	<input type="radio"/>	<input type="radio"/>
<b>S4 ~ S5</b>	4 ~ 5m	<input type="radio"/>	<input type="radio"/>
<b>S6 ~ S7</b>	6 ~ 7m	<input type="radio"/>	<input type="radio"/>
<b>S8 ~ S10</b>	8 ~ 10m	<input type="radio"/>	<input type="radio"/>

(Note 5) If RCON-EC connection specification (ACR) is selected as an option. (Note) The robot cable is standard.

**Main Specifications**

Item		Description				
Lead	Ball screw lead (mm)	16	10	5	2.5	
Horizontal	Payload	Max. payload (kg) (energy-saving disabled)	6.5	16	25	35
		Max. payload (kg) (energy-saving enabled)	6.5	15	25	35
	Speed/acceleration/deceleration	Max. speed (mm/s)	800	600	300	150
		Min. speed (mm/s)	40	30	7	4
Vertical	Payload	Max. payload (kg) (energy-saving disabled)	1.5	2.5	6.5	6.5
		Max. payload (kg) (energy-saving enabled)	1	2.5	5	6.5
	Speed/acceleration/deceleration	Max. speed (mm/s)	800	600	300	135
		Min. speed (mm/s)	40	30	7	4
Push	Max. push force (N)	46	73	150	310	
	Max. push speed (mm/s)	40	30	20	20	
Brake	Brake specification	Non-excitation actuating solenoid brake				
	Brake holding force (kgf)	1.5	2.5	6.5	6.5	
Stroke	Min. stroke (mm)	50	50	50	50	
	Max. stroke (mm)	150	150	150	150	
	Stroke pitch (mm)	50	50	50	50	

Item	Description
Driving system	Ball screw, φ8mm, rolled C10
Positioning repeatability	±0.05mm
Lost motion	- (two-point positioning function; cannot be represented)
Rod non-rotation precision	-
Service life	5000km
Ambient operating temperature, humidity	0 ~ 40°C, 85%RH or less (Non-condensing)
Degree of protection	IP20
Vibration & shock resistance	4.9m/s <sup>2</sup>
Overseas standards	CE marking, RoHS directive
Motor type	Stepper motor
Encoder type	Incremental/battery-less absolute
Number of encoder pulses	800 pulse/rev

**Table of Payload by Speed/Acceleration**

**Energy-saving setting disabled** The unit for payload is kg. If blank, operation is not possible.

**Lead 16**

Orientation	Horizontal		Vertical	
	Acceleration (G)			
Speed (mm/s)	0.3	0.5	0.7	1
0	6.5	4	3	2
140	6.5	4	3	2
280	6.5	4	3	2
420	6.5	4	2.5	1.5
560	5	3	2	1
700	3.5	1.5	1	0.5
800		1	1	0.5

**Lead 10**

Orientation	Horizontal		Vertical	
	Acceleration (G)			
Speed (mm/s)	0.3	0.5	0.7	1
0	16	11	7	4.5
175	16	11	7	4.5
350	12.5	7	4	2.5
435	9.5	5	3	1.5
525	5	4	2	1
600	4.5	2	1	0.5

**Lead 5**

Orientation	Horizontal		Vertical	
	Acceleration (G)			
Speed (mm/s)	0.3	0.5	0.3	0.5
0	25	22	6.5	4.5
85	25	22	6.5	4.5
130	25	20	5	4.5
215	15	15	4	4
260	10	10	2	2
300	5	5	1.5	1.5

**Lead 2.5**

Orientation	Horizontal		Vertical	
	Acceleration (G)			
Speed (mm/s)	0.3	0.3	0.3	0.3
0	35	35	6.5	6.5
40	35	35	6.5	6.5
85	35	35	6.5	6.5
105	35	35	6.5	6.5
135	30	30	2	2
150	10	10		

**Energy-saving setting enabled** The unit for payload is kg. If blank, operation is not possible.

**Lead 16**

Orientation	Horizontal		Vertical	
	Acceleration (G)			
Speed (mm/s)	0.3	0.7	0.3	0.3
0	6.5	2.5	1	
140	6.5	2.5	1	
280	5	2	1	
420	4	1	0.5	
560	2.5	0.5	0.5	

**Lead 10**

Orientation	Horizontal		Vertical	
	Acceleration (G)			
Speed (mm/s)	0.3	0.7	0.3	0.3
0	15	5.5	2.5	
175	15	5.5	2.5	
350	6	2	1.5	
435	4.5	1.5	0.5	
525	0.5			

**Lead 5**

Orientation	Horizontal		Vertical	
	Acceleration (G)			
Speed (mm/s)	0.3	0.3	0.3	0.3
0	25	25	5	
85	25	25	5	
130	25	25	5	
215	8	8	2	

**Lead 2.5**

Orientation	Horizontal		Vertical	
	Acceleration (G)			
Speed (mm/s)	0.3	0.3	0.3	0.3
0	35	35	6.5	
40	35	35	6.5	
85	34	34	6.5	
105	25	25	1	

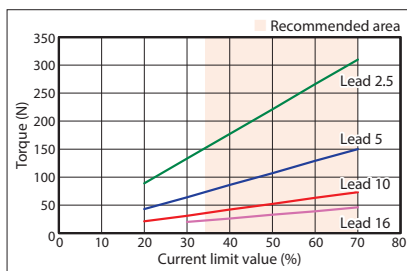
**Stroke and Max Speed**

Lead (mm)	Energy-saving setting	50 ~ 150 (Every 50mm)
16	Disabled	800
	Enabled	560
10	Disabled	600
	Enabled	525 <435>
5	Disabled	300
	Enabled	215
2.5	Disabled	150 <135>
	Enabled	105

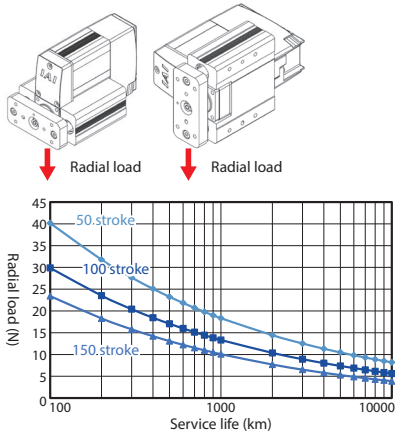
(Note) Values in < > are for vertical use.

(Unit: mm/s)

**Correlation between Torque and Current Limit**



**Allowable Radial Load and Service Life**



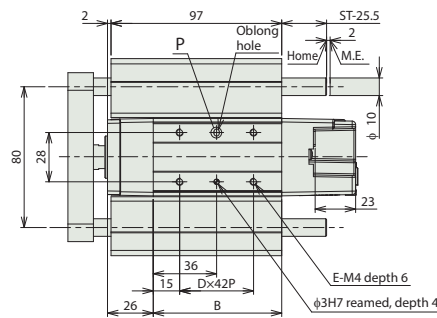
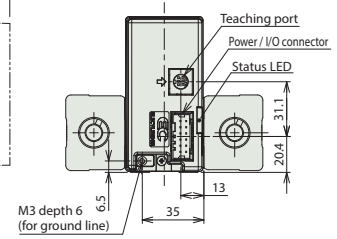
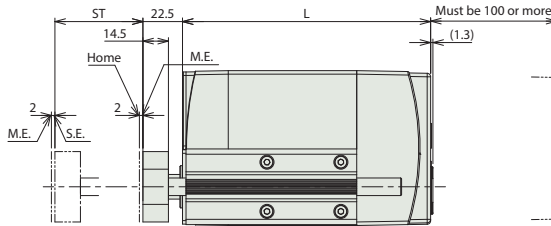
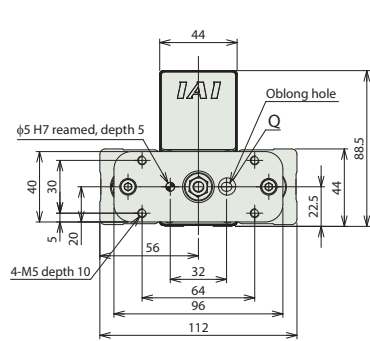
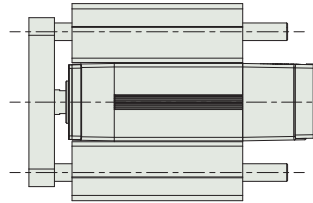
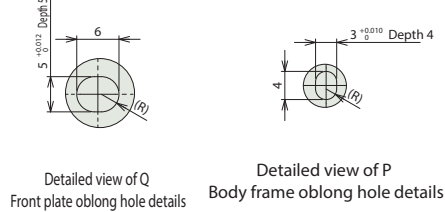
**Dimensions**

CAD drawings can be downloaded from our website.  
[www.intelligentactuator.com](http://www.intelligentactuator.com)



(Note) When returning to the home position, the rod will move to the M.E. Be careful of interference with surrounding objects.

ST: Stroke  
 M.E: Mechanical end  
 S.E: Stroke end



**Dimensions by stroke**

Encoder type	Stroke	Incremental			Battery-less absolute		
		50	100	150	50	100	150
L	Without brake	141	191	241	166	191	241
	With brake	191	191	241	204	204	241
B	Without brake	73	123	173	98	123	173
	With brake	123	123	173	136	136	173
D	Without brake	1	2	3	1	2	3
	With brake	2	2	3	2	2	3
E	Without brake	4	6	8	4	6	8
	With brake	6	6	8	6	6	8

**Mass by stroke**

Encoder type	Stroke	Incremental			Battery-less absolute		
		50	100	150	50	100	150
Mass (kg)	Without brake	2.1	2.4	2.7	2.2	2.4	2.7
	With brake	2.5	2.5	2.8	2.5	2.6	2.8

**Applicable controllers**

(Note) EC Series products are equipped with a built-in controller. Please refer to P. 24 for details on built-in controllers.



# EC-TC5

Mini

Table Type

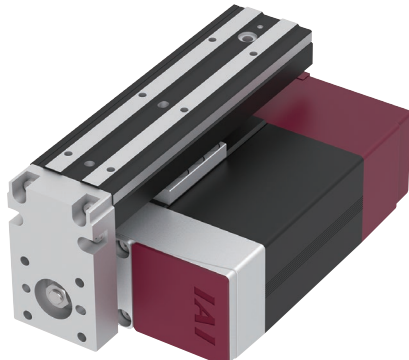
Side-mounted Motor

Body Width  
**40 mm**

**24v**  
Stepper Motor

**Model Specification Items**

<b>EC</b>	<b>TC5</b>				
Series	Type	Lead	Stroke	Power / I/O cable length	Options
		S 16mm H 10mm M 5mm L 2.5mm	50 50mm 100 100mm 150 150mm	See power / I/O cable length below	See options below



(Note) The photo above shows table left mounting (GT4).

Stroke	
Stroke (mm)	EC-TC5
<b>50</b>	<input type="radio"/>
<b>100</b>	<input type="radio"/>
<b>150</b>	<input type="radio"/>

Option <span style="font-size: small;">* Please check the Options reference pages to confirm each option.</span>		
Name	Option code	Reference page
RCON-EC connection specification (Note 1)	<b>ACR</b>	21
Brake	<b>B</b>	21
Designated grease specification (Note 2)	<b>G5</b>	21
Table right mount (Note 3)	<b>GT2</b>	21
Table bottom mount (Note 3)	<b>GT3</b>	21
Table left mount (Note 3)	<b>GT4</b>	21
Non-motor end specification	<b>NM</b>	21
PNP specification	<b>PN</b>	21
Split motor and controller power supply specification	<b>TMD2</b>	21
Battery-less absolute encoder specification	<b>WA</b>	21
Wireless communication specification	<b>WL</b>	22
Wireless axis operation specification	<b>WL2</b>	22

- (Note 1) If the RCON-EC connection specification (ACR) is selected, the PNP specification (PN) and split motor and controller power supply specification (TMD2) cannot be selected.
- (Note 2) The operating temperature environment for designated grease specification (G5) is 10°C to 40°C.
- (Note 3) Be sure to enter a code in the option column for Model Specification Items.

POINT  
Selection Notes

- (1) "Main Specifications" displays the payload's maximum value at 50 stroke.
- (2) If performing push-motion operations, refer to the "Correlation between Torque and Current Limit" diagram. The torques listed are only reference values. Please refer to P. 22 for applicable notes.
- (3) Be sure to select an option code for the table mounting direction from the option price list below.
- (4) The reference values of the overhang load length are 100m or less in the table top direction for the Ma direction, 150mm or less in the table tip direction, and 120mm or less in the Mb/Mc directions.
- (5) Pay close attention to the installation orientation. Please refer to P.4 for more information.

### Power / I/O cable length

Standard connector cable			
Cable code	Cable length	User wiring specification (flying leads)	RCON-EC connection specification (Note 5) (with connectors on both ends)
		CB-EC2-PWBIO□□□-RB supplied	CB-REC2-PWBIO□□□-RB supplied
<b>0</b>	No cable	<input type="radio"/> (Note 4)	<input type="radio"/>
<b>1 ~ 3</b>	1~3m	<input type="radio"/>	<input type="radio"/>
<b>4 ~ 5</b>	4 ~ 5m	<input type="radio"/>	<input type="radio"/>
<b>6 ~ 7</b>	6 ~ 7m	<input type="radio"/>	<input type="radio"/>
<b>8 ~ 10</b>	8 ~ 10m	<input type="radio"/>	<input type="radio"/>

- (Note 4) Only terminal block connector is supplied. Please refer to P. 25 for details.
- (Note 5) If RCON-EC connection specification (ACR) is selected as an option.
- (Note) The robot cable is standard.

### 4-way connector cable

Cable code	Cable length	User wiring specification (flying leads)	RCON-EC connection specification (Note 6) (with connectors on both ends)
		CB-EC2-PWBIO□□□-RB supplied	CB-REC2-PWBIO□□□-RB supplied
<b>S1 ~ S3</b>	1~3m	<input type="radio"/>	<input type="radio"/>
<b>S4 ~ S5</b>	4 ~ 5m	<input type="radio"/>	<input type="radio"/>
<b>S6 ~ S7</b>	6 ~ 7m	<input type="radio"/>	<input type="radio"/>
<b>S8 ~ S10</b>	8 ~ 10m	<input type="radio"/>	<input type="radio"/>

- (Note 6) If RCON-EC connection specification (ACR) is selected as an option.
- (Note) The robot cable is standard.

**Main Specifications**

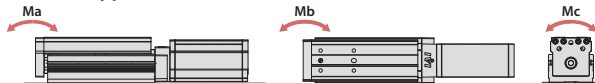
Item		Description				
Lead	Ball screw lead (mm)	16	10	5	2.5	
Horizontal	Payload	Max. payload (kg) (energy-saving disabled)	6.5	12.5	12.5	12.5
		Max. payload (kg) (energy-saving enabled)	6.5	12.5	12.5	12.5
	Speed/acceleration/deceleration	Max. speed (mm/s)	800	600	300	150
		Min. speed (mm/s)	40	30	7	4
Vertical	Payload	Max. payload (kg) (energy-saving disabled)	1.5	2.5	5	6.5
		Max. payload (kg) (energy-saving enabled)	1	2.5	5	6.5
	Speed/acceleration/deceleration	Max. speed (mm/s)	700	525	260	135
		Min. speed (mm/s)	40	30	7	4
Push	Max. push force (N)	46	73	150	310	
	Max. push speed (mm/s)	40	30	20	20	
Brake	Brake specification	Non-excitation actuating solenoid brake				
	Brake holding force (kgf)	1.5	2.5	5	6.5	
Stroke	Min. stroke (mm)	50	50	50	50	
	Max. stroke (mm)	150	150	150	150	
	Stroke pitch (mm)	50	50	50	50	

Item		Description
Driving system	Ball screw, $\phi 8\text{mm}$ , rolled C10	
Positioning repeatability	$\pm 0.05\text{mm}$	
Lost motion	- (two-point positioning function; cannot be represented)	
Static allowable moment	Ma: 13.0Nm	
	Mb: 18.6Nm	
	Mc: 25.3Nm	
Dynamic allowable moment (Note 7)	Ma: 4.98Nm	
	Mb: 7.11Nm	
	Mc: 9.68Nm	
Service life	5000km	
Ambient operating temperature, humidity	0 ~ 40°C, 85%RH or less (Non-condensing)	
Degree of protection	IP20	
Vibration & shock resistance	4.9m/s <sup>2</sup>	
Overseas standards	CE marking, RoHS directive	
Motor type	Stepper motor	
Encoder type	Incremental/battery-less absolute	
Number of encoder pulses	800 pulse/rev	

(Note 7) Based on the standard rated operation life of 5,000km. Operation life varies according to operating and mounting conditions. Please refer to EC General Catalog 2020 P.369 for details on service life.

**Table type moment direction**



**Table of Payload by Speed/Acceleration**

**Energy-saving setting disabled** The unit for payload is kg. If blank, operation is not possible.

**[50mm stroke]**

**Lead 16**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)				Vertical	
		0.3	0.5	0.7	1	0.3	0.5
	0	6.5	4	3	2	1.5	1.5
	140	6.5	4	3	2	1.5	1.5
	280	6.5	4	3	2	1.5	1.5
	420				1.5		

**Lead 10**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)				Vertical	
		0.3	0.5	0.7	1	0.3	0.5
	0	12.5	11	7	4.5	2.5	2
	175	12.5	11	7	4.5	2.5	2
	350	9.5	7	4	2.5	2.5	2
	435				1.5		

**Lead 5**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)		Vertical	
		0.3	0.5	0.3	0.5
	0	12.5	12.5	5	4.5
	85	12.5	12.5	5	4.5
	130	12.5	12.5	5	4.5
	215	12	12	4	4
	260	9	7	1	1
	300	2	0.5		

**Lead 2.5**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)		Vertical	
		0.3	0.5	0.3	0.5
	0	12.5	12.5	6.5	6.5
	40	12.5	12.5	6.5	6.5
	85	12.5	12.5	6.5	6.5
	105	12.5	12.5	6.5	6.5
	135	12.5	12.5	3	3
	150	1	1		

**[100mm stroke]**

**Lead 16**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)				Vertical	
		0.3	0.5	0.7	1	0.3	0.5
	0	6.5	4	3	2	1.5	1.5
	140	6.5	4	3	2	1.5	1.5
	280	6.5	4	3	2	1.5	1.5
	420	6.5	4	2.5	1.5	1.5	1.5
	560		3	2	1		1
	700				0.5		

**Lead 10**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)				Vertical	
		0.3	0.5	0.7	1	0.3	0.5
	0	6.5	6.5	6.5	4.5	2.5	2
	175	6.5	6.5	6.5	4.5	2.5	2
	350	6.5	6.5	4	2.5	2.5	2
	435	6.5	5	3	1.5	1.5	1
	525		2	1.5	1		0.5
	600		0.5				

**Lead 5**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)		Vertical	
		0.3	0.5	0.3	0.5
	0	6.5	6.5	5	4.5
	85	6.5	6.5	5	4.5
	130	6.5	6.5	5	4.5
	215	6.5	6.5	4	4
	260	6.5	6.5	1	1
	300	2	0.5		

**Lead 2.5**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)		Vertical	
		0.3	0.5	0.3	0.5
	0	6.5	6.5	6.5	6.5
	40	6.5	6.5	6.5	6.5
	85	6.5	6.5	6.5	6.5
	105	6.5	6.5	6.5	6.5
	135	6.5	6.5	3	3
	150	1	1		

**[150mm stroke]**

**Lead 16**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)				Vertical	
		0.3	0.5	0.7	1	0.3	0.5
	0	4	4	3	2	1.5	1.5
	140	4	4	3	2	1.5	1.5
	280	4	4	3	2	1.5	1.5
	420	4	4	2.5	1.5	1.5	1.5
	560	4	3	2	1	1	1
	700		1.5	1	0.5		0.5
	800			1	0.5		

**Lead 10**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)				Vertical	
		0.3	0.5	0.7	1	0.3	0.5
	0	4	4	4	4	2.5	2
	175	4	4	4	4	2.5	2
	350	4	4	4	2.5	2.5	2
	435	4	4	3	1.5	1.5	1
	525	3	2	1.5	1	0.5	0.5
	600		0.5				

**Lead 5**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)		Vertical	
		0.3	0.5	0.3	0.5
	0	4	4	5	4.5
	85	4	4	5	4.5
	130	4	4	5	4.5
	215	4	4	4	4
	260	4	4	1	1
	300	2	0.5		

**Lead 2.5**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)		Vertical	
		0.3	0.5	0.3	0.5
	0	6.5	6.5	6.5	6.5
	40	6.5	6.5	6.5	6.5
	85	6.5	6.5	6.5	6.5
	105	6.5	6.5	6.5	6.5
	135	6.5	6.5	3	3
	150	1	1		



■ **Energy-saving setting enabled** The unit for payload is kg. If blank, operation is not possible.

**[50mm stroke]**

**Lead 16**

Orientation	Horizontal		Vertical
	Acceleration (G)		
Speed (mm/s)	0.3	0.7	0.3
0	6.5	2.5	1
140	6.5	2.5	1
280	5.5	2	1

**Lead 10**

Orientation	Horizontal		Vertical
	Acceleration (G)		
Speed (mm/s)	0.3	0.7	0.3
0	12.5	5.5	2.5
175	12.5	5.5	2.5
350	5.5	2	0.5

**Lead 5**

Orientation	Horizontal	Vertical
	Acceleration (G)	
Speed (mm/s)	0.3	0.3
0	12.5	5
85	12.5	5
130	12.5	5
215	6	0.5

**Lead 2.5**

Orientation	Horizontal	Vertical
	Acceleration (G)	
Speed (mm/s)	0.3	0.3
0	12.5	6.5
40	12.5	6.5
85	12.5	6.5
105	12.5	1

**[100mm stroke]**

**Lead 16**

Orientation	Horizontal		Vertical
	Acceleration (G)		
Speed (mm/s)	0.3	0.7	0.3
0	6.5	2.5	1
140	6.5	2.5	1
280	5.5	2	1
420	4	1	0.5

**Lead 10**

Orientation	Horizontal		Vertical
	Acceleration (G)		
Speed (mm/s)	0.3	0.7	0.3
0	6.5	5.5	2.5
175	6.5	5.5	2.5
350	5.5	2	0.5
435	0.5		

**Lead 5**

Orientation	Horizontal	Vertical
	Acceleration (G)	
Speed (mm/s)	0.3	0.3
0	6.5	5
85	6.5	5
130	6.5	5
215	6	0.5

**Lead 2.5**

Orientation	Horizontal	Vertical
	Acceleration (G)	
Speed (mm/s)	0.3	0.3
0	6	6.5
40	6	6.5
85	6	6.5
105	6	1

**[150mm stroke]**

**Lead 16**

Orientation	Horizontal		Vertical
	Acceleration (G)		
Speed (mm/s)	0.3	0.7	0.3
0	4	2.5	1
140	4	2.5	1
280	4	2	1
420	4	1	0.5
560	2.5	0.5	0.5

**Lead 10**

Orientation	Horizontal		Vertical
	Acceleration (G)		
Speed (mm/s)	0.3	0.7	0.3
0	4	4	2.5
175	4	4	2.5
350	4	2	0.5
435	0.5		

**Lead 5**

Orientation	Horizontal	Vertical
	Acceleration (G)	
Speed (mm/s)	0.3	0.3
0	4	5
85	4	5
130	4	5
215	4	0.5

**Lead 2.5**

Orientation	Horizontal	Vertical
	Acceleration (G)	
Speed (mm/s)	0.3	0.3
0	4	6.5
40	4	6.5
85	4	6.5
105	4	1

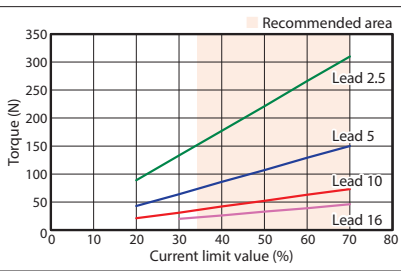
**Stroke and Max Speed**

Lead (mm)	Energy-saving setting	50 (mm)	100 (mm)	150 (mm)
		16	Disabled <280>	700 <560>
	Enabled	280	420	560
10	Disabled	435 <350>	600 <525>	
	Enabled	350	435 <350>	
5	Disabled	300 <260>		
	Enabled	215		
2.5	Disabled	150 <135>		
	Enabled	105		

(Unit: mm/s)

(Note) Values in <> are for vertical use.

**Correlation between Torque and Current Limit**



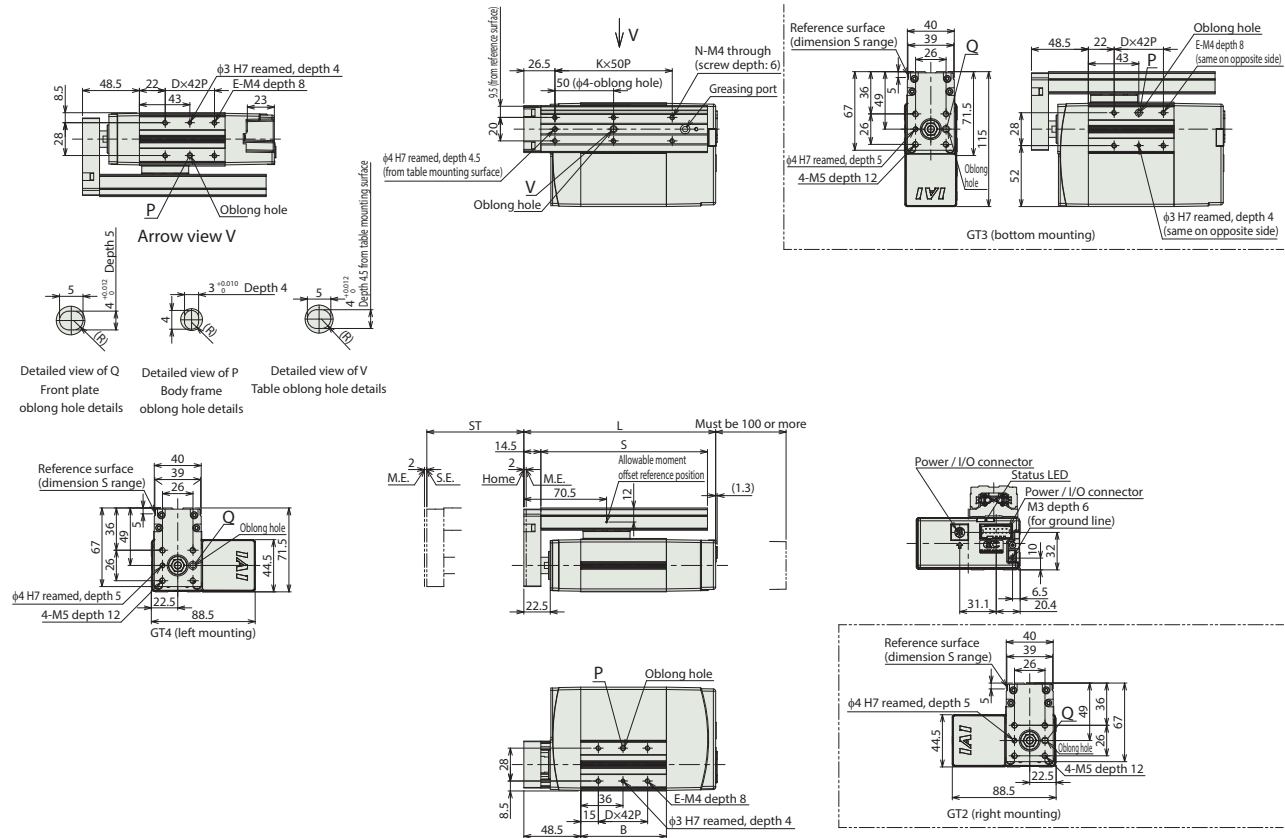
Dimensions

CAD drawings can be downloaded from our website.  
www.intelligentactuator.com



(Note) When returning to the home position, the rod will move to the M.E. Be careful of interference with surrounding objects.

ST: Stroke  
M.E: Mechanical end  
S.E: Stroke end



Dimensions by stroke

Encoder type		Incremental			Battery-less absolute		
	Stroke	50	100	150	50	100	150
L	Without brake	163.5	213.5	263.5	188.5	213.5	263.5
	With brake	213.5	213.5	263.5	226.5	226.5	263.5
B	Without brake	73	123	173	98	123	173
	With brake	123	123	173	136	136	173
D	Without brake	1	2	3	1	2	3
	With brake	2	2	3	2	2	3
E	Without brake	4	6	8	4	6	8
	With brake	6	6	8	6	6	8
K	Without brake	2	3	4	2	3	4
	With brake	2	3	4	2	3	4
N	Without brake	6	8	10	6	8	10
	With brake	6	8	10	6	8	10
S	Without brake	142	192	242	142	192	242
	With brake	142	192	242	142	192	242

Mass by stroke

Encoder type		Incremental			Battery-less absolute		
	Stroke	50	100	150	50	100	150
Mass (kg)	Without brake	1.3	1.6	1.9	1.5	1.6	1.9
	With brake	1.7	1.8	2.1	1.8	1.9	2.1

Applicable controllers

(Note) EC Series products are equipped with a built-in controller. Please refer to P. 24 for details on built-in controllers.

# EC-TW5

Mini

Table Type

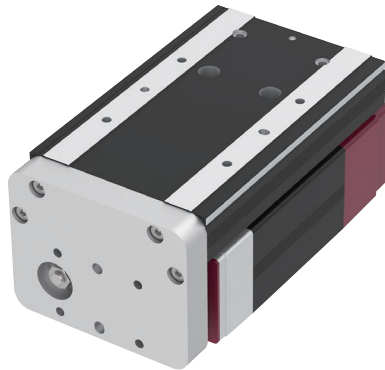
Side-mounted Motor

Body Width  
**90 mm**

**24v**  
Stepper Motor

**Model Specification Items**

<b>EC</b>	<b>TW5</b>				
Series	Type	Lead	Stroke	Power / I/O cable length	Options
		S 16mm H 10mm M 5mm L 2.5mm	50 50mm 100 100mm 150 150mm	See power / I/O cable length below	See options below



Horizontal

Vertical

Side

Ceiling

Stroke	
Stroke (mm)	EC-TW5
<b>50</b>	<input type="radio"/>
<b>100</b>	<input type="radio"/>
<b>150</b>	<input type="radio"/>

Option <span style="font-size: small;">* Please check the Options reference pages to confirm each option.</span>		
Name	Option code	Reference page
RCON-EC connection specification (Note 1)	<b>ACR</b>	21
Brake	<b>B</b>	21
Designated grease specification (Note 2)	<b>G5</b>	21
Non-motor end specification	<b>NM</b>	21
PNP specification	<b>PN</b>	21
Split motor and controller power supply specification	<b>TMD2</b>	21
Battery-less absolute encoder specification	<b>WA</b>	21
Wireless communication specification	<b>WL</b>	22
Wireless axis operation specification	<b>WL2</b>	22

(Note 1) If the RCON-EC connection specification (ACR) is selected, the PNP specification (PN) and split motor and controller power supply specification (TMD2) cannot be selected.

(Note 2) The operating temperature environment for designated grease specification (G5) is 10°C to 40°C.

POINT  
Selection Notes

(1) "Main Specifications" displays the payload's maximum value at 50mm stroke.

(2) If performing push-motion operations, refer to the "Correlation between Torque and Current Limit" diagram. The torques listed are only reference values. Please refer to P. 22 for applicable notes.

(3) The reference values of the overhang load length are 100m or less in the table top direction for the Ma direction, 150mm or less in the table tip direction, and 120mm or less in the Mb/Mc directions.

(4) Pay close attention to the installation orientation. Please refer to P.4 for more information.

### Power / I/O cable length

Standard connector cable			
Cable code	Cable length	User wiring specification (flying leads)	RCON-EC connection specification (Note 4) (with connectors on both ends)
		CB-EC-PWBIO□□□-RB supplied	CB-REC-PWBIO□□□-RB supplied
<b>0</b>	No cable	<input type="radio"/> (Note 3)	<input type="radio"/>
<b>1 ~ 3</b>	1~3m	<input type="radio"/>	<input type="radio"/>
<b>4 ~ 5</b>	4 ~ 5m	<input type="radio"/>	<input type="radio"/>
<b>6 ~ 7</b>	6 ~ 7m	<input type="radio"/>	<input type="radio"/>
<b>8 ~ 10</b>	8 ~ 10m	<input type="radio"/>	<input type="radio"/>

(Note 3) Only terminal block connector is supplied. Please refer to P. 25 for details.

(Note 4) If RCON-EC connection specification (ACR) is selected as an option, the robot cable is standard.

### 4-way connector cable

Cable code	Cable length	User wiring specification (flying leads)	RCON-EC connection specification (Note 5) (with connectors on both ends)
		CB-EC2-PWBIO□□□□-RB supplied	CB-REC2-PWBIO□□□□-RB supplied
<b>S1 ~ S3</b>	1~3m	<input type="radio"/>	<input type="radio"/>
<b>S4 ~ S5</b>	4 ~ 5m	<input type="radio"/>	<input type="radio"/>
<b>S6 ~ S7</b>	6 ~ 7m	<input type="radio"/>	<input type="radio"/>
<b>S8 ~ S10</b>	8 ~ 10m	<input type="radio"/>	<input type="radio"/>

(Note 5) If RCON-EC connection specification (ACR) is selected as an option, the robot cable is standard.

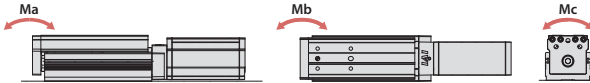
**Main Specifications**

Item		Description				
Lead	Ball screw lead (mm)	16	10	5	2.5	
Horizontal	Payload	Max. payload (kg) (energy-saving disabled)	6.5	16	20	20
		Max. payload (kg) (energy-saving enabled)	6.5	15	20	20
	Speed/acceleration/deceleration	Max. speed (mm/s)	700	525	300	135
		Min. speed (mm/s)	40	30	7	4
Vertical	Payload	Max. payload (kg) (energy-saving disabled)	1.5	2.5	5	6.5
		Max. payload (kg) (energy-saving enabled)	1	2.5	5	6.5
	Speed/acceleration/deceleration	Max. speed (mm/s)	560	435	260	135
		Min. speed (mm/s)	40	30	7	4
Push	Max. push force (N)	46	73	150	310	
	Max. push speed (mm/s)	40	30	20	20	
Brake	Brake specification	Non-excitation actuating solenoid brake				
	Brake holding force (kgf)	1.5	2.5	5	6.5	
Stroke	Min. stroke (mm)	50	50	50	50	
	Max. stroke (mm)	150	150	150	150	
	Stroke pitch (mm)	50	50	50	50	

Item	Description
Driving system	Ball screw, $\phi$ 8mm, rolled C10
Positioning repeatability	$\pm$ 0.05mm
Lost motion	- (two-point positioning function; cannot be represented)
Static allowable moment	Ma: 32.3Nm
	Mb: 23.5Nm
	Mc: 45.0Nm
Dynamic allowable moment (Note 6)	Ma: 11.6Nm
	Mb: 16.6Nm
	Mc: 34.0Nm
Service life	5000km
Ambient operating temperature, humidity	0 ~ 40°C, 85%RH or less (Non-condensing)
Degree of protection	IP20
Vibration & shock resistance	4.9m/s <sup>2</sup>
Overseas standards	CE marking, RoHS directive
Motor type	Stepper motor
Encoder type	Incremental/battery-less absolute
Number of encoder pulses	800 pulse/rev

(Note 6) Based on the standard rated operation life of 5,000km. Operation life varies according to operating and mounting conditions. Please refer to EC General Catalog 2020 P. 369 for details on service life.

**Table type moment direction**



**Table of Payload by Speed/Acceleration**

**Energy-saving setting disabled** The unit for payload is kg. If blank, operation is not possible.

**[50mm stroke]**

**Lead 16**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)					
		0.3	0.5	0.7	1	0.3	0.5
	0	6.5	4	3	2	1.5	1.5
	140	6.5	4	3	2	1.5	1.5
	280	6.5	4	3	2	1.5	1.5
	420				1.5		

**Lead 10**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)					
		0.3	0.5	0.7	1	0.3	0.5
	0	16	11	7	4.5	2.5	2
	175	16	11	7	4.5	2.5	2
	350	12.5	7	4	2.5	2.5	2
	435				0.5		

**Lead 5**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)			
		0.3	0.5	0.3	0.5
	0	20	20	5	4.5
	85	20	20	5	4.5
	130	20	17.5	5	4.5
	215	20	13	4	4
	260	7	6.5	1	1
	300	1			

**Lead 2.5**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)		Vertical Acceleration (G)
		0.3	0.3	
	0	20		6.5
	40	20		6.5
	85	20		6.5
	105	20		6.5
	135	18		1.5

**[100mm stroke]**

**Lead 16**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)					
		0.3	0.5	0.7	1	0.3	0.5
	0	6.5	4	3	2	1.5	1.5
	140	6.5	4	3	2	1.5	1.5
	280	6.5	4	3	2	1.5	1.5
	420	6.5	4	2.5	1.5	1.5	1.5
	560		3	2	1		0.5
	700				0.5		

**Lead 10**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)					
		0.3	0.5	0.7	1	0.3	0.5
	0	15.5	11	7	4.5	2.5	2
	175	15.5	11	7	4.5	2.5	2
	350	12.5	7	4	2.5	2.5	2
	435	9.5	5	3	0.5	1	1
	525		2	1			

**Lead 5**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)			
		0.3	0.5	0.3	0.5
	0	15.5	15.5	5	4.5
	85	15.5	15.5	5	4.5
	130	15.5	15.5	5	4.5
	215	15.5	13	4	4
	260	7	6.5	1	1
	300	1			

**Lead 2.5**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)		Vertical Acceleration (G)
		0.3	0.3	
	0	15.5		6.5
	40	15.5		6.5
	85	15.5		6.5
	105	15.5		6.5
	135	15.5		1.5

**[150mm stroke]**

**Lead 16**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)					
		0.3	0.5	0.7	1	0.3	0.5
	0	6.5	4	3	2	1.5	1.5
	140	6.5	4	3	2	1.5	1.5
	280	6.5	4	3	2	1.5	1.5
	420	6.5	4	2.5	1.5	1.5	1.5
	560		5	3	2	1	0.5
	700		1.5	1	0.5		

**Lead 10**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)					
		0.3	0.5	0.7	1	0.3	0.5
	0	10	10	7	4.5	2.5	2
	175	10	10	7	4.5	2.5	2
	350	10	7	4	2.5	2.5	2
	435	9.5	5	3	0.5	1	1
	525	4.5	2	1			

**Lead 5**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)			
		0.3	0.5	0.3	0.5
	0	10	10	5	4.5
	85	10	10	5	4.5
	130	10	10	5	4.5
	215	10	10	4	4
	260	7	6.5	1	1
	300	1			

**Lead 2.5**

Orientation	Speed (mm/s)	Horizontal Acceleration (G)		Vertical Acceleration (G)
		0.3	0.3	
	0	10		6.5
	40	10		6.5
	85	10		6.5
	105	10		6.5
	135	10		1.5

■ **Energy-saving setting enabled** The unit for payload is kg. If blank, operation is not possible.

**[50mm stroke]**

**Lead 16**

Orientation	Horizontal		Vertical
	Acceleration (G)		
Speed (mm/s)	0.3	0.7	0.3
0	6.5	2.5	1
140	6.5	2.5	1
280	5.5	2	1

**Lead 10**

Orientation	Horizontal		Vertical
	Acceleration (G)		
Speed (mm/s)	0.3	0.7	0.3
0	15	5.5	2.5
175	15	5.5	2.5
350	5	2	0.5

**Lead 5**

Orientation	Horizontal		Vertical
	Acceleration (G)		
Speed (mm/s)	0.3	0.3	
0	20	5	
85	20	5	
130	20	5	
215	4.5		

**Lead 2.5**

Orientation	Horizontal		Vertical
	Acceleration (G)		
Speed (mm/s)	0.3	0.3	
0	20	6.5	
40	20	6.5	
85	20	4.5	
105	18	1	

**[100mm stroke]**

**Lead 16**

Orientation	Horizontal		Vertical
	Acceleration (G)		
Speed (mm/s)	0.3	0.7	0.3
0	6.5	2.5	1
140	6.5	2.5	1
280	5.5	2	1
420	4	1	0.5

**Lead 10**

Orientation	Horizontal		Vertical
	Acceleration (G)		
Speed (mm/s)	0.3	0.7	0.3
0	15	5.5	2.5
175	15	5.5	2.5
350	5	2	0.5
435	0.5		

**Lead 5**

Orientation	Horizontal		Vertical
	Acceleration (G)		
Speed (mm/s)	0.3	0.3	
0	15.5	5	
85	15.5	5	
130	15.5	5	
215	4.5		

**Lead 2.5**

Orientation	Horizontal		Vertical
	Acceleration (G)		
Speed (mm/s)	0.3	0.3	
0	15.5	6.5	
40	15.5	6.5	
85	15.5	4.5	
105	15.5	1	

**[150mm stroke]**

**Lead 16**

Orientation	Horizontal		Vertical
	Acceleration (G)		
Speed (mm/s)	0.3	0.7	0.3
0	6.5	2.5	1
140	6.5	2.5	1
280	5.5	2	1
420	4	1	0.5
560	2	0.5	

**Lead 10**

Orientation	Horizontal		Vertical
	Acceleration (G)		
Speed (mm/s)	0.3	0.7	0.3
0	10	5.5	2.5
175	10	5.5	2.5
350	5	2	0.5
435	0.5		

**Lead 5**

Orientation	Horizontal		Vertical
	Acceleration (G)		
Speed (mm/s)	0.3	0.3	
0	10	5	
85	10	5	
130	10	5	
215	4.5		

**Lead 2.5**

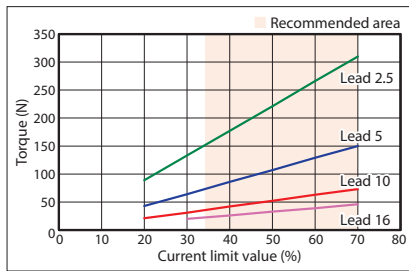
Orientation	Horizontal		Vertical
	Acceleration (G)		
Speed (mm/s)	0.3	0.3	
0	10	6.5	
40	10	6.5	
85	10	4.5	
105	10	1	

**Stroke and Max Speed**

Lead (mm)	Energy-saving setting	50 (mm)	100 (mm)	150 (mm)
				(Unit: mm/s)
16	Disabled	420 <280>	700 <560>	
	Enabled	280	420	560 <420>
10	Disabled	435 <350>	525 <435>	
	Enabled	350	435 <350>	
5	Disabled	300 <260>		
	Enabled	215 <130>		
2.5	Disabled	135		
	Enabled	105		

(Note) Values in <> are for vertical use.

**Correlation between Torque and Current Limit**



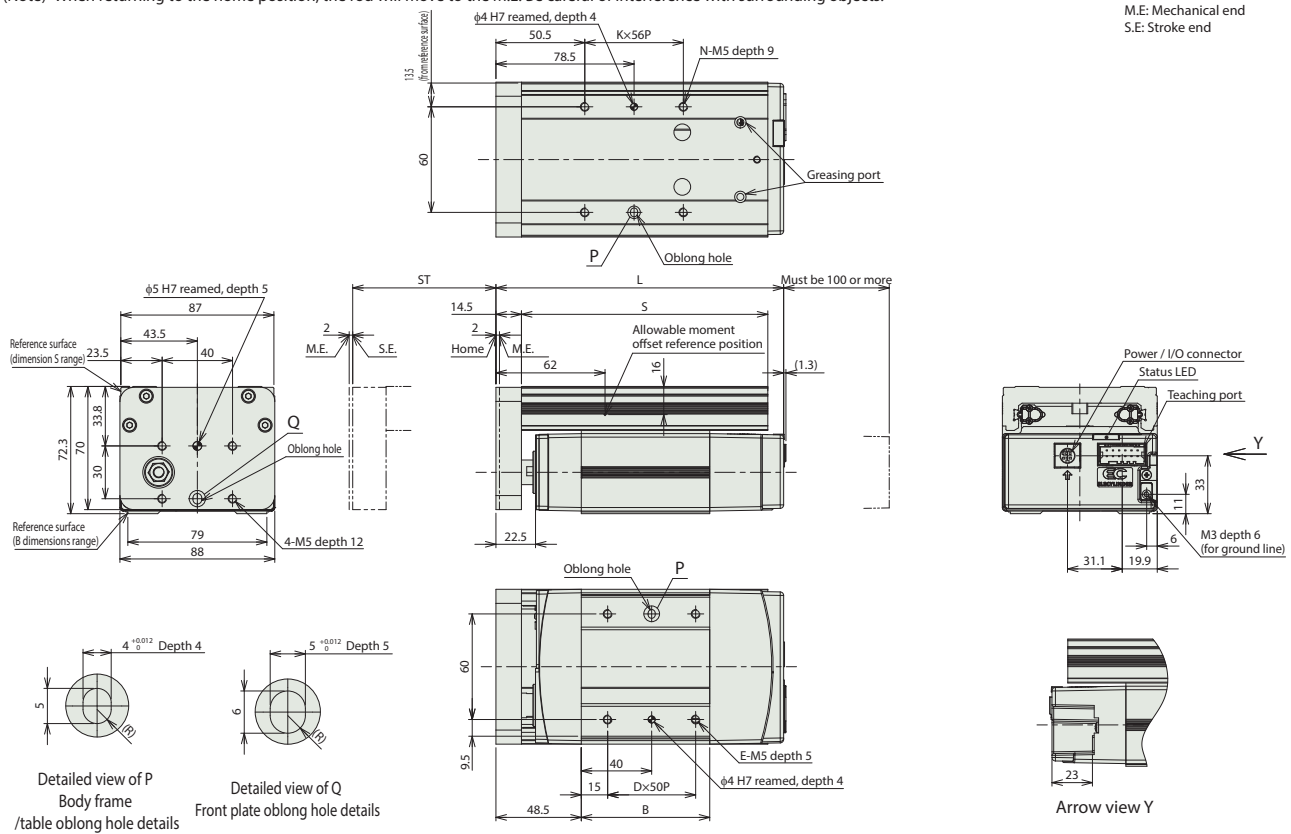
Dimensions

CAD drawings can be downloaded from our website.  
www.intelligentactuator.com



(Note) When returning to the home position, the rod will move to the M.E. Be careful of interference with surrounding objects.

ST: Stroke  
M.E: Mechanical end  
S.E: Stroke end



Dimensions by stroke

Encoder type		Incremental			Battery-less absolute		
Stroke		50	100	150	50	100	150
L	Without brake	163.5	213.5	263.5	188.5	213.5	263.5
	With brake	213.5	213.5	263.5	226.5	226.5	263.5
B	Without brake	73	123	173	98	123	173
	With brake	123	123	173	136	136	173
D	Without brake	1	2	3	1	2	3
	With brake	2	2	3	2	2	3
E	Without brake	4	6	8	4	6	8
	With brake	6	6	8	6	6	8
K	Without brake	1	2	3	1	2	3
	With brake	1	2	3	1	2	3
N	Without brake	4	6	8	4	6	8
	With brake	4	6	8	4	6	8
S	Without brake	140	190	240	140	190	240
	With brake	140	190	240	140	190	240

Mass by stroke

Encoder type		Incremental			Battery-less absolute		
Stroke		50	100	150	50	100	150
Mass (kg)	Without brake	1.7	2.2	2.6	1.9	2.2	2.6
	With brake	2.2	2.4	2.8	2.3	2.5	2.8

Applicable controllers

(Note) EC Series products are equipped with a built-in controller. Please refer to P. 24 for details on built-in controllers.

# ELECYLINDER® Series Options

## RCON-EC connection specification \*Cannot be selected with the TMD2 and PN options (the ACR option includes the split motor and controller power supply specification)

**Model** **ACR**

**Description** This option should be selected to connect over an R-unit to a field network.  
\*If this option is selected, the power supply must be a twin power supply and the input/output specification must be NPN. Therefore, it cannot be selected with the TMD2 or PN options.

## Brake

**Model** **B**

**Description** When the actuator is mounted vertically, this works as a holding mechanism that prevents the table or rod from falling and damaging any attachments when the power or servo is turned off. When using the rotary on its side or vertically, this holding mechanism also prevents the output shaft from accidentally rotating due to the weight of the attached object, and damaging the attached object when the power or servo is turned off.

## Designated grease specification

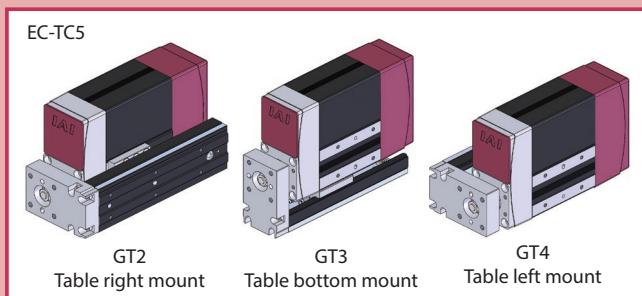
**Model** **G5**

**Description** Replaces the grease applied to the actuator ball screw, linear guide, and sliding surface of the rod with food machine grease (White Alcom Grease).

## Table mounting direction

**Model** **GT2 / GT3 / GT4** **Applicable models** EC-TC5

**Description** Select the table position of EC-TC5. Be sure to enter a code in the model number.



## Non-motor end specification

**Model** **NM** **Applicable models** EC-TC5/TW5

**Description** The home position is normally set to the motor side. This option is for setting the home position on the other side in order to accommodate variations in equipment layout, etc.

## PNP specification \* Cannot be selected with ACR option, which uses the NPN specification.

**Model** **PN**

**Description** EC Series products provide NPN specification input/output for connecting external devices as standard. Specifying this option changes input/output to the PNP specification.

## Twin power supply specification \* Cannot be selected with the ACR option (the RCON-EC connection specification is a split motor and controller power supply specification)

**Model** **TMD2**

**Description** This option includes an actuator operation stop input. Select this option to allow shutting down the actuator drive power only. Please refer to P. 25 for more information on wiring.

## Battery-less absolute encoder specification

**Model** **WA**

**Description** EC Series products use the incremental encoder specification as standard. Specify this option to have a built-in battery-less absolute encoder installed.



### Wireless communication specification

- Model** WL
- Description** This option enables support for wireless communication. Specifying this option enables wireless communication with the TB-03 teaching pendant. The start point, end point, and AVD can be adjusted via wireless communication.

### Wireless axis operation specification

- Model** WL2
- Description** Specifying WL2 allows for the product to operate wirelessly as with WL (start point, end point, and AVD adjustment), and to also perform axis travel operation tests (forward end/backward end movement, jog, and inching). However, this function is not meant to perform automatic operation. Please refer to P. 326 of the EC General Catalog for precautions on axis operations using a wireless connection. (Note) Customers cannot change WL to WL2, or WL2 to WL. Please contact IAI for this.

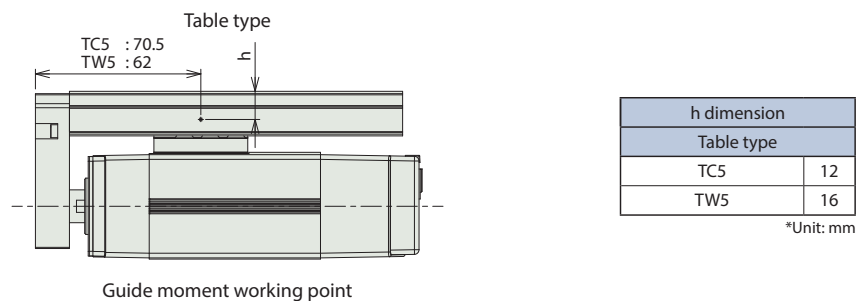
## Notes on use of table type actuators for push-motion operation

When performing a push-motion operation using a table type actuator, be sure to limit the push current so that the reactive moment caused by the torque does not exceed the dynamic allowable moment (Ma, Mb) listed in the catalog.

Please refer to the figures below, which show the working point of the guide moment, for help with calculating the moment. When doing so, take the offset amount of the torque working point into consideration.

Note that applying excessive force that exceeds the dynamic allowable moment may damage the guide and reduce its service life.

Select a push current that is safely within its limits.



## Push-motion operation

Push-motion operation is a function that keeps the rod or slider pushed up against a part, as with an air cylinder. Please check the usage instructions and precautions below prior to use.

### [Torque adjustment]

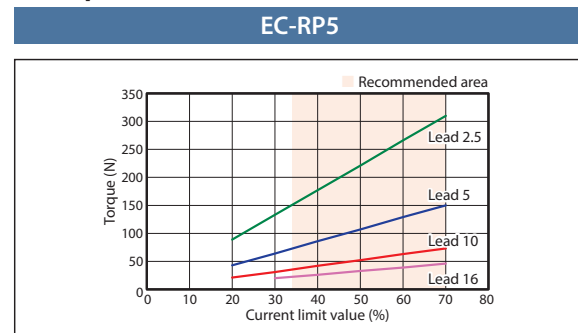
- The torque during a push-motion operation can be adjusted by changing the "torque (%)" on ELECYLINDER®.
- Please check the torque for the applicable model in the "correlation diagrams between torque and current limit" on the production specification page, and select a model that matches your conditions.

### [Lead selection method]

Select a lead with the desired torque in the recommended current limit value range (the colored area in the graph).

Lead 10 would be appropriate for the EC-RP5 type shown in the figure to the right if a torque of 50N is desired. Selecting lead 5 would limit the adjustment range.

### (Example)

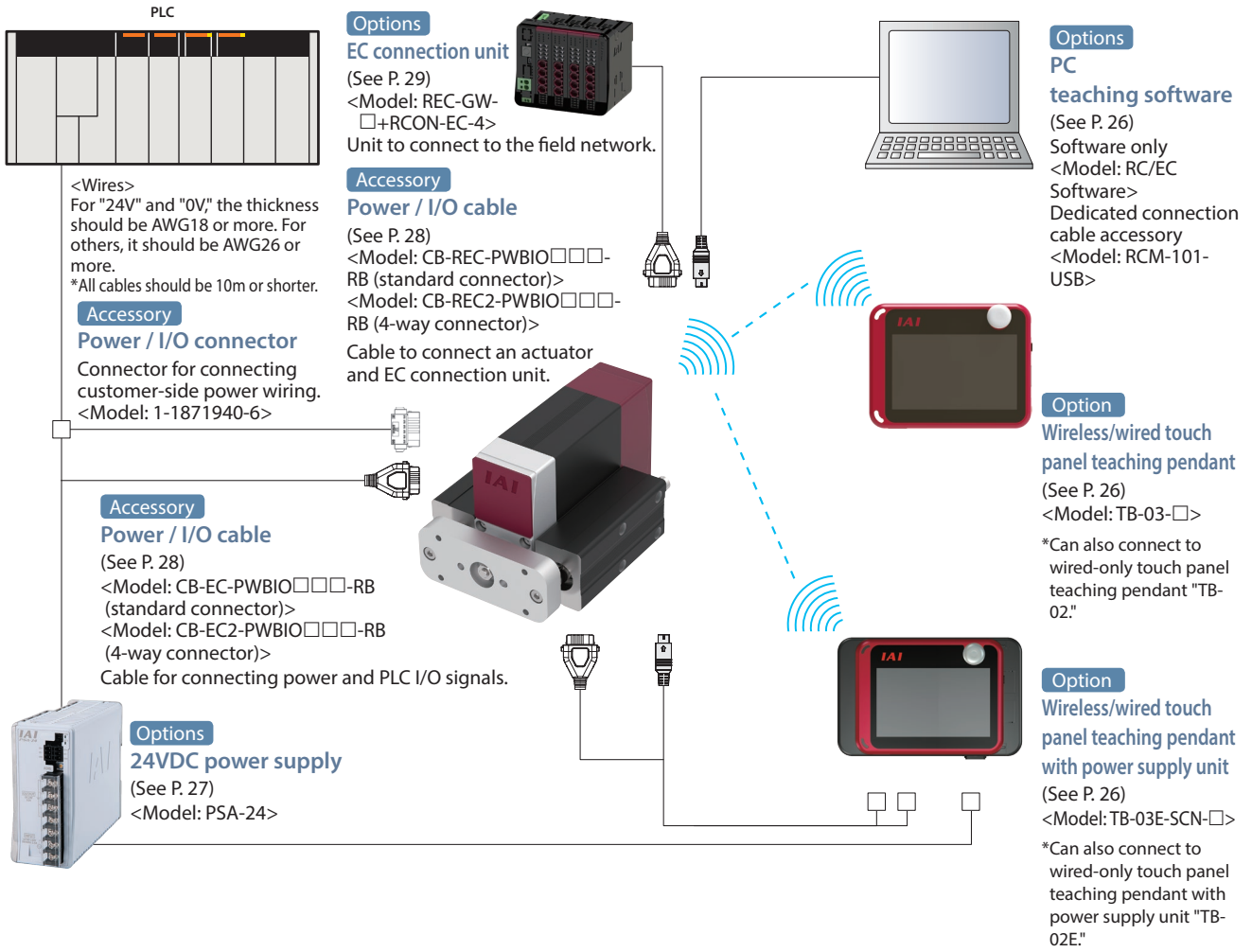


<Correlation between Torque and Current Limit>



- The "correlation diagrams between torque and current limit" show lower guidelines for torque for each current limit value.
- Individual differences in the motor and variations in machine operation may cause the torque lower limit to be exceeded by around 40%, even if the current limit value is the same. This is especially true when the current limit value is 30% or lower, and the torque lower limit could be exceeded by 40% or more.

**System Configuration**



**List of accessories**

■ Power / I/O cables, connectors

[Standard connector]

Product category		Accessory
Power / I/O cable length (selected with actuator model)	RCON-EC connection specification (ACR) selection	
0	No	Power / I/O connector (1-1871940-6)
	Yes	—
1 ~ 10	No	Power / I/O cable (CB-EC-PWBIO□□□-RB)
	Yes	Power / I/O cable (CB-REC-PWBIO□□□-RB)

[Four-way connector]

Product category		Accessory
Power / I/O cable length (selected with actuator model)	RCON-EC connection specification (ACR) selection	
S1 ~ S10	No	Power / I/O cable (CB-EC2-PWBIO□□□-RB)
	Yes	Power / I/O cable (CB-REC2-PWBIO□□□-RB)

## Basic Controller Specifications

Specification item		Specification content	
Number of controlled axes		1 axis	
Power supply voltage		24VDC ±10%	
Power capacity	RP5, GD5, TC5, TW5	Energy-saving disabled: Rated 3.5A, max. 4.2A Energy-saving enabled: Max. 2.2A	
Brake release power supply		24VDC ±10%, 200mA (only for external brake release)	
Generated heat		8W (at 100% duty)	
Inrush current (Note 1)	RP5, GD5, TC5, TW5	8.3A (with inrush current limit circuit)	
Momentary power failure resistance		Max 500μs	
Motor size		□35	
Motor rated current		1.2A	
Motor control system		Weak field-magnet vector control	
Supported encoders		Incremental (800 pulse/rev), battery-less absolute encoder (800 pulse/rev)	
SIO		RS485 1ch (Modbus protocol compliant)	
PIO	Input specification	No. of inputs	3 points (forward, backward, alarm clear)
		Input voltage	24VDC ±10%
		Input current	5mA per circuit
		Leakage current	Max. 1mA per point
		Isolation method	Non-isolated
	Output specification	No. of outputs	3 points (forward complete, backward complete, alarm)
		Output voltage	24VDC ±10%
		Output current	50mA per point
		Residual voltage	2V or less
		Isolation method	Non-isolated
Data setting, input method		PC teaching software, touch panel teaching pendant, digital speed controller	
Data retention memory		Position and parameters are saved in non-volatile memory (no limit to number of rewrites)	
LED display	Controller status display	Servo ON (green light ON) / Alarm (red light ON) / Initializing when power comes ON (orange light ON) / Minor failure alarm (green/red alternately blinking) / Operation from teaching: Stop from teaching (red light ON) / Servo OFF (light OFF)	
	Wireless status display	Initializing wireless hardware, without wireless connection, or connecting from TP board (light OFF) Connecting through wireless (green blinking) / Wireless hardware error (red blinking) / Initializing when power comes ON (orange light ON)	
Predictive maintenance/preventative maintenance		When the number of movements or operation distance has exceeded the set value and when the LED (right side) blinks alternately green and red at overload warning *Only when configured in advance	
Ambient operating temperature		0 ~ 40°C	
Ambient operating humidity		5%RH ~ 85%RH (Non-condensing or freezing)	
Operating environment		No corrosive gas and excessive dust	
Insulation resistance		500VDC 10MΩ	
Electric shock protection mechanism		Class 1 basic insulation	
Cooling method		Natural air cooling	

(Note 1) Inrush current flows for approximately 5ms after the power is input. (At 40°C.) Inrush current value differs depending on the impedance on the power line.

## Solenoid valve method

ELECYLINDER® products normally use a double solenoid method.  
Change parameter No. 9 ("solenoid valve type selection") to use the single solenoid method.

<Caution>

Operation cannot be performed using the single solenoid method when operating connected to RCON-EC.

**I/O (Input/Output) Specifications**

I/O		Input		Output	
Specifications		Input voltage	24VDC ±10%	Load voltage	24VDC ±10%
		Input current	5mA per circuit	Maximum load current	50mA per point
		ON/OFF voltage	ON voltage: Min. 18VDC OFF voltage: Max. 6VDC	Residual voltage	2V or less
		Leakage current	Max. 1mA per point	Leakage current	Max. 0.1mA per point
Isolation method		Non-isolated from external circuit		Non-isolated from external circuit	
I/O logic	NPN				
	PNP				

(Note) Isolation method is non-isolated. When grounding an external device (such as a PLC) connected to ELECYLINDER®, use the same ground as ELECYLINDER®.

**I/O Signal Wiring Diagram**

I/O		Standard specification	Split motor and controller power supply specification (option model: TMD2)
Power / I/O connector		<p>0V A1 (Reserved) A2 (Note 1) Backward complete A3 (Note 1) Forward complete A4 Alarm output A5 (Reserved) A6</p> <p>B1 24V B2 Brake release B3 Backward command B4 Forward command B5 Alarm cancel B6 (reserved)</p>	<p>Drive power and control power are separate for the TMD2 specification.</p> <p>0V A1 <b>24V (control) A2</b> (Note 1) Backward complete A3 (Note 1) Forward complete A4 Alarm output A5 (Reserved) A6</p> <p>B1 24V (drive) B2 Brake release B3 Backward command B4 Forward command B5 Alarm cancel B6 (reserved)</p>
I/O logic	NPN	<p>0V                      24V</p>	<p>0V                      24V</p>
	PNP	<p>24V                      0V</p>	<p>24V                      0V</p>

(Note 1) Switching to the single solenoid method will change B3 to "forward/backward command" and B4 to "unused."

I/O Signal Table

Power / I/O connector pin assignment			
Pin No.	Connector nameplate name	Signal abbreviation	Function overview
B3 (Note 1)	Backward	ST0	Backward command
B4 (Note 1)	Forward	ST1	Forward command
B5	Alarm cancel	RES	Alarm cancel
A3	Backward complete	LS0/PE0	Backward complete/push complete
A4	Forward complete	LS1/PE1	Forward complete/push complete
A5	Alarm	*ALM	Alarm detection (b-contact)
B2	Brake release	BKRLS	Brake forced release (for brake equipped specification)
B1 (Note 2)	24V	24V	24V input
A1	0V	0V	0V input
A2 (Note 2)	(24V)	(24V)	24V input

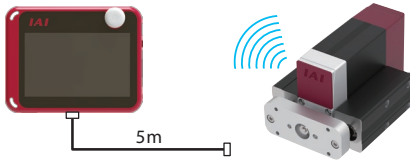
(Note 1) Switching to the single solenoid method will change B3 to "forward/backward" and B4 to "unused." However, the power / I/O connector display will still read "B3: Backward" and "B4: Forward."

(Note 2) B1 is 24V (drive) and A2 is 24V (control) for the split motor and controller power supply specification (TMD2).

Option

Wireless/wired touch panel teaching pendant

- **Features** This teaching device supports wireless connections. Start point/end point/AVD input and axis operation can be performed wirelessly.
- **Model TB-03-**  Please contact IAI for the current supported versions.
- **Configuration** Wireless or wired connection

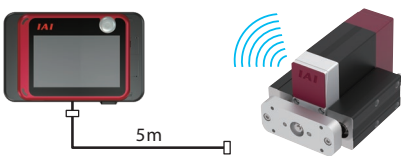


TB-03 body specifications

Power input voltage range	24VDC ±10% [supplied from controller]
	5.9VDC (5.7 ~ 6.3V) [supplied from AC adapter]
Power consumption	3.6W or less
Consumption current	150mA (supplied from controller)
Ambient operating temperature	0 ~ 40°C (Non-condensing or freezing)
Ambient operating humidity	5%RH ~ 85%RH (Non-condensing or freezing)
Ambient storage temperature	-20 ~ 40°C
Degree of protection	IPX0
Mass	670g (body) + approx. 285g (dedicated cable)
Charging method	Wired connection with dedicated AC adapter/controller

Wired/wireless touch panel teaching pendant with power supply unit

- **Model TB-03E-**  Please contact IAI for the current supported versions.
- **Configuration** Wireless or wired connection



Power supply unit specifications

Rated input voltage	Single-phase 100 ~ 230VAC±10%
Input current	(Under rated I/O conditions in ambient temperature of 25°C) 1.4A typ. (100VAC) 0.6A typ. (230VAC)
Frequency range	50/60Hz ±5%
Power capacity	(Under rated I/O conditions in ambient temperature of 25°C) 141VA (100VAC) 145VA (230VAC)
Output voltage	24VDC ±10%
Load current	With energy-saving setting disabled: Rated 3.5A, max. 4.2A With energy-saving setting enabled: Rated 2.2A
Output capacity	With energy-saving setting disabled: Rated 84W, max. 98.4W With energy-saving setting enabled: Rated 52.8W
Ambient operating temperature	0 ~ 40°C (Non-condensing or freezing)
Ambient operating humidity	5%RH ~ 85%RH (Non-condensing or freezing)
Ambient storage temperature	-20 ~ 70°C
Atmosphere	No corrosive gas and excessive dust
Altitude	1000m or less above sea level
Vibration resistance	Frequency: 10 ~ 57Hz / Amplitude: 0.075mm Frequency: 57 ~ 150Hz / Acceleration: 9.8m/s <sup>2</sup> [XYZ directions] Sweep time: 10 minutes, Number of sweeps: 10
Degree of protection	IP30
Mass	Approx. 740g
Cooling method	Natural air cooling

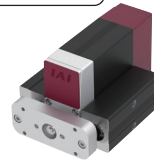
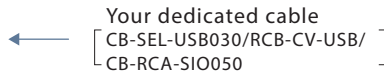
## Teaching software for PC (Windows only)

- **Features** This start-up support software provides functions such as position teaching, trial operation, and monitoring. It provides a complete range of functions required to make adjustments, to help reduce start-up time.

- **Model RC/EC Software** (software only, for customers who already own a dedicated connection cable)

Please contact IAI for the current supported versions.

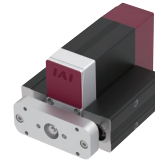
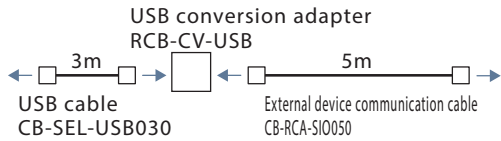
### ■ Configuration



- **Model RCM-101-USB** (with an external device communication cable + USB conversion adapter + USB cable)

Please contact IAI for the current supported versions.

### ■ Configuration



## 24V power

- **Model PSA-24 (without fan)**

- **Model PSA-24L (with fan)**



### ■ Specifications Table

Item	Specification	
	100VAC input	200VAC input
Power input voltage range	100VAC ~ 230 VAC ±10%	
Input power supply current	3.9A or less	1.9A or less
Power capacity	Without fan: 250VA	Without fan: 280VA
	With fan: 390VA	With fan: 380VA
Inrush current <sup>*1</sup>	Without fan: 17A (typ.)	Without fan: 34A (typ.)
	With fan: 27.4A (typ.)	With fan: 54.8A (typ.)
Generated heat	28.6W	20.4W
Output voltage range <sup>*2</sup>	24V ±10%	
Continuous rated output	Without fan: 8.5A (204W), with fan: 13.8A (330W)	
Peak output	17A (408W)	
Efficiency	86% or more	90% or more
Parallel connection <sup>*3</sup>	Up to 5 units	

\*1 The pulse width of flowing inrush current is less than 5ms

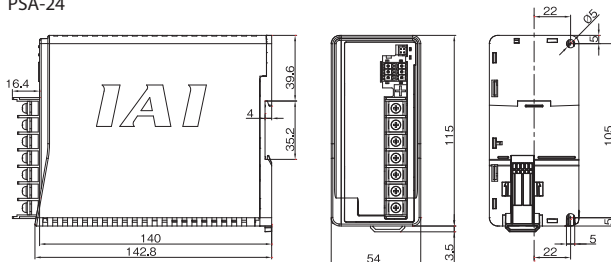
\*2 This power supply can vary the output voltage according to the load in order to enable parallel operation. The power supply unit is therefore for use with IAI controllers only.

\*3 Parallel connection cannot be used under the following conditions.

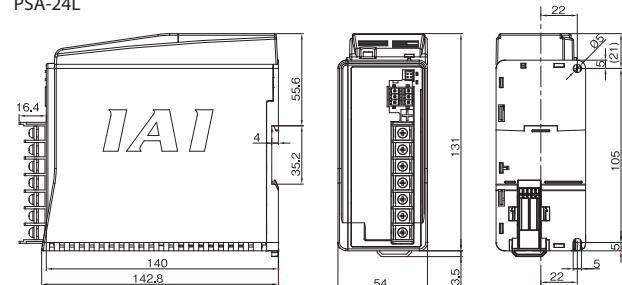
- Parallel connection of PSA-24 (specification without fan) and PSA-24L (specification with fan)
- Parallel connection with a power supply unit other than this power supply
- Parallel connection with PS-24

### ■ External Dimensions

PSA-24



PSA-24L



**Maintenance Parts**

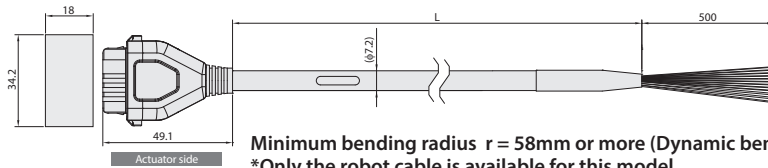
When placing an order for a replacement cable after purchasing a product, please use the model name shown below.

■ Table of compatible cables

Cable type	Cable model
Power / I/O cable (user-wired specification)	CB-EC-PWBIO□□□-RB
Power / I/O cable (user-wired specification, four-way connector)	CB-EC2-PWBIO□□□-RB
Power / I/O cable (RCON-EC connection specification)	CB-REC-PWBIO□□□-RB
Power / I/O cable (RCON-EC connection specification, four-way connector)	CB-REC2-PWBIO□□□-RB

Model **CB-EC-PWBIO□□□-RB**

\*Please indicate the cable length (L) in □□□ (for example, 030 = 3m)

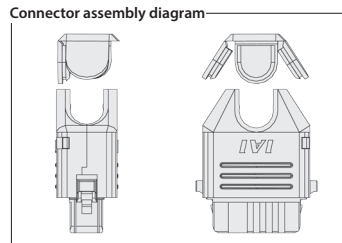
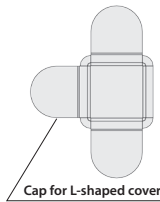
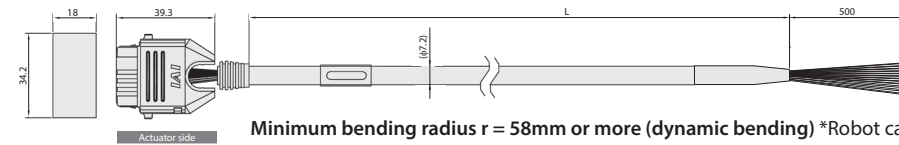


Color	Signal name	Pin No.
Black (AWG18)	0V	A1
Red (AWG18)	24V	B1
Light blue (AWG22) (Reserved) (Note 1)	A2	
Orange (AWG26)	IN0	B3
Yellow (AWG26)	IN1	B4
Green (AWG26)	IN2	B5
Pink (AWG26) (Reserved)	B6	
Blue (AWG26)	OUT0	A3
Purple (AWG26)	OUT1	A4
Gray (AWG26)	OUT2	A5
White (AWG26) (Reserved)	A6	
Brown (AWG26)	BKRLS	B2

(Note 1) 24V (control) when split motor and controller power supply specification (TMD2) selected.

Model **CB-EC2-PWBIO□□□-RB**

\*Please indicate the cable length (L) in □□□ (for example, 030 = 3m)

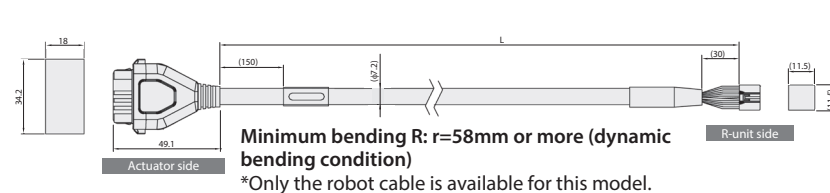


Color	Signal name	Pin No.
Black (AWG18)	0V	A1
Red (AWG18)	24V	B1
Light blue (AWG22) (Reserved) (Note 1)	A2	
Orange (AWG26)	IN0	B3
Yellow (AWG26)	IN1	B4
Green (AWG26)	IN2	B5
Pink (AWG26) (Reserved)	B6	
Blue (AWG26)	OUT0	A3
Purple (AWG26)	OUT1	A4
Gray (AWG26)	OUT2	A5
White (AWG26) (Reserved)	A6	
Brown (AWG26)	BKRLS	B2

(Note 1) 24V (control) when split motor and controller power supply specification (TMD2) selected.

Model **CB-REC-PWBIO□□□-RB**

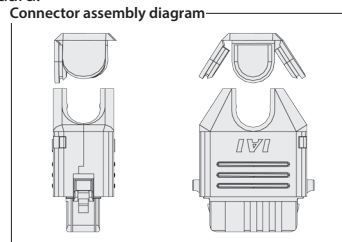
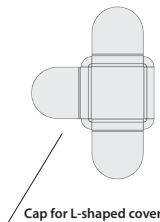
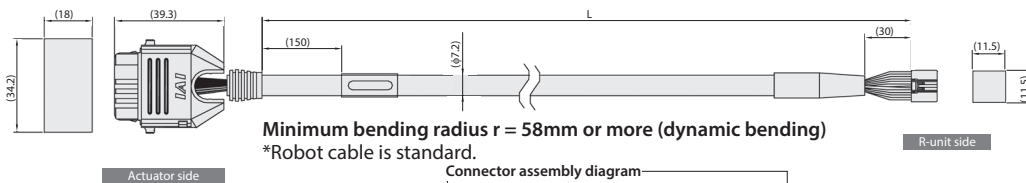
\*Please indicate the cable length (L) in □□□, maximum 10m (for example, 030 = 3m)



Color	Signal name	Pin No.	Pin No.	Signal name	Color
Black (AWG18)	0V	A1	1	24V(MP)	Red (AWG18)
Red (AWG18)	24V(MP)	B1	12	24V(CP)	Light blue (AWG22)
Light blue (AWG22)	24V(CP)	A2	7	OUT0	Orange (AWG26)
Orange (AWG26)	IN0	B3	8	OUT1	Yellow (AWG26)
Yellow (AWG26)	IN1	B4	9	OUT2	Green (AWG26)
Green (AWG26)	IN2	B5	6	SD+	Pink (AWG26)
Pink (AWG26)	SD+	B6	10	SD-	White (AWG26)
White (AWG26)	SD-	A6	3	IN0	Blue (AWG26)
Blue (AWG26)	OUT0	A3	4	IN1	Purple (AWG26)
Purple (AWG26)	OUT1	A4	5	IN2	Gray (AWG26)
Gray (AWG26)	OUT2	A5	11	BKRLS	Brown (AWG26)
Brown (AWG26)	BKRLS	B2	13	FG	Green (AWG26)

Model **CB-REC2-PWBIO□□□-RB**

\*Please indicate the cable length (L) in □□□, maximum 10m (for example, 030 = 3m)



Color	Signal name	Pin No.	Pin No.	Signal name	Color
Black (AWG18)	0V	A1	2	0V	Black (AWG22)
Red (AWG18)	24V(MP)	B1	1	24V(MP)	Red (AWG22)
Light blue (AWG22)	24V(CP)	A2	12	24V(CP)	Light blue (AWG22)
Orange (AWG26)	IN0	B3	7	OUT0	Orange (AWG26)
Yellow (AWG26)	IN1	B4	8	OUT1	Yellow (AWG26)
Green (AWG26)	IN2	B5	9	OUT2	Green (AWG26)
Yellow (AWG26)	SD+	B6	6	SD+	Yellow (AWG26)
Light gray (AWG26)	SD-	A6	10	SD-	Light gray (AWG26)
Blue (AWG26)	OUT0	A3	3	IN0	Blue (AWG26)
Purple (AWG26)	OUT1	A4	4	IN1	Purple (AWG26)
Gray (AWG26)	OUT2	A5	5	IN2	Gray (AWG26)
Brown (AWG26)	BKRLS	B2	11	BKRLS	Brown (AWG26)
			13	FG	Green (AWG26)



# REC Introducing REC

## Connect ELECYLINDER® to a field network(\*)

This field network connection unit is specifically for use with ELECYLINDER®.

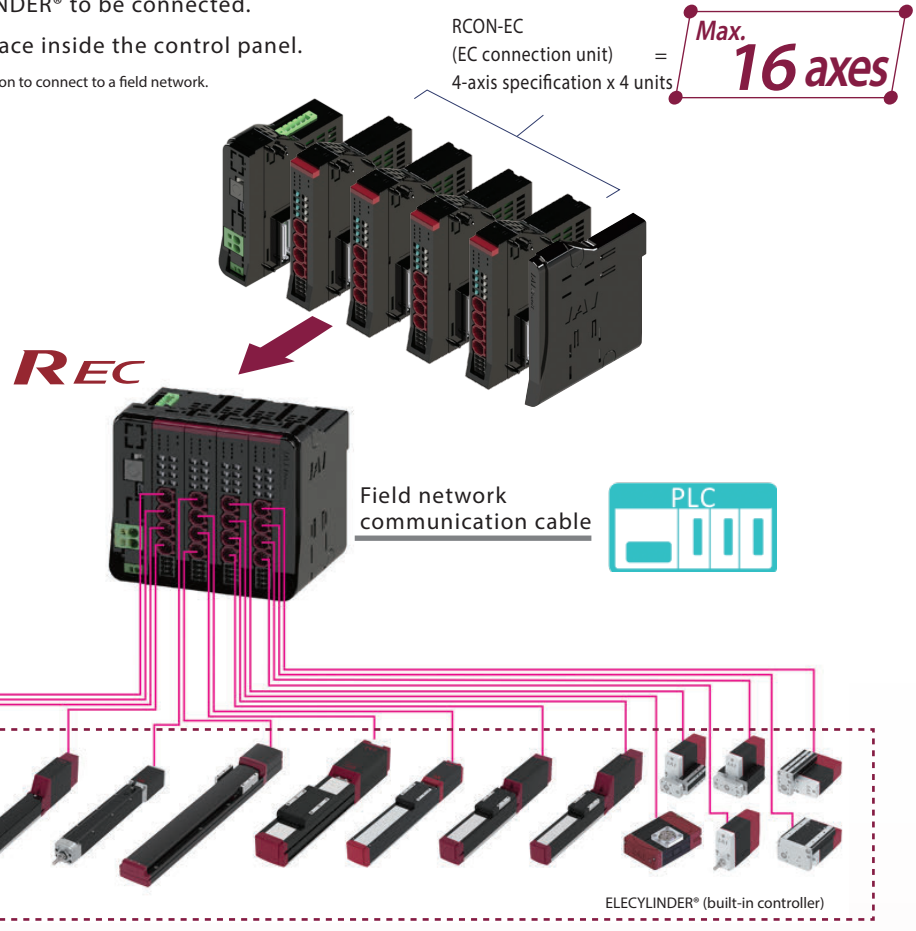
It allows up to 16 axes of ELECYLINDER® to be connected.

It is ideal for saving wiring and space inside the control panel.

\*Select the RCON-EC connection specification (ACR) option to connect to a field network.

### Compatible networks

- CC-Link
- CC-Link IE Field
- DeviceNet
- EtherNet/IP™
- EtherCAT®
- PROFIBUS®
- PROFINET®



## EC connection unit can be connected mixed with other driver units connected to RCON

Connect to RCON to allow mixed connections with ROBO Cylinder and single axis robots.



➔ Refer to **R-unit** Catalog for details

# MEMO

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The information contained in this product brochure may change without prior notice due to product improvements.

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